

Computational Complexity

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Chapter 1

Formalizations

1.1 Formalizing Problems & Language

Definition 1.1.1. The language generated by a finite set M is defined as

$$M^* := \{s \in M^k \mid k \in \mathbb{N}\}$$

Definition 1.1.2. A problem is a function $f : \{0, 1\}^* \mapsto \{0, 1\}^*$

Example 1.1.3. addition of $a, b \in \mathbb{Z}$ can be done in

$$O(\log(\text{sizeof}(a)) + \log(\text{sizeof}(b)))$$

Remark 1.1.4. all objects like “integer x ”, “graph G ”, “vector v ” ... will be finite and we can fix a dictionary that interprets all characters $\{a_1, a_2, \dots\}$ as $\{1, 11, \dots\}$ and uses 0 as a separator.

Definition 1.1.5. A Problem f is called boolean or decision problem if $f : \{0, 1\}^* \mapsto \{0, 1\}$

Usually problems can be reduced to such boolean problems. For example addition can be reduced to $g : (+, i) : \mathbb{Z} \times \mathbb{Z} \mapsto \{0, 1\}$ s.t. $\forall a, b \in \mathbb{Z} : g(a, b)$ is the i -th bit of $(a + b)$. A problem f has an associated set denoted by

$$L_f := \{x \in \{0, 1\}^* \mid f(x) = 1\}$$

this set is called language of f . So we have a strong connection between languages, decision problems and subsets of $\{0, 1\}^*$.

Example 1.1.6. “testing whether a number is prime or not” $\leftrightarrow f : \{0, 1\}^* \mapsto \{0, 1\} \leftrightarrow PRIMES := \{x \in \{0, 1\}^* \mid x \text{ is prime}\}$

Definition 1.1.7. Identify “decide a language L_f ” and “compute a boolean f ”.

1.2 Formalizing Machines

Definition 1.2.1. A Turing machine M consists of

- a finite control-tape of (Γ, Q, δ)

- a possibly infinite data-tape

such that

- Γ is the alphabet of M , it always contains of \triangleright (start), \square (blank), 0, 1 and any other character, but finitely many
- Q is a finite set of stats (we say that M is in state ...) and it has two special states: q_s (starting state) and q_f (ending-state)
- $\delta : Q \times \Gamma^2 \rightarrow Q \times \Gamma \times \{L, R, S\}^2$ is a transition function of M

A configuration of M comprises of (state, input-head, work-head) and an application of δ changes the configuration. One step of M looks like: Say the current configuration is (q, i, w) and $\delta(q, i, w) = (\overline{q'}, w', \epsilon_1, \epsilon_2)$ than the action of δ means:

- change the state to q'
- write w' to the cell where the work-head is
- move the input head one cell in the direction $\epsilon_1 \in \{L = \text{left}, R = \text{right}, S = \text{stay}\}$ (if it is possible) and move the work-head in the direction ϵ_2

Example 1.2.2. *abc*

$(\triangleright, \triangleright) \mapsto (\triangleright, R, S)$
 $(0, \triangleright) \mapsto (\triangleright, R, S)$
 $(1, \triangleright) \mapsto (\triangleright, R, S)$
 $(\square, \triangleright) \mapsto (\triangleright, L, R)$
 $(\triangleright, \square) \mapsto (\square, S, L)$
 $(0, \square) \mapsto (1, L, L)$
 $(1, \square) \mapsto (0, L, L)$

Remark 1.2.3. • The number of states $(|\delta|)$ represents the size of a C-program

- The number of work-cells that M actually uses represent the working-space of a program that is used
- The number of δ -applications on the start configuration to reach the final configuration is the time used by a program when executed

Exercise 1.2.4. • Simulate high-school methods of addition / multiplikation on a turing machine

- proof that any C-program has a corresponding turing machine and vice versa

So a turing machine is just a “computer” with an infinite harddisk.

1.3 Church-Turing-Thesis

The Church-Turing-Thesis says that every physically realizable computing device - silicon based, DNA-based or alien technology - can be simulated on a turing machine.

Definition 1.3.1. We say a problem f is computable or decidable or rekursive if there exists a turing machine M s.t. $\forall x \in \{0,1\}^*$ it holds that M gives the output $f(x)$ in finite time. A boolean Funktion is called computable enumerable, recursively enumerable or decidable enumerable when there is a turing machine that "prints" L_f .

After this Definition the question comes up if there are uncomputable functions that are computable enumerable.

Definition 1.3.2.

$$HALT := \{(M, x) \mid M \text{ is a turing machine, } x \in \{0,1\}^*, M \text{ halts on } x\}$$

Theorem 1.3.3. $HALT$ is enumerable but \overline{HALT} is not.

To proof this theorem we will give turing machines as input to other turing machines. Every description of a turing machine ...

TODO: go on

Definition 1.3.4. Diophantine Problem: Given a \mathbb{Z} -polynomial, decide it's solvability over \mathbb{N} .

- posed by Hilbert (1900)
- Turing studied the Halting Problem 1.3.2 (1936)
- a plan was suggested by Davis, Putnam & Robinson (1950-1960)
- the proof was completed by Matiyasevich (1970)

We will basically proof a stronger theorem:

Theorem 1.3.5. If R is a computably enumerable language then

$$\exists P_R \in \mathbb{Z}[x, x_1, \dots, x_n]$$

s.t. $\forall b \in \{0,1\}^* \cap R$ the equation $P_R(b, x_1, \dots, x_n) = 0$ is solvable over \mathbb{N} . P_R is called a Diophantine representation.

Corrolar 1.3.6. If $HALT$ has a Diophantine representation, the Diophantine Problem is uncomputable.

Corrolar 1.3.7. Even for polynomials of degree 4 its undecidable.

Exercise 1.3.8. Let K be a field and $P \in K[x_1, \dots, x_n]$. Show that the polynomial equation $P(x_1, \dots, x_n) = 0$

- a) has an equivalent quadratic system
- b) can be reduced to an equation of degree ≤ 4

Corrolar 1.3.9. $\exists f \in \mathbb{Z}[\bar{x}]$ s.t all its positive values on \mathbb{N} -evaluations is exactly $PRIMES$ i.e.:

$$PRIMES = \{f(n) \mid n \in \mathbb{N} \ \& \ f(n) > 0\}$$

Proof. $PRIMES$ is computably enumerable. So by 1.3.5 a polynomial

$$P_{PRIMES}(x, x_1, \dots, x_n)$$

exists. Define

$$f(x, x_1, \dots, x_n) := x \cdot (1 - P_{PRIMES}^2(x, x_1, \dots, x_n))$$

Now we see that (for $\bar{x} = (x_1, \dots, x_n)$)

$$f(\bar{x}) > 0 \Leftrightarrow x > 0, (1 - P_{PRIMES}^2) > 0 \Leftrightarrow x > 0, P_{PRIMES} = 0$$

□

First step in the proof of 1.3.5: (representing a turing-machine computation by an arithmetic formular in $+, -, *, =, <, \&, \vee, \forall, \exists$)

Let R be enumerable by a turing-machine M_R . We will construct a first-order arithmetic formula $F_R(b)$ s.t. $b \in R \Leftrightarrow F_R(b) = true$. Example:

$$\forall x_1 \exists x_3 \forall x_2 [x_1^2 > x_2 + x_3 \ \& \ x_3 > 0]$$

F_R will be built by using:

atomic formulas $t_1 = t_2, t_1 < t_2$ where $t_1, t_2 \in \mathbb{N}[\bar{x}]$.

logical operators $\&$ (logical “and”), \vee (logical “or”)

existential quantifier \exists (universe = \mathbb{N})

restricted universal quantifier $\forall z < U$ (universe = \mathbb{N} and $U \in \mathbb{N}$ fixed)

Proposition 1.3.10. *If a turing-machine M_R enumerates R then we can construct a first-order arithmetic formula $F_R(b)$ that imitates M_R step-by-step till it prints b only by using the above.*

Proof. We construct

- a first-order arithmetic formula $F_R(b)$ that imitates M_R step-by-step until it prints b .
- First attempt: Assume one head and one tape in M_R
 - associate a configuration of M_R with a vector

$$C := [s(C), p(C), q(C), a_0(C), \dots, a_{q(C)-1}(C)]$$

where s is the state, p is the number of the cell where the head points to, q is the number of used cells and a_i are the bits on the tape.

- $F_R(b) := \exists C_1 \exists C_2 [Start(C_1) \ \& \ Compute(C_1, C_2) \ \& \ Stop(C_2, b)]$
- $Start(C_1)$: asserts the start configuration

$$(s(C_1) = q_{start}) \ \& \ (p(C_1) = 1) \ \& \ (a_0(C_1) = \square)$$

- $Stop(C_2, b)$: asserts that $b = (b_0, \dots, b_{m-1})$ has been printed

$$(\exists m < q(C_2)) \ \& \ (\forall i < m)(a_i(C_2) = b_i) \ \& \ (a_m(C_2) = \square)$$

- $Compute(C_1, C_2)$: asserts that there is a configuration sequence

$$L = [g_0(L), \dots, g_w(L)]$$

s.t. M_R follows them to reach C_2 from C_1

$$\exists L \exists w (g_0(L) = C_1) \ \& \ (g_w(L) = C_2) \ \&$$

$$((\forall i < w) \exists C_3 \exists C_4 (g_i(L) = C_3) \ \& \ (g_{i+1}(L) = C_4))$$

$$\ \& \ \bigwedge_{I \in \delta_{M_R}} Step_I(C_3, C_4)$$

- $Step_I(C_3, C_4)$: assert that C_3 to C_4 is a step following an instruction $I \in \delta_{M_R}$: Say, $I = (s, b) \mapsto (s', b', \epsilon); \epsilon \in \{L, R, S\}$. For $\epsilon = S$:

$$\begin{aligned} (s(C_3) = s) \quad \& \quad (s(C_4) = s') \quad \& \\ (\exists k \exists n (\quad \quad \quad (p(C_3) = k) \quad \& \quad (p(C_4) = k) \\ \quad \quad \quad \& \quad (a_k(C_3) = b) \quad \& \quad (a_k(C_4) = b') \\ \& \ (\forall i < n) \quad \quad (a_i(C_3) = k) \quad \vee \quad a_i(C_4) \quad)) \end{aligned}$$

Exercise 1.3.11. Do it for $\epsilon = L$ and $\epsilon = R$

- the problem is we are quantifying over vectors C_1 and C_2 of variable length (even worse: L is a vector of vectors).
- Remedy: Try encoding a vector $[a_0, \dots, a_{n-1}]$ as a pair (x, y) of integers.
- How to decode a_i back from (x, y) arithmetically?

□

Theorem 1.3.12. Chinese Remainder Theorem: If m, n are coprime integers then

$$\forall a, b \ \exists x [x \equiv a \pmod{m} \ \& \ x \equiv b \pmod{n}]$$

or equivalently: If $\gcd(m, n) = 1$ then $\mathbb{Z}/mn\mathbb{Z} \cong \mathbb{Z}/m\mathbb{Z} \times \mathbb{Z}/n\mathbb{Z}$.

Exercise 1.3.13. Proof 1.3.12

- Encode $C = [n, a_0, \dots, a_{n-1}]$ as (x, y) s.t.

$$\begin{aligned} n &\equiv x \pmod{y+1} \\ a_0 &\equiv x \pmod{2y+1} \\ a_1 &\equiv x \pmod{3y+1} \\ &\dots \\ a_{n-1} &\equiv x \pmod{ny+1} \end{aligned}$$

- Decoding requires modulo computation:

$$a \equiv b \pmod{c} \Leftrightarrow (\exists d) [(a = b + cd) \vee (a = b - cd)]$$

- There always exists (x, y) encoding $[a_0, \dots, a_{n-1}, n]$. Proof. it suffices to use a y s.t. $\{y+1, 2y+1, \dots, (n+1)y+1\}$ are mutually coprime. Verify that $\text{lcm}(1, \dots, n+1) \mid y$ then it works. \square
- How to express $y \equiv 0 \pmod{\text{lcm}(1, \dots, n+1)}$ arithmetically?

$$\text{lcm} \mid y \Leftrightarrow (\forall i < n+2)(y \equiv 0 \pmod{i})$$

Exercise 1.3.14. Finish the construction of $F_R(b)$.

Proposition 1.3.15. If a first-order arithmetic formula has no universal quantifier then we can derive a Diophantine instance from it.

Proof. We distinct the following cases:

- $(\exists z)(P(z) = 0)$ is just a Diophantine instance
- $\exists z_1 \exists z_2 : (P(z_1) = 0 \ \& \ P(z_2) = 0) \Leftrightarrow \exists z_1 \exists z_2 : (P^2(z_1) + P^2(z_2) = 0)$
- $\exists z_1 \exists z_2 (P(z_1) = 0 \vee Q(z_2) = 0) \Leftrightarrow \exists z_1 \exists z_2 (P(z_1)Q(z_2) = 0)$
- $\exists z_1 \exists z_2 (P(z_1) < Q(z_2)) \Leftrightarrow \exists z_1 \exists z_2 \exists z (P(z_1) + z + 1 - Q(z_2) = 0)$

Induction finishes the proof. \square

So lets proof 1.3.5 assuming we already have a Diophantine representation of:

Binomial Coefficient $x = \binom{y}{z}$

Factorial $x = y!$

Exponential function $x = y^z$

Proof. Let M_R be the enumerator of R . We have already constructed F_R in 1.3 and the only part of it left to convert to a Diophantine problem is:

$$(\forall z < U) \exists x_1 \dots \exists x_n (P(b, z, x_1, \dots, x_n) = 0)$$

Our aim is to get an equivalent formula that looks like

$$\exists y_1, \dots, \exists y_m (Q(b, y_1, \dots, y_m) = 0)$$

The assertion is actually existential, it says there exists:

$$\begin{array}{ll} \text{for} & z = 0 : x_1^{(0)}, \dots, x_n^{(0)} \\ \text{for} & z = 1 : x_1^{(1)}, \dots, x_n^{(1)} \\ \text{for} & z = U - 1 : x_1^{(U-1)}, \dots, x_n^{(U-1)} \end{array}$$

We want to compress the columns $[0, \dots, U-1]$ as Z and x_i^0, \dots, x_i^{U-1} as w_i . So we use the Chinese Remainder idea again: suppose we fix U coprime integers u_0, \dots, u_{U-1} then there is a vector (U, w_1, \dots, w_n) s.t.:

$$\forall z \in \{0, \dots, U-1\} \forall i \in \{1, \dots, n\}, w_i \equiv x_i^{(z)} \pmod{u_z}$$

This encodes the z -th row by (Z, w_1, \dots, w_n) but modulo u_z . Because now

$$P(b, Z, w_1, \dots, w_n) \equiv 0 \pmod{u_z} \quad \forall z < U$$

or equivalently

$$P(b, Z, w_1, \dots, w_n) \equiv 0 \pmod{u_0 \cdot \dots \cdot u_{U-1}}$$

So we have captured zeroness $\pmod{u_z}$ and we make it absolut by choosing u_z large enough. So its remains to find out how large we have to choose u_z . Say $|x_i^{(z)}| < X \quad \forall z, N = \deg(P)$ and $M = \text{sum of absolute coefficients in } P$. Then

$$|P(b, z, x_1, \dots, x_n)| < M \cdot ((b+1) \cdot U \cdot X)^N =: T$$

Thus forcing $u_z > T$ gives us:

$$P(b, Z, w_1, \dots, w_n) \equiv 0 \pmod{u_z} \Rightarrow P(b, z, x_1^{(z)}, \dots, x_n^{(z)}) \pmod{u_z}$$

Since $u_z > T > |P(b, z, x_1^{(z)}, \dots, x_n^{(z)})|$ it follows that $P(b, z, x_1^{(z)}, \dots, x_n^{(z)}) = 0$.

So we need coprime u_z s whose product has a Diophantine representation. Assuming the representation of the binomial coefficient, let us fix:

$$\begin{aligned} u_0 \cdot \dots \cdot u_{U-1} &= \binom{v}{u} \\ &= \frac{v(v-1)\dots(v-u+1)}{1 \cdot 2 \cdot \dots \cdot u} \\ &= \left(\frac{v+1}{1} - 1\right) \cdot \left(\frac{v+1}{2} - 1\right) \cdot \dots \cdot \left(\frac{v+1}{U} - 1\right) \end{aligned}$$

Pick $u_z = \left(\frac{v+1}{z+1} - 1\right)$.

- To make $u_z \in \mathbb{N} : (u!)|(v+1)$
- Note that $\gcd\left(\frac{v+1}{1} - 1, \frac{v+1}{j} - 1\right) = \gcd\left(\frac{v+1}{i} - 1, \frac{v+1}{i} \frac{j-i}{j}\right) = \gcd\left(\frac{v+1}{i} - 1, \frac{j-i}{j}\right)$
- Show that $u_z > u_{z+1}$

Exercise 1.3.16. a) If we force $(u!)^2|(v+1)$ then u_0, \dots, u_{U-1} are coprime naturals.

b) $v \equiv z \pmod{u_z}$

$$G_1: P(b, V, w_1, \dots, w_n) \equiv 0 \pmod{u}$$

$$\forall i \in \{1, \dots, n\} : G_{2,i} (\forall z < U)(w_i \pmod{\left(\frac{v+1}{z+1} - 1\right)} < X) :$$

$$G_3: \left(\frac{v+1}{U} - 1\right) \geq M \cdot ((b+1) \cdot U \cdot X)^N$$

$$G_4: v+1 \equiv 0 \pmod{(u!)^2}$$

Exercise 1.3.17. Verify that

$$\exists X \exists V \exists w_1, \dots \exists w_n (G_1 \& G_{21} \& \dots \& G_{2n} \& G_3 \& G_4)$$

is equivalent to

$$(\forall z < U) \exists x_1 \dots \exists x_n (P(b, z, x_1, \dots, x_n) = 0)$$

The only kind of universal quantifier that we need to remove is:

$$(\forall z < U)(w_i \pmod{u_z < X} \dots w_i \pmod{u_z < X})$$

if and only if (u_z divides at least one of $w_i, w_i - 1, \dots, w_i - X + 1$). The second statement implies that $u_z | w_i \cdot (w_i - 1) \cdot \dots \cdot (w_i - X + 1)$ which is equivalent to $u_z | \frac{w_i!}{(w_i - X)!}$. So $(\forall z < U)(w_i \pmod{u_z < X}) \Rightarrow \overset{v}{u} | \frac{w_i!}{(w_i - X)!}$. If we know how to express $\overset{v}{u}$ and factorial then we can express the condition

$$G'_{2,i}: \overset{v}{u} | \frac{w_i!}{(w_i - X)!}$$

which says that

$$\forall z \in \{0, \dots, U - 1\} \forall i \in \{1, \dots, n\} : u_z | \frac{w_i!}{(w_i - X)!}$$

So Fix a $z \in \{0, \dots, U - 1\}$ and from the fact $u_z | \frac{w_i!}{(w_i - X)!}$ we get:

$$\exists S_1 | (u_z), S_1 > u_z^{\frac{1}{x}} \exists y_1^{(z)} < X, S_1 | (w_1 - y_1^{(z)})$$

from $S_1 | \frac{w_2!}{(w_2 - X)!}$ we get:

$$\begin{aligned} \exists S_2 | S_1, S_2 &> u_z^{\frac{1}{x^2}} \exists y_2^{(z)} < X, S_2 | (w_2 - y_2^{(z)}) \\ &\dots \\ \exists S_n | S_{n-1}, S_n &> u_z^{\frac{1}{x^n}} \exists y_n^{(z)} < X, S_n | (w_n - y_n^{(z)}) \\ &\Rightarrow S_n > (u_z)^{\frac{1}{x^n}} \& S_n | (w_1 - y_1^{(z)}, \dots, (w_n - y_n^{(z)})) \\ \Rightarrow P(b, V, w_1, \dots, w_n) &\equiv P(b, z, y_1^{(z)}, \dots, y_n^{(z)}) \equiv 0 \pmod{S_n} \end{aligned}$$

So if we choose $S_n > T$ then $P(b, z, y_1^{(z)}, \dots, y_n^{(z)}) = 0$. So choose

$$G'_3: u_{U-1} \geq (M((b+1)XU)^N)^{x^n}$$

Exercise 1.3.18. Verify that:

$$\exists X \exists V \exists w_1 \dots \exists w_n (G_1 \& G'_{2,1} \& \dots \& G_{2n'} \& G'_3 \& G_4)$$

is equivalent to

$$(\forall z < U) \exists x_1 \dots \exists x_n (P(b, z, x_1, \dots, x_n) = 0)$$

□

Lemma 1.3.19. We can find a Diophantine representation of the binomial coefficients using that of the exponential: That means, we want a Diophantine representation of the predicat:

$$(z \leq y) \& \frac{y}{z}:$$

Proof.

$$\begin{aligned} (1+p)^y &= \sum_{i=0}^y \binom{y}{i} p^i \\ &= u + \left(\frac{y}{z} + pv\right) p^z \\ u &:= \sum_{i=0}^{z-1} \binom{y}{i} p^i \\ v &:= \sum_{i=z+1}^y \binom{y}{i} p^{i-z-1} \end{aligned}$$

So we can hope to

a) quotient $((1+p)^y/p^3)$

b) and by $(\text{mod } p)$ we get $\frac{y}{z}$

The two divisions (first by p^3 and the second by p) give $\frac{y}{z}$ if and only if $u < p^z$ & $\frac{y}{z} < p$. So let us choose $p = (3^y + 1)$:

a)

$$\begin{aligned} u &= \sum_{i=0}^y z - 1 \cdot i p^i \\ &< 2^y \sum_{i=0}^y z - 1 p^i \\ &= 2^y \frac{p^z - 1}{p - 1} \\ &= 2^y \frac{p^z - 1}{3^y} \\ &< p^z \end{aligned}$$

b) $\frac{y}{z} < 2^y < p$

The two divisions will extract $\frac{y}{z}$ from $(1+p)^y$ for $p = (3^y + 1)$.

Exercise 1.3.20. Verify that: $(z \leq y)$ & $(x = \frac{y}{z})$ is equivalent to

$$(z \leq y) \ \& \ \exists p \exists u \exists v ((p = 3^y + 1) \ \& \ ((1+p)^y = u + (x+vp)p^z) \ \& \ (u < p^z) \ \& \ (x < p))$$

So a Diophantine representation of exponential yields a Diophantine representation of $x = \frac{y}{z}$. \square

Lemma 1.3.21. We can find a Diophantine representation of factorial:

$$x = y!$$

using exponential and binomial coefficients.

Proof. Note that $y!$ appears in $y^w = \frac{w!}{y!(w-y)!}$. Let $w \gg y$ then $y^w \approx \frac{w^w}{y!} \Rightarrow y! = \frac{w^w}{\frac{w^w}{y}}$. So how big should w be?

$$y! \leq \frac{w^y}{y} = y! \frac{w}{w} \frac{w}{w-1} \cdots \frac{w}{w-y+1} \leq y! \left(\frac{w}{w-y} \right)^y = y! \left(1 + \frac{y}{w-y} \right)^y$$

So let $\frac{1}{t} = \frac{y}{w-y}$:

$$\begin{aligned} \frac{w^y}{y} &\leq y! \left(1 + \frac{1}{t} \right)^y \leq y! \left(1 + \sum_{i=1}^y i \frac{1}{t^i} \right) \\ &\leq y! \left(1 + \frac{2^y y}{t} \right) = y! + \frac{2^y y y!}{t} \end{aligned}$$

let $t = 2^y y y^y$, then $\frac{w^y}{y} \leq y! + \frac{1}{2}$ and note that $w = y + 2^{y+1} y y^y + 2$ and that $y! \leq \frac{w^y}{y} \leq y! + \frac{1}{2}$. By keeping the integral part of this term we have computed $y!$. \square

Exercise 1.3.22. Verify that: $x = y!$ is equivalent to

$$\exists w \exists r \left((w = y + 2^{y+1} y^{y+2}) \ \& \ (w^y = x \frac{w}{y} + r) \ \& \ (r < \frac{w}{y}) \right)$$

Lemma 1.3.23. *We will now reduce exponential to a special exponential: Compute v^n modulo a small polynomial in v (e.g. $v^2 - 2av + 1$). $v^n \equiv x_n(a) + y_n(a)(v - a) \pmod{v^2 - 2av + 1}$ where $a \geq 2$ & $((a + \sqrt{a^2 - 1})^n = x_n(a) + y_n(a)\sqrt{a^2 - 1})$*

Proof. Viewing $(v^2 - 2av + 1)$ as a polynomial in v . it factors as: $(v - (a + \sqrt{a^2 - 1}))(v - (a - \sqrt{a^2 - 1}))$. For $v = (a + \sqrt{a^2 - 1})$ or $v = (a - \sqrt{a^2 - 1})$ the congruence is true. \square

Suppose we have a Diophantine representation of $x_n(a)$ and $y_n(a)$ say

$$F(a, x, y, n) := ((x = x_n(a) \ \& \ y = y_n(a))$$

Then we immediately have a representation of $u \equiv v^n \pmod{v^2 - 2av + 1}$. It will be an absolute equality if $(2av - v^2 - 1) > u, v^n$.

Lemma 1.3.24. $x_n(b) \geq b^n \ \forall b \geq 2$

Proof. We have $(b + \sqrt{b^2 - 1})^n = x_n(b) + y_n(b)\sqrt{b^2 - 1}$. We see that $x_0(b) = 1$ and $x_1(b) = b$. Observe that $x_{n+1}(b) + y_{n+1}(b)\sqrt{b^2 - 1} = (x_n(b) + y_n(b)\sqrt{b^2 - 1})(b + \sqrt{b^2 - 1}) = (bx_n(b) + (b^2 - 1)y_n(b)) + (x_n(b) + by_n(b))\sqrt{b^2 - 1}$ which implies by comparison of coefficients

$$\begin{aligned} x_{n+1}(b) &= bx_n(b) + (b^2 - 1)y_n(b) \\ &\geq bx_n(b) \\ \Rightarrow x_{n+1}(b) &\geq bn + 1 \end{aligned}$$

\square

We can make $2av - v^2 - 1 > v^n$ if we force $(2av - v^2 - 1) > x_n(v)$. So the conditions for $u = v^n$ are:

$$E_1: F(a, x, y, n) \text{ represents } (a + \sqrt{a^2 - 1})^n = x + y\sqrt{a^2 - 1}$$

$$E_2: u \equiv x + y \pmod{v^2 - 2av + 1} \text{ represents } u \equiv v^n \pmod{v^2 - 2av + 1}$$

$$E_3: (u < (2av - v^2 - 1)) \ \& \ (X < (2av - v^2 - 1))$$

$$E_4: F(v, X, Y, n) \text{ represents } (v + \sqrt{v^2 - 1})^n = (X + Y\sqrt{v^2 - 1}) \Rightarrow X \geq v^n$$

Exercise 1.3.25. *Verify that: $(u = v^n)$ is equivalent to*

$$\exists a \exists x \exists y \exists X \exists Y (E_1 \ \& \ E_2 \ \& \ E_3 \ \& \ E_4)$$

Finally we want to represent $x_n(a)$ and $y_n(a)$ such that

$$(a + \sqrt{a^2 - 1})^n = x_n(a) + y_n(a)\sqrt{a^2 - 1}$$

$(x_n(a), y_n(a))$ are roots of a special Fermat's equation:

$$x^2 - (a^2 - 1)y^2 = 1$$

because: $1 = x_n(a)^2 - (a^2 - 1)y_n(a)^2$ and $(a + \sqrt{a^2 - 1})(a - \sqrt{a^2 - 1}) = 1$

In the hope of representing $(x_n(a), y_n(a))$ we investigate this equation:

We can write a recurrence for $(x_{m+n}(a))$ in terms of $x_m(a)$, $y_n(a)$ and $x_n(a)$ because of $x_{m+n}(a) + y_{m+n}(a)\sqrt{a^2 - 1} = (x_m(a) + y_m(a)\sqrt{a^2 - 1})(x_n(a) + y_n(a)\sqrt{a^2 - 1})$

Lemma 1.3.26.

$$\begin{aligned} x_{m+n} &= x_m x_n + (a^2 - 1) y_m y_n \\ y_{m+n} &= x_m y_n + x_n y_m \\ x_{n+1} &= a x_n + (a^2 - 1) y_n \\ x_{n+1} &= a y_n + x_n \end{aligned}$$

Lemma 1.3.27. *Say $a \geq 2$. Then*

$$x^2 - (a^2 - 1)y^2 = 1; x, y \geq 0 \Leftrightarrow \exists n (x = x_n(a) \ \& \ y = y_n(a))$$

Proof. “ \Leftarrow ” is clear, so suppose $x^2 - (a^2 - 1)y^2 = 1$ and (w.l.o.g.) $y > 1$.

$$\begin{aligned} &\Rightarrow (x - y\sqrt{a^2 - 1})(x + y\sqrt{a^2 - 1}) = 1 \\ &\Rightarrow [(x - y\sqrt{a^2 - 1})(a + \sqrt{a^2 - 1})][x + y\sqrt{a^2 - 1}](a - \sqrt{a^2 - 1}) = 1 \end{aligned}$$

Look at the integral points give by this equation: $(ax - y(a^2 - 1), -x + ay)$ which is obviously satisfying the fermat equation. It is an \mathbb{N} -point and its “smaller” than (x, y) .

- Suppose $ax < y(a^2 - 1)$ then $1 = x^2 - (a^2 - 1)y^2 < y^2 \frac{(a^2 - 1)^2}{a^2} - (a^2 - a)y^2 = \frac{(a^2 - 1)y^2}{a^2}(-1) < 0$, a contradiction.
- Suppose $x < ay$ then $1 = x^2 - (a^2 - 1)y^2 = a^2 y^2 - (a^2 - 1)y^2 = y^2 > 1$ also a contradiction.
- Suppose $-x + ay \geq y$ then $1 = x^2 - (a^2 - 1)y^2 \leq (a - 1)^2 y^2 - (a^2 - 1)y^2 = (-2a + 1)y^2 < 0$, a contradiction.

□

We can see that several (say n) applications of the descent will have to stop at: $y = 1, x = a$.

$$\begin{aligned} &(x + y\sqrt{a^2 - a})(a - \sqrt{a^2 - 1})^n = (a + \sqrt{a^2 - 1}) \\ &\Rightarrow (x + y\sqrt{a^2 - a}) = (a + \sqrt{a^2 - 1})^{n+1} \end{aligned}$$

Thus, $x = x_{n+1}(a) \ \& \ y = y_{n+1}(a)$.

Next we show that modulo relations: $x_N(a) \equiv x_m(a) \pmod{x_n(a)}$ is almost equivalent to: $N \equiv m \pmod{n}$.

Lemma 1.3.28. *Say, $a \geq 2 \ \& \ 0 < m < n$. Then*

$$\forall N, x_N(a) \equiv x_m(a) \pmod{x_n(a)} \Leftrightarrow N \equiv \pm m \pmod{4n}$$

Proof. Let us compute $x_{i+2n} \pmod{x_n}$:

$$\begin{aligned} x_{i+2n} + y_{i+2n}\sqrt{a^2 - 1} &= (x_i + y_i\sqrt{a^2 - 1})(x_n + y_n\sqrt{a^2 - 1})^2 \\ \Rightarrow x_{i+2n} &\equiv x_i y_n^2 (a^2 - 1) \pmod{x_n} \\ \Rightarrow x_{i+2n} &\equiv x_i (x_n^2 - 1) \pmod{x_n} \\ \Rightarrow x_{i+2n} &\equiv -x_i \pmod{x_n} \end{aligned}$$

□

Exercise 1.3.29. *Similary, compute $x_{2n-i} \pmod{x_n}$ and proof that*

$$x_{2n-i} \equiv -x_i \pmod{x_n}$$

Therefor, we have:

- $\{x_0x_1, \dots, x_{n-1}\}$
- $\{x_n, \dots, x_{2n-1}\} \equiv_{x_n} \{-x_n, -x_{n-1}, \dots, x_1\}$
- $\{x_{2n}, \dots, x_{3n-1}\} \equiv_{x_n} \{-x_0, -x_1, \dots, -x_{n-1}\}$
- $\{x_{3n}, \dots, x_{4n-1}\} \equiv_{x_n} \{x_n, x_{n-1}, \dots, x_1\}$

Exercise 1.3.30. Show that $x_0 < x_1 < \dots < x_{n-1} < x_n$ using 1.3.26

So x_m appears at $\pm m \pmod{4n}$ places. Now do the same thing for y :

Lemma 1.3.31. Say, $a \geq 2$ & $n \geq 1$ then $\forall N : y_N(a) \equiv 0 \pmod{y_n(a)} \Leftrightarrow N \equiv 0 \pmod{n}$

Exercise 1.3.32. proof this lemma.

We can also look at $y_N \pmod{y_n^2}$:

Lemma 1.3.33. Say, $a \geq 2$ & $n \geq 1$, then $\forall N, y_N(a) \equiv 0 \pmod{y_n(a)^2} \Leftrightarrow N \equiv 0 \pmod{ny_n}$.

Proof. “ \Rightarrow ” Suppose $y_n^2 | y_N$ then $n | N$ and so $\exists k, N = kn$:

$$\begin{aligned} \Rightarrow (x_N + y_N \sqrt{a^2 - 1}) &= (x_{kn} + y_{kn} \sqrt{a^2 - 1}) = (x_n + y_n \sqrt{a^2 - 1})^k \\ &= \sum_{i=0}^k \binom{k}{i} x_n^{k-i} \cdot (y_n \sqrt{a^2 - 1})^i \\ \Rightarrow y_n &\equiv kx_n^{k-1} y_n \pmod{y_n^2} \end{aligned}$$

Since $y_n^2 | y_N$ we get $y_n | kx_n^{k-1} \Rightarrow y_n | k \Rightarrow ny_n | N$. “ \Leftarrow ” Suppose $ny_n | N$. Then $\exists k : N = kn$ & $y_n | k$ and $y_N \equiv 0 \pmod{y_n^2}$ by 1.3. \square

Now look $\pmod{a-1}$:

Lemma 1.3.34. Say $a \geq 2$ & $n \geq 1$ then $(x_n, y_n) \equiv (1, n) \pmod{a-1}$.

Proof.

By 1.3.26:

$$\begin{aligned} x_{i+1} &= ax_i + (a^2 - 1)y_i \\ x_{i+1} &= x_i + ay_i \\ x_{i+1} &\equiv x_i \pmod{a-1} \Rightarrow x_i \equiv 1 \pmod{a-1} \\ x_{i+1} &\equiv x_i + y_i \pmod{a-1} \Rightarrow y_i \equiv i \pmod{a-1} \end{aligned}$$

Simply 1.3.26:

Lemma 1.3.35.

$$a \equiv a' \pmod{b} \Rightarrow (x_n(a), y_n(a)) \equiv (x_n(a'), y_n(a')) \pmod{b}$$

Exercise 1.3.36. proof this lemma

Now we are ready to give a Diophantine representation of $F(a, x, y, n) := (a + \sqrt{a^2 - 1})^n = x + y\sqrt{a^2 - 1}$. We certainly need $F_1 : x^2 - (a^2 - 1)y^2 = 1$. But how do we ensure that (x, y) is the n -th point in F_1 ? So we can put $y \equiv n \pmod{a-1}$, but it is not enough as n can be much larger hen a . The idea is to construct sort of an n -th (X, Y) point on another Fermat-equation $F_2 : X^2 - (A^2 - 1)Y^2 = 1$ which has a large A . Then connect the points (x, y) and (X, Y) by a third point (U, V) satisfying $F_3 : U^2 - (a^2 - 1)V^2 = 1$ such that $F(a, x, y, n)$ is forced.

$$\text{Say } (x, y) = (x_m(a), y_m(a)); (U, V) = (x_N(a), x_N(a)), (X, Y) = (x_M(A), y_M(A)).$$

Force M to be sort of n $F_4 : Y \equiv n \pmod{A-1}$ which implies 1.3.35 $\Rightarrow M \equiv n \pmod{A-1}$

connect (X, Y) to (x, y) via (U, V)

$$F_5 : 0 < x < U \ \& \ X \equiv x \pmod{U} \ \& \ A \equiv a \pmod{U}$$

and with 1.3.27 it follows that $x_M(a) \equiv x_m(a) \equiv x_n(a) \pmod{y_N(a)}$ and by 1.3.31 it follows that $M \equiv \pm m \pmod{4N}$.

connect these two congruences $F_6 : V \equiv 0 \pmod{m^2dy^2}$ by 1.3.34 it follows that $my|N$. $F_7 : A - 1 \equiv 0 \pmod{4y}$ which implies $4y|(A - 1), 4N \Rightarrow n \equiv \pm m \pmod{4y}$

make the congruence absolute $F_8 : n \leq y$ which implies $m \leq y \Rightarrow n = m$

Exercise 1.3.37. Verify that $(a \geq 2) \ \& \ (a + \sqrt{a^2 - 1})^n = (x + y\sqrt{a^2 - 1})$ is equivalent to $(a \geq 2) \ \& \ \exists A \exists X \exists Y \exists U \exists V (F_1 \ \& \ \dots \ \& \ F_8)$

□

Chapter 2

P , NP and beyond

We now consider problems that have obvious algorithms that run in finite time and will study the resources required by an algorithm. Examples for resources are:

time which is the number of transitions of a turing machine M till it stops on a given input x . We say that is the “time taken by M on x ”.

space which is the number of cells used on the tape

randomness which is a more exotic resources, describing the number of random bits an algorithm uses

Time taken by M is viewed as a function $\text{time}_M : \mathbb{N} \rightarrow \mathbb{N}, n \mapsto \text{time}_M(n)$ where $\text{time}_M(n) := \max_{|x|=n} \{\text{time taken by } M \text{ on } x\}$. As time_M is dependent on low-level details of M , it is quite messy to specify time_M exactly. So we just approximate $\text{time}_M(n)$ by asymptotic. Two functions $f, g : \mathbb{N} \rightarrow \mathbb{N}$ can be in the following relations:

- a) $f = O(g) \Leftrightarrow \exists c, N > 0 \forall n \geq N. f(n) \leq cg(n)$
- b) $f = \Omega(g) \Leftrightarrow g = O(f)$
- c) $f = \Theta(g) \Leftrightarrow f = O(g) \ \& \ g = O(f)$
- d) $f = o(g) \Leftrightarrow \forall \epsilon \in \mathbb{R}^{>0} \exists N > 0 \forall n \geq N$
- e) $f = \omega(g) \Leftrightarrow g = o(f)$

Example 2.0.38. $10n^2 + 100 \log(n) = O(n^2), \Theta(n^2), \omega(n^{1.99}) \neq \omega(n^2)$

Definition 2.0.39. We say that

- g is an upper bound on f if $f = O(g)$
- f is a lower bound on g if $g = \Omega(f)$

Exercise 2.0.40. Show that the high-school method to add two integers takes time $\Theta(n)$.

2.1 Polynomialtime

For a function $T : \mathbb{N} \rightarrow \mathbb{N}$ we define a set of languages (which is equivalent to decision problems) that have algorithms of time $O(T(n))$:

$$\text{Dtime}(T) := \{L \subset \{0,1\}^* \mid L \text{ is decided by a turing machine } M \\ \& \text{ time}_M(n) = O(T(n))\}$$

Which algorithms should we call “efficient” now? Algorithms that run in time $O(|x|^n)$ for a constant n are called efficient. The set of all these problems is called P :

$$P := \bigcup_{c \in \mathbb{N}} \text{Dtime}(n^c)$$

It stands for polynomial-time algorithms. We call an algorithm or a turing machine M deterministic polynomial-time if it is solving a problem $L \in P$. There are some tricky issues with polynomial time: For $\text{time}_{M_1} = f_1(n) = n^{100}$, $\text{time}_{M_2} f_2(n) = n^{lg\lg n}$ the turing machine M_1 is polynomial-time while M_2 is not. M_2 is more than polynomial-time. But

$$\text{time}_{M_2}(n) > \text{time}_{M_1}(n) \Leftrightarrow n > 2^{2^{100}}$$

Nevertheless P is the most elegant way to study inherent complexity of natural problems.

2.2 NP: Nondeterministic polynomial-time

Let us start with some example problems:

Travelling Salesman Problem (TSP) Suppose we are given a complete graph on n nodes $\{1, \dots, n\}$ with distances $\{d_{ij} \in \mathbb{N} \mid 1 \leq i, j \leq n\}$. Is there a closed circuit visiting each node exactly once of length $\leq k$?

Subset Sum Given a set $S = \{s_1, \dots, s_m\} \subseteq \mathbb{N}$ and $t \in \mathbb{N}$. Is there a subset $T \subseteq S$ that sums to t ?

Integer Programming Given m linear inequalities, over \mathbb{Z} in x_1, \dots, x_n :

$$a_{i1}x_1 + \dots + a_{im}x_m \leq b_i \quad \forall 1 \leq i \leq m$$

Is there a common point $(x_1, \dots, x_m) \in \mathbb{Z}^m$?

Exercise 2.2.1. *Proof that*

- “TSP” can be solved in $O(n!) \approx O(2^{n \log(n)})$ time
- “Subset Sum” can be solved in $O(2^m)$ time
- “Integer Programming” can be solved in $O(2^{m^2})$ time

All these algorithms are in

$$EXP := \bigcup_{c \in \mathbb{N}} \text{Dtime}(2^{n^c})$$

Anything better for these three problems is still unknown!

Exercise 2.2.2. Show that a given candidate solution for “TSP”, “Subset Sum” or “Integer Programming” can be verified in P .

This was observed and the class NP was defined by Cook (1971) and Levin (1973).

Definition 2.2.3. A language $L \subset \{0, 1\}^*$ is in NP if $\exists c \in \mathbb{N}$ and a polynomial-time turing-machine M s.t. $\forall x \in \{0, 1\}^*$:

$$x \in L \Leftrightarrow \exists u \in \{0, 1\}^{|x|^c}, M(x, u) = 1$$

This u satisfying $M(x, u) = 1$ is called a certificate for x with respect to M and M is called a verifier of L .

Lemma 2.2.4. “Subset Sum” is in NP

Proof.

language

$$L := \left\{ (S, t) \mid S \subseteq \mathbb{N}, t \in \mathbb{N}, \exists T \subset S, \sum_{x \in T} x = t \right\}$$

input $x := (S, T)$

certificate $u := T$ for which $\sum_{x \in T} x = t$ & $T \subseteq S$

verifier $M :=$ the turing machine that outputs 1 on input (S, t, T) iff

$$T \subseteq S \ \& \ \sum_{x \in T} x = t$$

constant $c := 1$

□

Exercise 2.2.5. Proof that $P \subseteq NP$ (note that u can be just taken empty)

Lemma 2.2.6. $NP \subseteq EXP$

Proof. Let $L \in NP$, let M be its verifier (of time n^d) and c s.t. $x \in L$ iff $\exists u \in \{0, 1\}^{|x|^c}, M(x, u) = 1$. Define M' to be the turing machine that scans an u of length $|x|^c$, simulates M on (x, u) and outputs 1 iff $M(x, u) = 1$ for some u . Note that M' runs in time $2^{|x|^c} |x|^d < 2^{|x|^{c+1}}$ and that M' accepts x iff $x \in L$. So $L \in Dtime(2^{|x|^{c+1}})$. □

Remark 2.2.7. Its not known whether $P = NP$ or $NP = EXP$.

Definition 2.2.8. A Nondeterministic Turing Machine (NDTM) N is a Turing Machine (1.2.1) with two transition functions, so $N = (\Gamma, Q, \delta_0, \delta_1)$ (+ infinite tapes). At any configuration $C = [s, p, b]$ it's transition is no more unique and it can follow δ_0 or δ_1 each step. N is said to accept $x \in \{0, 1\}^*$ iff there is a non-empty set of options for steps leading to the halt and the accept state. The time taken by N on x is $\min_{paths} \{ \# \text{ steps taken to halt on } x \}$.

We cannot really identify this with a physical device (unlike we did with turing-machine, which are actually computers), so a non-deterministic turing-machine is really an abstract machine. non-deterministic turing-machines motivate a class, like Dtime:

Definition 2.2.9. Let T be a functions $\mathbb{N} \rightarrow \mathbb{N}$, define

$$\text{Ntime}(T(N)) := \{L \subseteq \{0,1\}^* \mid L \text{ is decided by a non-deterministic turing-machine } N \\ \& \text{time}_N(n) = O(T(n))\}$$

Theorem 2.2.10.

$$NP = \bigcup_{c \in \mathbb{N}} \text{Ntime}(n^c)$$

Proof. First we show that $NP \subseteq \bigcup_{c \in \mathbb{N}} \text{Ntime}(n^c)$: Let $L \in NP$. Then L has a deterministic polynomial-time verifier M , s.t. $x \in L$ iff $\exists u \in \{0,1\}^{|x|^c}$, $M(x,u) = 1$. Define a non-deterministic turing-machine N that has transition functions δ_0 and δ_1 s.t. on input x , N writes at each transition either 0 (by δ_0) or 1 (by δ_1). N does this for $|x|^c$ many steps, call this output w . Then N should simulate $M(x,w)$ and copies its output. So $L \in \text{Ntime}(nc + 1 + \text{time}_M(x))$.

Next we show $\bigcup_{c \in \mathbb{N}} \text{Ntime}(n^c) \subseteq NP$. Let $L \in \text{Ntime}(n^c)$. Then there exists a non-deterministic turing-machine N that decides L in time $O(n^c)$. $x \in L$ iff \exists path p in N (which can be views as string of length $O(|x|^c)$) s.t. N accepts x in p which has a deterministic polynomial-time turing-machine given (x,p) as input, simulate N following p . So $L \in NP$. \square

Definition 2.2.11. A boolean formular in conjunctive normal form (CNF) is

$$\phi(x_1, \dots, x_n) = \bigwedge_i \left(\bigvee_j v_{ij} \right)$$

where the literals $v_{ij} \in \{x_1, \dots, x_n, \overline{x_1}, \dots, \overline{x_n}\}$. The Terms in the brakets are called clause. A boolean formula ϕ is called satisfiable if there exists a valuation v of the variables s.t. $\phi(v) = 1$.

NP has a “hardest” problem (with respect to efficiency, not to computability).

Definition 2.2.12. SAT: Given a boolean formula ϕ in CNF, decide if ϕ is satisfiable. The corresponding language is:

$$\text{SAT} := \{\phi \mid \phi \text{ is in CNF and is satisfiable}\}$$

Example 2.2.13.

$$(x_1 \vee \overline{x_2} \vee x_3) \& (\overline{x_2} \vee x_3)$$

(so it's a combination of \vee , $\&$, $\overline{}$)

Lemma 2.2.14.

$$\text{SAT} \in NP$$

Proof. Given a boolean formula ϕ in CNF. The valuation v is the certificate and the verifier is: evaluate ϕ at v . \square

Lemma 2.2.15. $\forall L \in NP$, L can be “efficiently reduced” to SAT.

Proof. (The proof is really what we did in the beginning of proof of Hilbert’s 10th problem) As $L \in NP$ there exists a polynomial-time verifier M s.t.

$$x \in L \Leftrightarrow \exists u \in \{0, 1\}^{|x|^c}, M(x, u) = 1$$

Idea: We want to capture the computation of M on (x, u) step-by-step in a CNF formula ϕ_x s.t. ϕ_x is satisfiable iff $\exists u$ with $M(x, u) = 1$ in other words:

$$\phi_x \in SAT \Leftrightarrow x \in L$$

With each configuration C of M we associated an array of variables:

$$[s(C), p(C), a_0(C), \dots, a_{T-1}(C)]$$

but now we just know T as a functions of $|x|$. Final formula looks like:

$$\phi_x(\dots) := Start(C_1, x) \ \& \ Compute(C_1, C_2) \ \& \ Stop(C_2)$$

where $Compute(C_1, C_2)$ asserts that there is a sequence of configurations $C_1 = g_0, \dots, g_{T-1} = C_2$ s.t. each step is valid (follows δ_M):

$$(g_0 = C_1) \ \& \ (g_{T-1} = C_2) \ \& \ (\forall i < T) \left(\bigvee_{I \in \delta_M} Step_I(g_i, g_{i+1}) \right)$$

and $Step_I(g_i, g_{i+1})$ asserts that the transition from g_i to g_{i+1} follows the instructions $I: (q, b) \mapsto (q', b', \epsilon)$. For $\epsilon =$ “Stay”:

$$\begin{aligned} s(g_i) = q \ \& \ s(g_{i+1}) = q' \\ \& \ \exists k (p(g_i) = p(g_{i+1}) = k \ \& \ a_k(g_i) = b \ \& \ a_k(g_{i+1}) = b' \ \& \\ (\forall j < T) (j = k \vee a_j(g_i) = a_j(g_{i+1}))) \end{aligned}$$

Exercise 2.2.16. a) Observe that “ $a = b$ ” can be written as $\& s$ of $a_i = b_i$ where a_i, b_i are bits.

$$a_i = b_i \Leftrightarrow (a_i \vee \bar{b}_i) \ \& \ (\bar{a}_i \vee b_i)$$

b) $(\forall i < T) E_i \equiv E_0 \ \& \ \dots \ \& \ E_{T-1}$

c) We can convert M to an oblivious turing-machine M' (i.e. on an input x the head-position at the i -th step of M' is just a function of $(|x|, i)$) and then construct ϕ_x .

d) $x \in L$ iff ϕ_x is satisfiable.

□

Theorem 2.2.17. SAT is NP-hard.

Remark 2.2.18. SAT can be “efficiently reduced” to 3SAT (where $3SAT := \{\phi \mid \phi \text{ is a 3 CNF and is satisfiable}\}$). We say that ϕ is in 3 CNF if $\phi = \bigwedge_i (v_{i1} \vee v_{i2} \vee v_{i3})$.

Proof. Idea: A clause like $x_1 \vee \overline{x_2} \vee x_3 \vee \overline{x_4}$ is satisfiable iff $(x_1 \vee \overline{x_2} \vee z) \ \& \ (\overline{z} \vee x_3 \vee \overline{x_4})$ is satisfiable. So ϕ can be converted into an equivalent 3 CNF with more variables and more clauses (but not much more, it's only a polynomial blow-up).
□

3SAT is a hardest problem in NP. We now formalize this feature:

Definition 2.2.19. We say that a problem A reduces to a problem B via a complexity class C (in symbols $A \leq_C B$) iff there is a turing machine M in C s.t. $x \in A$ iff $M(x) \in B$.

Definition 2.2.20. A problem A is Karp reducible to B iff $A \in_P B$ (where P is the polynomial-time complexity class)

Definition 2.2.21. We say that a problem B is NP-hard iff $\forall A \in NP : A \leq_P B$ and we say that it is NP-complete iff B is NP-hard and $B \in NP$.

Exercise 2.2.22. • $A \leq_P B \ \& \ B \leq_P C \Rightarrow A \leq_P C$

- If A is NP-hard & $A \in P \Rightarrow P = NP$
- If A is NP-hard & $A \leq_P B \Rightarrow B$ is NP-hard
- If A and B are NP-complete $\Rightarrow A \leq_P B \ \& \ B \leq_P A$

Corrolar 2.2.23. Thus NP-complete problems are the hardest in NP.

Lemma 2.2.24.

3SAT \leq INTEGER – PROGRAMMING

Proof. Let $\phi = C_1 \ \& \ \dots \ \& \ C_m$ and $x_{i,j} \in \{x_j, \overline{x_j}\}$ the variables in C_i for $i \in \{1, \dots, m\}, j \in \{1, 2, 3\}$ and define for $j \in \{1, 2, 3\}$

$$\begin{array}{llll} \text{if } x_{i,j} = x_j & \text{define } z_{i,j} = y_{i,j} & \in \mathbb{Z} \\ \text{if } x_{i,j} = \overline{x_j} & \text{define } z_{i,j} = 1 - y_{i,j} & \in \mathbb{Z} \end{array}$$

Now for every clause C_i we generate the following inequalities:

$$\begin{array}{rcl} z_{i,1} + z_{i,2} + z_{i,3} & \geq & 1 \\ 1 \geq y_{i,1} & \geq & 0 \\ 1 \geq y_{i,2} & \geq & 0 \\ 1 \geq y_{i,3} & \geq & 0 \end{array}$$

Example: We transform $(x_1 \vee \overline{x_2} \vee \overline{x_3})$ (where $x_1, x_2, x_3 \in \{T, F\}$) into

$$\begin{array}{rcl} y_1 + (1 - y_2) + (1 - y_3) & \geq & 1 \\ 1 \geq y_1 & \geq & 0 \\ 1 \geq y_2 & \geq & 0 \\ 1 \geq y_3 & \geq & 0 \\ y_1, y_2, y_3 & \in & \mathbb{Z} \end{array}$$

Exercise 2.2.25. Show that the integer-program, defined above, is solveable iff ϕ is satisfiable.

□

Definition 2.2.26. *Quadratic equality over finite fields:*

$QUADEQN := \{S \mid S \text{ is a set of quadratic equations over a finite field \& } S \text{ has a root}\}$

Lemma 2.2.27.

$$3SAT \leq_P QUADEQN \ \& \ QUADEQN \in NP$$

Proof. Let $\phi = C_1 \ \& \ \dots \ \& \ C_m$ and $x_{i,j} \in \{x_j, \overline{x_j}\}$ the variables in C_i for $i \in \{1, \dots, m\}, j \in \{1, 2, 3\}$ and define for $j \in \{1, 2, 3\}$

Example: We transform $(x_1 \vee \overline{x_2} \vee \overline{x_3})$ (where $x_1, x_2, x_3 \in \{T, F\}$) into $1 - (1 - x_1)x_2x_3$ with $x_1, x_2, x_3 \in \mathbb{F}_2$.

Define $\psi(\phi) := \prod_{i=1}^m \phi(C_i)$, now we see that $\psi(\phi) = 1$ has an \mathbb{F}_2 -root iff ϕ is satisfiable.

How to reduce the degree (from $3m$ to 2)?

$$1 - (1 - x_1)x_2x_3 \mapsto \begin{cases} 1 - (1 - x_1)z_1 & = & 1 \\ z_1 & = & x_2x_3 \end{cases}$$

□

2.3 co-Classes

Definition 2.3.1. *To a language $L \subseteq \{0, 1\}^*$ we define the co-language \overline{L} by*

$$\overline{L} := \{0, 1\}^* \setminus L$$

Definition 2.3.2.

$$coNP := \{L \subseteq \{0, 1\}^* \mid \overline{L} \in NP\}$$

Remark 2.3.3. *If $L \in NP$ then given an x , it is “easy” to verify whether $x \notin L$ (or equivalently $x \in \overline{L}$).*

Definition 2.3.4. *A DNF formula is a formula in the form:*

$$\bigvee_i \left(\bigwedge_j^{n_i} x_{ij} \ \& \ \bigwedge_j^{m_i} \overline{x_{ij}} \right)$$

Definition 2.3.5. *Problem: Tautology*

$TAUT := \{\phi \mid \phi \text{ is a DNF formula and a tautology (i.e. true for all evaluations)}\}$

Remark 2.3.6.

$$TAUT \in coNP$$

Proof. Given $\phi(x_1, \dots, x_n)$, $\phi \notin TAUT$ iff $\exists v : \phi(v) = \text{False}$. □

Theorem 2.3.7. *TAUT is coNP-hard.*

Proof. Given $L \in coNP$ we can want to reduce L to $TAUT$: We know that there exists a polynomial-time Turing-machine M s.t. $x \in \overline{L}$ iff $\exists u : M(x, u) = 1$. Using the idea in 2.2.17 we construct a boolean formula ϕ_x s.t. $x \in \overline{L}$ iff ϕ_x is satisfiable. So $x \in L$ iff ϕ_x is unsatisfiable. And $\neg\phi_x$ is a tautology. In symbols:

$$L \leq_P TAUT$$

□

Definition 2.3.8.

$$NP \cap coNP := \{L \subseteq \{0,1\}^* \mid L \in NP \ \& \ L \in coNP\}$$

Remark 2.3.9. $P \subseteq NP \cap coNP$ but it is not known whether if this is an equation or a strict subset-relation.

Exercise 2.3.10. “The decision version of integer factoring” $\in NP \cap coNP$

Remark 2.3.11. It is unknown if

$$GraphIso \in NP \cap coNP$$

Theorem 2.3.12.

$$NP \neq coNP \Rightarrow P \neq NP$$

Proof. If $NP \neq coNP$ but $P = NP$ then $P \neq coP = P$ which is a contradiction. \square

Remark 2.3.13. But it’s an open question whether $NP = coNP$ or whether $NP = coNP \Rightarrow P = NP$.

Definition 2.3.14.

$$1^n := \underbrace{1 \dots 1}_{n\text{-times}}$$

Remark 2.3.15. Gödel’s question:

$$Theorems := \{(\phi, 1^n) \mid \phi \text{ is a mathematical statement for which there is a proof of length } \leq n\}$$

First notice that $Theorems \in NP$ and that it is NP -hard. If $P = NP$ then $Theorems \in P$ and mathematicians are obsolete.

2.4 EXP and $NEXP$

Definition 2.4.1.

$$EXP := \bigcup_{C \in \mathbb{N}} Dtime(2^{n^C})$$

is the class of exponential-time problems, and

$$NEXP := \bigcup_{C \in \mathbb{N}} Ntime(2^{n^C})$$

is the class of nondeterministic exponential-time problems.

Remark 2.4.2. $P \subseteq NP \subseteq EXP \subseteq NEXP$ and it is unknown whether any of these relations are strict. It is known that $P \neq EXP$ and $NP \neq NEXP$.

Theorem 2.4.3.

$$P = NP \Rightarrow EXP = NEXP$$

Proof. Let $P = NP$ and $L \in NEXP$, say $L \in Ntime(2^{n^C})$ for some $n, C \in \mathbb{N}$ and M is a polynomial-time turing-machine s.t.

$$x \in L \Leftrightarrow \exists u \in \{0, 1\}^{2^{|x|^C}} : M(x, u) = 1$$

Define a language $L' := \{(x, 1^{|x|^C}) \mid x \in L\}$ (this trick is called padding technice). And we see that $L' \in NP$ with the same verifier as M and the same certificate as in L . So $L' \in P \Rightarrow L \in EXP \Rightarrow NEXP \subseteq EXP \Rightarrow NEXP = EXP$. \square

Remark 2.4.4. *It's unknown whether $EXP = NEXP \Rightarrow P = NP$.*

Definition 2.4.5. *Let $f : \mathbb{N} \rightarrow \mathbb{N}$, define*

$$\text{Space}(f(n)) := \{L \subseteq \{0, 1\}^* \mid L \text{ is decided by a turing machine that uses } O(f(n)) \text{ cells/space}\}$$

and then we can define

$$P_{\text{Space}} := \bigcup_{c \in \mathbb{N}} \text{Space}(n^c)$$

2.5 Hierarchy Theorems

Now we will show some “easy” complexity class sparations: given “strictly more” resources (time, space, nondeterminism) turing machines can solve more problems.

Theorem 2.5.1. *Let $f, g : \mathbb{N} \rightarrow \mathbb{N}$ s.t. $g(n) = \omega(f(n)^2)$ then $Dtime(f(n)) \not\subseteq Dtime(g(n))$.*

Proof. Idea is the use of “diagonalization”, i.e. simulating M_y on y . Consider the turing machine D which does the following on an input $x \in \{0, 1\}^*$:

- Output 0 if x is not a description of a turing machine
- else simulate the encoded turing machine M_x with x as input. Simulate $g(|x|)$ steps:
 - if it does not get an output in $\{0, 1\}$ then output 0
 - else if it does get an output $M_x(x)$ output $1 - M_x(x)$

Notice that D desides a language, say L , in time $g(n)$. So $L \in Dtime(g(n))$. Suppose $L \in Dtime(f(n))$ and let M be a turing machine deciding L in time $\leq c \cdot f(n) \forall n \geq n_0$ for a constant n_0 .

Remark: There exist infinitely many strings $y \in \{0, 1\}^*$ that describe M (add garbage steps and variables to M and encode it again). Pick a “large” $y \in \{0, 1\}^*$ describing M with $g(|y|) \geq (c \cdot f(|y|))^2$ and $y \geq n_0$. What is $D(y)$? $M_y = M$ on y gives an answer in $\{0, 1\}$ in $\leq c \cdot f(|y|)$.

Exercise 2.5.2. *Show that D can simulate “s steps of M ” in $\leq s^2$ steps*

So D can be simulate $c \cdot f(|y|)$ steps of $M_y(y)$ in $g(|y|)$ steps so $D(y) = 1 - M_y(y) = 1 - M(y)$. This contradicts. D and M deciding the same language L . So $L \notin Dtime(f(n))$. \square

Theorem 2.5.3. Let $f, g : \mathbb{N} \rightarrow \mathbb{N}$ s.t. $g(n) = \omega(f(n))$ then $\text{Space}(f(n)) \not\subseteq \text{Space}(g(n))$.

Exercise 2.5.4. Proof the preceding theorem.

Theorem 2.5.5. Let $f, g : \mathbb{N} \rightarrow \mathbb{N}$ s.t. $g(n) = \omega(f(n))$. Then $\text{Ntime}(f(n)) \not\subseteq \text{Ntime}(g(n))$.

Proof. The idea is to use “lazy diagonalisation”: D will be “mostly” be identical to a non-deterministik turing machine M_y and differ only for “very large” y . Define a turing machine D which acts on input $x \in \{0, 1\}^*$:

- If $x \notin \{1\}^*$ then output 0
- else
 - if $s(i) < n < s(i+1)$ then simulate the non-deterministik turing machines $M_i(1n+1)$ for $g(|x|)$ steps
 - if $n = s(i+1)$ then output 1 if $M_i(1^{1+s(i)})$ recets in $g(i+s(i))$ steps and output 0 if it accepts.

If we choose $2^{g(1+s(i))} < g(s(i+1))$ then D decides a language $L \in \text{Ntime}(g(n))$.

Remark: for $g(n) = n$ the function is $2^{1+s(i)} < s(i+1)$ which means that s is very rapidly growing. Again suppose that $L \in \text{Ntime}(f(n))$. First suppose it is, let M be a non-deterministic turing machine deciding L in time $\leq c \cdot f(n)$, $\forall n \geq n_0$. We remark again there are infinitely many strings $y \in \{0, 1\}^*$ describing M . Pick a “large” y describing for M . Notice that $M = M_y$ and for all $n \in (s(y), s(y+1)) \cap \mathbb{Z}$ we see $d(1^n) = M_y(1^n) = M(1^n)$. By step (2) for all $n \in (s(y), s(y+1)) \cap \mathbb{Z}$, $D(1^n) = M_y(1^{n+1}) = M(1^{n+1})$.

$$\Rightarrow M(1^{1+s(y)}) = D(1^{s(y)+1}) = D(1^{s(y)+2}) = \dots = D(1^{s(y+1)})$$

But by step (3): $D(1^{s(y+1)}) \neq M_y(1^{1+s(y)})$ which is a contradiction and

$$L \notin \text{Ntime}(f(n))$$

□

These Hirarchy theorems are based on:

- a) corresponding turing machines can be enumerated
- b) they can be simulated by a turing machine

Definition 2.5.6.

$$PSPACE := \bigcup_{c \in \mathbb{N}} \text{Space}(n^c)$$

$$EXPSPACE := \bigcup_{c \in \mathbb{N}} \text{Space}(2^{n^c})$$

Exercise 2.5.7.

$$P \subseteq NP \subseteq PSPACE \subseteq EXP \subseteq NEXP \subseteq EXPSPACE$$

Corrolar 2.5.8. (from the Hirarchy theorems)

- $P \neq EXP$

- $NP \neq NEXP$
- $PSPACE \neq EXPSPACE$

Are there “expected” to be only NP -hard problems in NP / P ?

Theorem 2.5.9. (*Ladner’s Theorem*) *If $P \neq NP$ then $\exists L \in NP - P$ s.t. L is not NP -complete.*

Proof. $P \neq NP \Rightarrow SAT \notin P$ and we “pad” SAT to get the promised L :

$$SAT_H := \left\{ \phi 01^{|\phi|^{H(|\phi|)}} \mid \phi \text{ is a satisfiable formula in CNF} \right\}$$

for any function $H : \mathbb{N} \rightarrow \mathbb{N}$. First we show that SAT is NP -complete for

$$\lim_{n \rightarrow \infty} H(n) = \infty$$

Suppose that H is unbounded but $SAT \leq_P SAT_H$. This means that for any CNF ψ there is a $\phi(\psi)$ by the polynomial reduction with $\psi \mapsto \phi 01^{|\phi|^{H(|\phi|)}}$. If $|\psi| = n$ then

$$\begin{aligned} |\phi| + |\phi|^{H(|\phi|)} &\leq n^C \\ \Rightarrow |\phi| &\leq n^{\frac{C}{H(|\phi|)}} \\ \Rightarrow |\phi| &= o(n) = o(|\psi|) \end{aligned}$$

Repeating this reduction $|\psi|$ times we get a constant sized formula whose satisfiability can be tested trivially. so $SAT \in P$, a contradiction. So for $H(n) \rightarrow \infty$ SAT_H is not NP -complete.

Secondly define H s.t $H(n) \rightarrow \infty$ and show that $SAT_H \notin P$: Let $H(n)$ be the smallest $i < \log \log n$ s.t. $\forall x \in \{0, 1\}^{\leq \log n}$ and Turing machine M_i generated by i accept x in $i|x|^i$ steps iff $x \in SAT_H$. If there is no such i then $H(n) := \log \log n$. This is an iterative definition of H (it’s not circular). Remark following exercise (not needed for the proof):

Exercise 2.5.10. *Such an $H(n)$ is computable in $o(n^3)$.*

Now suppose that $SAT_H \in P$ and M is a Turing machine solving it in time $\leq cn^c$ for some constant c . Now let j be s.t.

- M is generated by j : $M = M_j$
- $j > c$

Thus M_j decides SAT_H in n^j steps implying by the definition of H that: $H(n) \leq j \quad \forall n$ with $\log \log j$.

- $\Rightarrow SAT_H$ is equivalent to SAT (up to polynomial time computations)
- $\Rightarrow SAT \in P$ a contradiction
- $\Rightarrow SAT_H \notin P$

At last we have to show that $\lim_{n \rightarrow \infty} H(n) = \infty$. Since $SAT_H \notin P$, for any j describing a Turing machine M_j there is an $x_j \in \{0, 1\}^*$ s.t. M_j cannot decide $x_j \in SAT_H$ in time $j|x_j|^j$. Then the definition of H implies that $\{n \mid H(n) = j_0\}$ is finite, in fact $\forall n : n < 2^{|x_j|}$. So $H(n) \rightarrow \infty$ for $n \rightarrow \infty$ and finally $SAT_H \notin P$, SAT_H is not NP -complete and $SAT_H \in NP$. \square

Can one prove that $P \neq NP$ by these diagonalization techniques?

Definition 2.5.11. We call a (non-deterministic) turing machine M an oracle (non-deterministic) turing machine using a language O if M has three special states q_{query} , q_{yes} and q_{no} and a special oracle tape s.t. when M enters the state q_{query} with string x on the oracle tape, in one step it moves to the state q_{yes} (or q_{no}) if $x \in O$ (or $x \notin O$).

Definition 2.5.12.

$$\begin{aligned} P^O &:= \{L \mid L \text{ has a polynomial-time oracle turing-machine using } O\} \\ NP^O &:= \{L \mid L \text{ has a polynomial-time oracle non-deterministic} \\ &\quad \text{turing machine using } O\} \end{aligned}$$

Exercise 2.5.13. a) $\overline{SAT}, TAUT \in P^{SAT}$

b) If $O \in P$ then $P^O = P$

c) With

$$ExpCom := \{(M, x, 1^n) \mid \text{the turing machine } M \text{ accepts } x \text{ in } \leq 2^n \text{ steps}\}$$

then

$$EXP = P^{ExpCom} = NP^{ExpCom}$$

2.6 can $P \neq NP$ be shown by diagonalization techniques?

The separation proofs we saw till now also hold under any fixed oracle O , e.g.

$$Dtime(f(n))^O \neq Dtime(f(n)^3)^O$$

Definition 2.6.1. Proofs about turing machines that also hold for every oracle O are called relativizing proofs.

We will now show, that diagonalization proofs are not able to show $P \neq NP$ or in other words: A proof of $P \neq NP$ will be non-relativizing.

Theorem 2.6.2. (Baker-Gill-Solovay) \exists oracles A and B s.t. $P^A = NP^A$ and $P^B \neq NP^B$.

Proof. Define

$$A := \{(M, x, 1^n) \mid \text{a turing machine } M \text{ accepts } x \text{ in less than } 2^n \text{ steps}\}$$

Exercise 2.6.3. Proof that $EXP = P^A = NP^A$.

We will construct B by diagonalization. For any language B let

$$U_B := \{1^m \mid \exists x \in B \text{ of length } m\}$$

and we will construct B s.t. $U_B \in NP^B$ but $U_B \notin P^B$. First note that there is an enumeration of oracle turing machines:

$$\{M_i \mid i \text{ describes the oracle turing machine } M_i\}$$

ordered according to the increasing order of i . we will define B iteratively. Initially $B = \emptyset$ and in the i -th iteration we already have defined a finite number of strings in or out of B and let n_i be an integer greater than the length of any string whose status is already defined. Run M_i^B on 1^{n_i} for a maximum of $2^{n_i} - 1$ steps:

- (1) if M_i queries B on a string whose status is undetermined, we define it “out of B ”.
- (2) if M_i queries B on a string whose status is known, be consistent
- (3) eventually in $2^{n_i} - 1$ steps if M_i^B accepts 1^{n_i} then we define all strings of length n_i “out of B ”.
- (4) if M_i^B rejects 1^{n_i} then we put an undetermined string of length n_i (a string which status is unknown right now) in B (that is possible because M_i queries $2^{n_i} - 1$ strings at maximum)

Exercise 2.6.4. Show that there is a string $x \in \{0, 1\}^{n_i}$ at the end of the i -th iteration for which M_i^B does not decide $x \in U_B$ in $2^{n_i} - 1$.

Thus if $U_B \in P^B$ then pick a large enough j s.t. M_j^B decides U_B in polynomial time. This contradicts the definition of B . So $U_B \notin P^B$ while $U_B \in NP^B$ which implies that $P^B \neq NP^B$. \square

2.7 More on space complexity

Recall that $NP \subseteq PSPACE \subseteq EXP$ and we now ask the question if any of this inclusions is strict.

Definition 2.7.1. For a function $f : \mathbb{N} \rightarrow \mathbb{N}$ define

$$\text{NSpace}(f(n)) := \{L \subseteq \{0, 1\}^* \mid \exists \text{ a non-deterministic turing machine deciding } L \text{ in } O(f(n)) \text{ space}\}$$

and

$$NPSPACE := \bigcup_{c \in \mathbb{N}} \text{NSpace}(n^c)$$

Definition 2.7.2.

$$L := \text{Space}(\log(n))$$

$$NL := \text{NSpace}(\log(n))$$

(of course we mean the work-tape)

If your working-space is $\log(n)$ the number of distinct configurations is just $2^{\log(n)}$ so $L \subseteq P$.

Example 2.7.3.

$$MULT = \{(m, n, mn) \mid m, n \in \mathbb{Z}\} \in L$$

We will see that

$$L \subseteq NL \subseteq P$$

Exercise 2.7.4. Show that:

- a) $\text{Dtime}(f(n)) \subseteq \text{Space}(f(n)) \subseteq \text{NSpace}(f(n)) \subseteq \text{Dtime}(2^{O(f(n))})$
- b) $\text{NP} \subseteq \text{PSPACE}$

2.8 PSPACE-completeness

Definition 2.8.1. B is PSPACE-complete if $B \in \text{PSPACE}$ & $\forall A \in \text{PSPACE} : A \leq_P B$.

Definition 2.8.2.

$TQBF := \{y = Q_1x_1 \cdots Q_nx_n \mid Q_1, \dots, Q_n \in \{\forall, \exists\}, \phi \text{ is a boolean formula s.t. } y \text{ is true}\}$

Example 2.8.3. for a Quantified Boolean Formula $\forall x_1 \exists x_2 \forall x_3 : \phi(x_1, x_2, x_3)$ where ϕ is a boolean formula and $x_1, x_2, x_3 \in \{0, 1\}$

Lemma 2.8.4.

$$TQBF \in \text{PSPACE}$$

Proof. Let $\psi := Q_1x_1 \cdots Q_nx_n \phi(x_1, \dots, x_n)$ be the input QBF with $|\phi| =: m$ where ϕ is given in a format where it can be evaluated in $O(m)$ time. We give the following recursive algorithm to check whether ψ is true: Define $q = \vee$ if $Q_1 = \exists$ and $q = \&$ if $Q_1 = \forall$. Then ψ is true iff

$$Q_2x_2 \cdots Q_nx_n \phi(0, x_2, \dots, x_n) q Q_2x_2 \cdots Q_nx_n \phi(1, x_2, \dots, x_n)$$

Now let $s_{n,m}$ be the space used by this algorithm, then

$$\begin{aligned} s_{n,m} &= s_{n-1,m} + O(n+m) \\ \Rightarrow s_{n,m} &= O(n(m+n)) \\ \Rightarrow TQBF &\in \text{Space}(n^2) \subset \text{PSPACE} \end{aligned}$$

□

Exercise 2.8.5. Show that $s_{n,m}$ can be made $O(n+m)$.

Lemma 2.8.6.

$$\forall A \in \text{PSPACE} : A \leq_P TQBF$$

Proof. Say let M be a turing machine deciding A in space $s(n)$ (which is a polynomial in n). We will construct a QBF $\psi_{M,x}$ of size $(s(n))^2$ whose truth depends on M accepting x . By the proof of the hardness of SAT we have a formula $\phi_{M,x}(c, c')$ that is true iff $c \mapsto c'$ is a valid transition step and it is of size $O(|c| + |c'|) = O(s(n))$. M will take $2^{ds(n)}$ configuration steps to accept x with $n = |x|$, because $2^{ds(n)}$ is the number of distinct configurations of M on x . Let $\psi_i(c, c')$ be a formula which is true iff \exists at most 2^i steps from $c \mapsto c'$. Then $\psi_{M,x} = \psi_{ds(n)}(c_{start}, c_{end})$ & $\psi_i(c, c') = \exists c'' (\psi_{i-1}(c, c'') \& \psi_{i-1}(c'', c'))$. We need to improve the recurrence:

$$\begin{aligned} \psi_i(c, c') &= \exists c'' (\psi_{i-1}(c, c'') \& \psi_{i-1}(c'', c')) \\ &= \exists c'' \forall D_1, D_2 ((D_1 = c \& D_2 = c'') \vee (D_1 = c'' \& D_2 = c)) \Rightarrow \phi_{i-1}(D_1, D_2) \end{aligned}$$

Remark 2.8.7. Remember that

$$\begin{aligned} A \Rightarrow B &\equiv \neg A \vee B \\ \neg(A \vee B) &\equiv \neg A \ \& \ \neg B \\ A \vee (\exists x : B) &\equiv \exists x : (A \vee B) \text{ if } A \text{ is free of } x \end{aligned}$$

$\Rightarrow \psi_{ds(n)}(c, c')$ is now a QBF of size $O(s(n)) \cdot ds(n) = O((s(n))^2)$. Observe that $x \in A$ iff $\psi_{ds(n)}(c_{start,x}, c_{stop,x})$ is true which implies that $A \leq_P TQBF$. \square

Theorem 2.8.8. *TQBF is PSPACE-complete.*

Proof. 2.8.4 and 2.8.6. \square

Theorem 2.8.9. (Savitch [1970])

$$NSpace(s(n)) \subseteq Space((s(n))^2) \quad s(n) \in \Omega(\log(n))$$

Proof. Let M be a nondeterministic turing machine deciding A in $Space(cs(n))$. Then by 2.8.6 for all possible $x \in \{0, 1\}^*$: $\psi_{M,x} = \psi_{ds(n)}(c_{start,x}, c_{end,x})$ is of size $O((s(n))^2)$. Using 2.8.4 check whether the QBF $\psi_{M,x}$ is true or not, in space $O((s(n))^2)$. So $x \in A$ can be checked in $Space((s(n))^2)$. \square

Corrolar 2.8.10.

$$NPSPACE = PSPACE$$

2.9 NL-completeness

We need a notion of reductions weaker than P (as $NL \subseteq P$):

Definition 2.9.1. • We call $f : \{0, 1\}^* \rightarrow \{0, 1\}^*$ implicitly L-computable if:

$$L_f := \{ \langle x, i \rangle \mid (f(x))_i = 1 \} \in L$$

(here $(f(x))_i$ means the i -th bit of $f(x)$)

$$L'_f := \{ \langle x, i \rangle \mid i \leq |f(x)| \} \in L$$

- We say $A \leq_L B$ if \exists an implicitly L-computable f s.t. $\forall x \in \{0, 1\}^*, x \in A \Leftrightarrow f(x) \in B$.
- B is NL-complete if $B \in NL$ & $\forall A \in NL : A \leq_L B$.

Exercise 2.9.2. a) $A \leq_L B \leq_L C \Rightarrow A \leq_L C$

b) $A \leq_L B$ & $B \in L \Rightarrow A \in L$

c) If B is NL-hard & $B \in L \Rightarrow NL = L$

Definition 2.9.3.

$$\begin{aligned} Path := \{ (G, s, t) \mid & G \text{ directed graph, } s, t \in V(G) \\ & \text{s.t. there is a directed path from } s \text{ to } t \} \end{aligned}$$

Lemma 2.9.4.

$$Path \in N$$

Proof. Let G be a directed graph with vertices s and t . Define a non-deterministic turing machine M s.t. it is always at some vertex and a transition step just goes to one of the many possible neighbours.

Exercise 2.9.5. *add the implementation details to this proof to finish it.*

As each vertex can be uniquely referred in $\log(n)$ bits, M can be shown to be using $O(\log(n))$ space. \square

Lemma 2.9.6.

$$\forall A \in NL : A \leq_L Path$$

Proof. Let M decide A . For an $x \in A$ construct a graph G where the vertices are all configurations of M , the edges are (c, c') where $c \mapsto c'$ is a valid step of M and $s = c_{start,x}, t = c_{end,x}$

Exercise 2.9.7. *Show that this is a L-reduction.*

\square

Theorem 2.9.8. *Path is NL-complete.*

Proof. 2.9.4 and 2.9.6. \square

2.10 The Polynomial Hierarchy

We will define an infinite family of complexity-classes, the Polynomial Hierarchy PH , which will basically consist of $NP, NP^{NP}, NP^{NP^{NP}}, \dots$, will be a generalization of NP and $coNP$ and tries to divide NP from $PSPACE$:

$$NP \subseteq PH \subseteq PSPACE$$

Definition 2.10.1.

$$\begin{aligned} MinDNF := & \{ \phi \mid \phi \text{ is a DNF formula not equivalent to any smaller DNF} \} \\ & \{ \phi \mid \forall \text{ DNF } \psi, |\psi| < |\phi|, \exists s, \psi(s) \neq \phi(s) \} \end{aligned}$$

This problem does not seem to be in NP (because of \exists) and $coNP$ (because of \forall), but it is in $PSPACE$. So it's motivating the following definition of a complexity class:

Definition 2.10.2. *A language $L \in \Pi_2^P$ iff there is polynomial-time turing-machine M and a constant $C > 0$ s.t. for any string $x \in \{0,1\}^*$: $x \in L \Leftrightarrow \forall u_1 \in \{0,1\}^{|x|^C}, \exists u_2 \in \{0,1\}^{|x|^C}, M(x, u_1, u_2) = 1$.*

Remark 2.10.3. *If you replace \forall by \exists the definition yields the definition of NP and if you replace \exists by \forall the definition of $coNP$. If you exchange \exists and \forall it is unknown which complexity class we will get (since it is not known if $NP \neq coNP$).*

Exercise 2.10.4. a) $MinDNF \in \Pi_2^P$

b) $NP, coNP \subseteq \Pi_2^P \subseteq PSPACE$

Definition 2.10.5. A language $L \in \Sigma_2^P$ iff there is a polynomial-time turing-machine M and a constant $c > 0$ s.t. $\forall x \in \{0, 1\}^* : x \in L \Leftrightarrow \exists u_1 \in \{0, 1\}^{|x|^c}, \forall u_2 \in \{0, 1\}^{|x|^c}, M(x, u_1, u_2) = 1$

Exercise 2.10.6. a) $NP, coNP \subseteq \Sigma_2^P \subseteq PSPACE$

$$b) \Sigma_2^P = co\Pi_2^P, \Pi_2^P = co\Sigma_2^P$$

$$c) NP, coNP \subseteq \Sigma_2^P \cap \Pi_2^P$$

Now we define Σ_i^P and Π_i^P by alternating the quantifiers \forall and \exists for $(i-1)$ times:

Definition 2.10.7. • For $i \geq 1$ a language $L \in \Sigma_i^P$ iff there is a polynomial-time turing-machine M and a constant $c > 0$ s.t. $\forall x \in \{0, 1\}^*, x \in L \Leftrightarrow \exists u_1 \in \{0, 1\}^{|x|^c}, \forall u_2 \in \{0, 1\}^{|x|^c}, \dots, Q_i u_i, M(x, u_1, \dots, u_i) = 1$ where $Q_i \in \{\forall, \exists\}$.

• Define Π_i^P analog.

$$\bullet \Sigma_0^P := \Pi_0^P := P$$

$$\bullet PH := \bigcup_{i \geq 0} \Sigma_i^P$$

Exercise 2.10.8. a) $\Sigma_1^P = NP, \Pi_1^P = coNP$

$$b) \forall i \geq 0 : \Sigma_i^P \subseteq \Sigma_{i+1}^P \text{ \& } \Pi_i^P \subseteq \Pi_{i+1}^P$$

$$c) \forall i \geq 0 : \Sigma_i^P = co\Pi_i^P$$

$$d) \forall i \geq 0 : \Pi_i^P \subseteq \Sigma_{i+1}^P \text{ \& } \Sigma_i^P \subseteq \Pi_{i+1}^P$$

$$e) \forall i \geq 0 : \Sigma_i^P, \Pi_i^P \subseteq \Sigma_{i+1}^P \cap \Pi_{i+1}^P$$

$$f) PH = \bigcup_{i \geq 0} \Pi_i^P$$

$$g) PH \subseteq PSPACE$$

It is open if $\exists i \geq 0$ s.t.

$$\Sigma_i^P \neq \Sigma_{i+1}^P$$

Even for $i = 0$ it is very hard: $P = \Sigma_0^P \neq \Sigma_1^P = NP$. Just like we believe $P \neq NP \neq coNP$, we also believe the above.

Definition 2.10.9. If PH turns out to be equal to Σ_i^P for a constant i then we say that PH collapses to the i -th level. The PH conjecture is: PH does not collapse.

The following results follow by the PH -conjecture:

Theorem 2.10.10. $\exists i \geq 1 : \Sigma_i^P = \Pi_i^P \Rightarrow PH = \Sigma_i^P$

Proof. $L \in \Sigma_{i+1}^P$ iff there is a polynomial-time turing-machine M and a constant $c > 0$ s.t. $x \in L$ iff $\exists u_1 \forall u_2 \dots Q_{i+1} u_{i+1} : M(x, u_1, \dots, u_{i+1}) = 1$ (1). Now define a related language

$$L' := \left\{ (y, z) \mid \forall u_2 \in \{0, 1\}^{|y|^c} \exists u_3 \dots Q_{i+1} u_{i+1} : M(y, z, u_2, \dots, u_{i+1}) \right\}$$

clearly: $L' \in \Pi_i^P = \Sigma_i^P \Rightarrow \forall (y, z), (y, z) \in L'$ iff $\exists v_1 \forall v_2 \dots Q_i v_i : M'(y, z, v_1, \dots, v_i) = 1$ (2). Now (1) can be rewritten as:

$$x \in L \Leftrightarrow \exists u_1, (x, u_1) \in L'$$

. Which by (2) gives iff $\exists u_1 \exists v_1 \exists v_2 \forall v_2 \dots Q_i v_i M'(x, u_1, v_1, \dots, v_i) = 1$. $L \in \Sigma_i^P \Rightarrow \Sigma_{i+1}^P = \Sigma_i^P \Rightarrow \Pi_{i+1}^P = \Pi_i^P$ (by applying $co-$ on both sides). so $\Sigma_{i+1}^P = \Sigma_i^P = \Pi_i^P = \Pi_{i+1}^P$. Now we can repeat the argument again and again. \square

Corrolar 2.10.11.

$$NP = coNP \Rightarrow PH = NP$$

Theorem 2.10.12.

$$\exists i \geq 0 : \Sigma_i^P = \Sigma_{i+1}^P \Rightarrow PH = \Sigma_i^P$$

Proof. Applying $co-$ to both sides of $\Sigma_i^P = \Sigma_{i+1}^P$ gives $\Pi_i^P = \Pi_{i+1}^P$. As $\Pi_i^P \subseteq \Sigma_{i+1}^P$ & $\Sigma_i^P \subseteq \Pi_{i+1}^P$ we get $\Sigma_{i+1}^P = \Sigma_i^P = \Pi_i^P = \Pi_{i+1}^P$. Applying 2.10.10 on $\Sigma_{i+1}^P = \Pi_{i+1}^P$ we get $PH = \Sigma_{i+1}^P = \Sigma_i^P$. \square

Corrolar 2.10.13.

$$P = NP \Rightarrow PH = P$$

Suppose A is PH -complete then $A \in \Sigma_i^P$ for some $i \geq 0$. Which implies that $PH = \Sigma_i^P$. Thus the PH -conjecture implies that A cannot exist. And as a

Corrolar 2.10.14. PH -cojecture $\Rightarrow PH \not\subseteq PSPACE$.

2.11 Σ_i^P -complete problems

Nevertheless there is no PH -complete, we can define Σ_i^P -complete problems for all constants $i \in \mathbb{N}$:

Definition 2.11.1. For $i \geq 1$, define

$$\begin{aligned} \Sigma_i SAT := \{ & \phi(u_1, \dots, u_i) \mid \phi(x_1, \dots, x_n) \\ & \text{is a boolean formular with a partition of} \\ & x_1, \dots, x_n \text{ into } u_1, \dots, u_i \text{ s.t.} \\ & \exists u_1 \forall u_2 \dots Q_i u_i [\phi(u_1, \dots, u_i) = 1]\} \end{aligned}$$

For exmplate u_1 could be $x_1 x_2 x_3$ and $u_2 = x_2 x_6$ etc.

Theorem 2.11.2. $\Sigma_i SAT$ is Σ_i^P -complete, for every $i \in \mathbb{N}^{\geq 1}$.

Proof. First we see by the definition of $\Sigma_i SAT$ that it is contained in Σ_i^P , you can take a turing machine that evaluates $\phi(x_1, \dots, x_n)$ for a given valuation u_1, \dots, u_i . $\phi \in \Sigma_i SAT$ iff $\exists u_1 \forall u_2 \dots Q_i u_i [M(\phi, u_1, \dots, u_i) = 1]$. Now we will show that $\Sigma_i SAT$ is Σ_i^P -hard: Any $L \in \Sigma_i^P$ has a corresponding polynomial-time turing-machine M by definition. The computation of M on (x, y_1, \dots, y_i) can be captured in a boolean formula $\phi_{x, y_1, \dots, y_i}$ (as in the proof of NP -hardness of SAT). Thus $L \leq_P \Sigma_i SAT$. \square

Definition 2.11.3. $\Pi_i SAT :=$ flip the quantifiers in the definition of $\Sigma_i SAT$.

Theorem 2.11.4. $\Pi_i SAT$ is Π_i^P -complete.

2.12 PH via oracle machines

Definition 2.12.1. For complexity classes C_1 and C_2 , we define

$$C_1^{C_2} := \bigcup_{L \in C_2} C_1^L$$

For e.g. $NP^{NP} = NP^{SAT}$. We will now see that $\Sigma_2^P = NP^{NP}$, i.e. a non-deterministic turing machine using SAT as an oracle can solve Σ_2^P in polynomial time. Note that $P^P = P$ but it is an open question whether $NP^{NP} = NP$ or not.

Theorem 2.12.2.

$$\forall i \geq 2 : \Sigma_i^P = NP^{\Sigma_{i-1}^P}$$

Proof. We will demonstrate the proof-idea by proving that $\Sigma_2^P = NP^{NP}$ which will naturally generalize to every i .

Suppose that $L \in \Sigma_2^P$ then there exists a polynomial-time turing-machine and a constant $c > 0$ s.t.

$$\forall x \in \{0, 1\}^* : x \in L \Leftrightarrow \exists u_1 \in \{0, 1\}^{|x|^c} \forall u_2 [M(x, u_1, u_2) = 1]$$

The associated language $L' := \{(y, z) \mid \forall u_2 \in \{0, 1\}^{|y|^c}, M(y, z, u_2) = 1\}$. Then we can rewrite the above to $x \in L$ iff $\exists u_1(x, u_1) \in L'$. As $L' \in coNP \subseteq P^{NP}$ and we get $L \in NP^{NP}$. So $\Sigma_2^P \subseteq NP^{NP}$.

Now suppose that $L \in NP^{NP} = NP^{SAT}$. Say L is decided in polynomial-time by a non-deterministic turing machine N using SAT as an oracle and let $\bar{c} = (c_1, \dots, c_m) \in \{0, 1\}^m$ be the transition-choices of N on x . It queries the oracle on formulas: $\phi_{\bar{c}, 1}, \dots, \phi_{\bar{c}, k}$ and got answers $\bar{a} = (a_1, \dots, a_k) \in \{0, 1\}^k$. Then

$$\begin{aligned} x \in L &\Leftrightarrow \exists \bar{c}, \bar{a} : (N \text{ accepts } x \text{ on the path } \bar{c}) \ \& \ (\bar{a} \text{ are correct answers}) \\ &\Leftrightarrow \exists \bar{c}, \bar{a}, u_1, \dots, u_k \forall v_1, \dots, v_k : (N \text{ accepts } x \text{ on the path } \bar{c}) \ \& \\ &\quad (\forall 1 \leq i \leq k, (a_i = 0 \Rightarrow \phi_{\bar{c}, i}(v_i) = 0) \ \& \ (a_i = 1 \Rightarrow \phi_{\bar{c}, i}(u_i) = 1)) \end{aligned}$$

Exercise 2.12.3. Proof the last equivalence above.

So $L \in \Sigma_2^P$ and $NP^{NP} \subseteq \Sigma_2^P$. Thus $\Sigma_2^P = NP^{NP}$. □

Exercise 2.12.4. complete the proof for $i > 2$ by showing that $\Sigma_i^P = NP^{\Sigma_{i-1}^P SAT}$.

Corrolar 2.12.5.

$$\Sigma_2^P = NP^{NP}, \Sigma_3^P = NP^{NP^{NP}}, \dots$$

We have the following situation:

$$P \subseteq NP \subseteq NP^{NP} \subseteq \dots \subseteq PH \subseteq PSPACE$$

And it is unknown if the last containment is sharp or not, but we will see counting problems which are in between.

2.13 Between PH and $PSPACE$

Definition 2.13.1. Define a function

$$\begin{aligned} \#SAT : \{ \phi \mid \phi \text{ is a boolean formula} \} &\rightarrow \mathbb{N} \\ \phi &\mapsto \text{number of satisfying assignments of } \phi \end{aligned}$$

It is an open question if $\#SAT$ is efficiently computable. It can be computed in polynomial space.

Definition 2.13.2.

$$FP := \{ f : \{0,1\}^* \rightarrow \{0,1\}^* \mid f \text{ is computable by a polynomial-time turing-machine } M_f \}$$

It is open if $\#SAT \in FP$ but if it is not, then $P = NP$.

Definition 2.13.3. A function $f : \{0,1\}^* \rightarrow \mathbb{N}$ is in $\#P$ if there exists a polynomial-time turing-machine M and $c \in \mathbb{R}^{>0}$ s.t. for all $x \in \{0,1\}^*$: $f(x) = |\{y \in \{0,1\}^{|x|^c} \mid M(x,y) = 1\}|$. In other words $\#P$ is the collection of functions that count the number of accepting paths of a polynomial-time non-deterministic turing-machine .

Exercise 2.13.4. a) $\#SAT \in \#P$

b) $NP \subseteq P^{\#SAT} \subseteq P^{\#P}$

c) $P^{\#P} \subseteq EXP, P^{\#P} \subseteq PSPACE$

d) $FP \subseteq \#P$

e) “Counting points on a variety over finite fields” $\in \#P$

It is open to show that $FP \not\subseteq \#P$ (arithmetic version of $P \neq NP$)

Remark 2.13.5. $\#P$ has an analogous decision problems class: PP .

Definition 2.13.6. A language $L \in PP$ if there exists a polynomial-time turing-machine M and $c \in \mathbb{R}^{>0}$ s.t. for all $x \in \{0,1\}^*$:

$$x \in L \Leftrightarrow |\{y \in \{0,1\}^{|x|^c} \mid M(x,y) = 1\}| \geq \frac{1}{2} 2^{|x|^c}$$

In other words PP corresponds to t_0 computing most-significant-bit of $\#P$ -function.

Exercise 2.13.7. a) $\#SAT \in FP^{PP}$

b) $P^{\#P} = P^{PP}$

2.14 $\#P$ -completeness

Definition 2.14.1. We call a function $f : \{0,1\}^{\mathbb{N}}$ is $\#P$ -complete if $f \in \#P$ and $\#P \subset FP^f$ (here FP^f is the set of functions computable by a polynomial-time oracle turing-machine M using f as an oracle, this is called “turing reduction”, in contrast to the karp-reduction).

Exercise 2.14.2. If f is #P-complete and $f \in FP$ then $\#P = FP$.

Theorem 2.14.3. #SAT is #P-complete

Proof. Recall that the computation of a polynomial-time non-deterministic turing-machine M can be encoded in a boolean formula. Thus, for any $g \in \#P$ with $g(x)$ equals the number of acceptings paths of M on input x . We get a boolean formula $\phi_{M,x}$ s.t. the number of satisfying assignments of $\phi_{M,x} = g(x)$. So $g \in FP^{\#SAT}$. Since g was arbitrary: $\#P \subseteq FP^{\#SAT}$. \square

2.15 PERMANENT and #P

Definition 2.15.1. Let F be a field, for $A = (A_{ij})_{1 \leq i, j \leq n} \in \mathbb{F}^{n \times n}$ the permanent is defined as:

$$\text{per}(A) := \sum_{\sigma \in S_n} A_{1, \sigma(1)} \cdot \dots \cdot a_{n, \sigma(n)}$$

here S_n is the group of $n!$ permutations of $\{1, \dots, n\}$. So per is defined like det but without any signs.

We will now show, that per is #P-complete:

Lemma 2.15.2. per for 0-1-matrices $\in \#P$.

Proof. Let $A \in \{0, 1\}^{n \times n}$, then $\text{per}(A) = |\{\sigma \in S_n \mid \prod_{i=1}^n a_{i, \sigma(i)} = 1\}|$. Define a non-deterministic turing-machine M that on input A , guesses $\sigma \in S_n$ and accpets A iff $\prod_{i=1}^n A_{i, \sigma(i)} = 1$. Hence $\text{per}(A) =$ number of accepting paths of M on input A it follows that per for 0-1-matrices $\in \#P$.

Exercise 2.15.3. Use the above idea to show: per for matrices over a finite field $\in \#P$.

This shows that $\text{per} \in FP^{\#SAT}$. \square

Definition 2.15.4. Given $A \in \mathbb{F}^{n \times n}$ and view it as the adjacency matrix of a weightes digraph on n vertices (with weight-function w and which we will also call A). Then a cycle cover C of the graph A is a subgraph of A having the n vertices and each vertex v has $\delta^+(v) = \delta^-(v) = 1$ (in-degree and out-degree are one). Thus a cycle cover C of A is basically a disjoint union of cycles covering all vertices of A . The weight of C is defined as

$$\text{wt}(C) := \prod_{v \in E(C)} w(v)$$

Exercise 2.15.5. a) $A_{1, \sigma(1)} \cdot \dots \cdot A_{n, \sigma(n)}$ equals the weight of the cycle cover in the graph A corresponding to the cycle-decomposition of permutation σ .

b)

$$\text{per}(A) = \sum_{C \text{ cycle-cover of } A} \text{wt}(C)$$

Lemma 2.15.6. per for 0-1-matrices is #P-hard.

Proof. We will relate #3SAT with per. Let ϕ be a CNF formula with m clauses (each with exactly 3 literals) F_1, \dots, F_m and n , named x_1, \dots, x_n , variables. Then we will construct a graph A with sum of its weighted cycle-covers kind of “equals to” the number of satisfying assignments of ϕ :

variables: $x_1, \dots, x_n \mapsto$ variable gadgets (graphs) V_1, \dots, V_n

clauses: $F_1, \dots, F_m \mapsto$ clause gadgets C_1, \dots, C_m

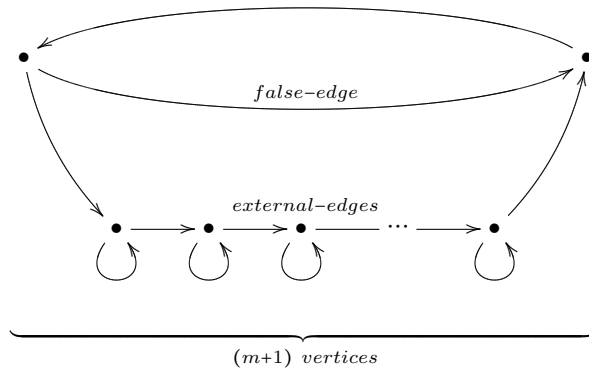
occurrence: x_i / \bar{x}_i occurs in $F_j \mapsto XOR_{i,j}$ -gadgets

These $n + m + 3m$ gadgets together will form the graph A s.t.

$$\sum_{C \text{ cycle-cover}} wt(C) = 4^{3m} \text{ number of satisfying assignments of } \phi$$

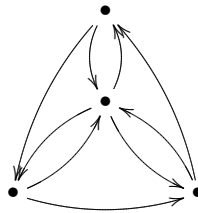
Unlabeled edges are understood to have weight 1 in the following.

Each variable x_i is converted to a graph gadget V_i :



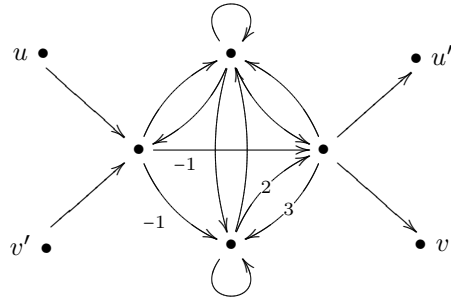
the edges between the bottom $m + 1$ vertices are called external. The cycle cover of V_i using the external edges corresponds to $x_i = T$ and the one using the upper edge (called false edge) corresponds to $x_i = F$.

Each clause F_j is converted to a graph gadget C_j :



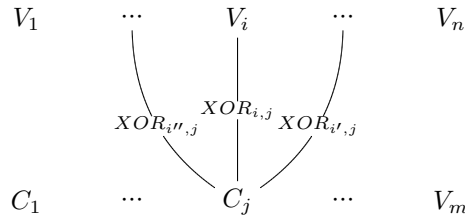
The 3 outer edges (called external again) correspond to the 3 literals of F_j . This graph has 3 cycle-covers each of weight 1 and corresponding to a dropped outer (external) edge. The dropped external edge specifies the literal in F_j set to “True”.

If a variable x_i (not it’s complement \bar{x}_i) appears in F_j then we connect the j -th external edge (u, u') of V_i to the x_i -external edge of C_i by a graph gadget $XOR_{i,j}$:

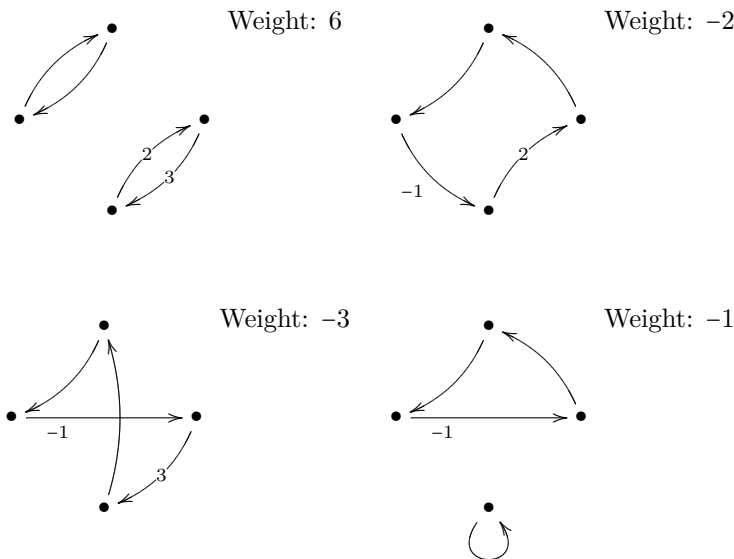


Finally if \bar{x}_i is in F_j then we connect the false edge (u, u') of V_i to the x_i external edge (v, v') of C_j by $XOR_{i,j}$.

We call the resulting graph A' and we can see by the following figure that the number of edges is quadratic in n and m .

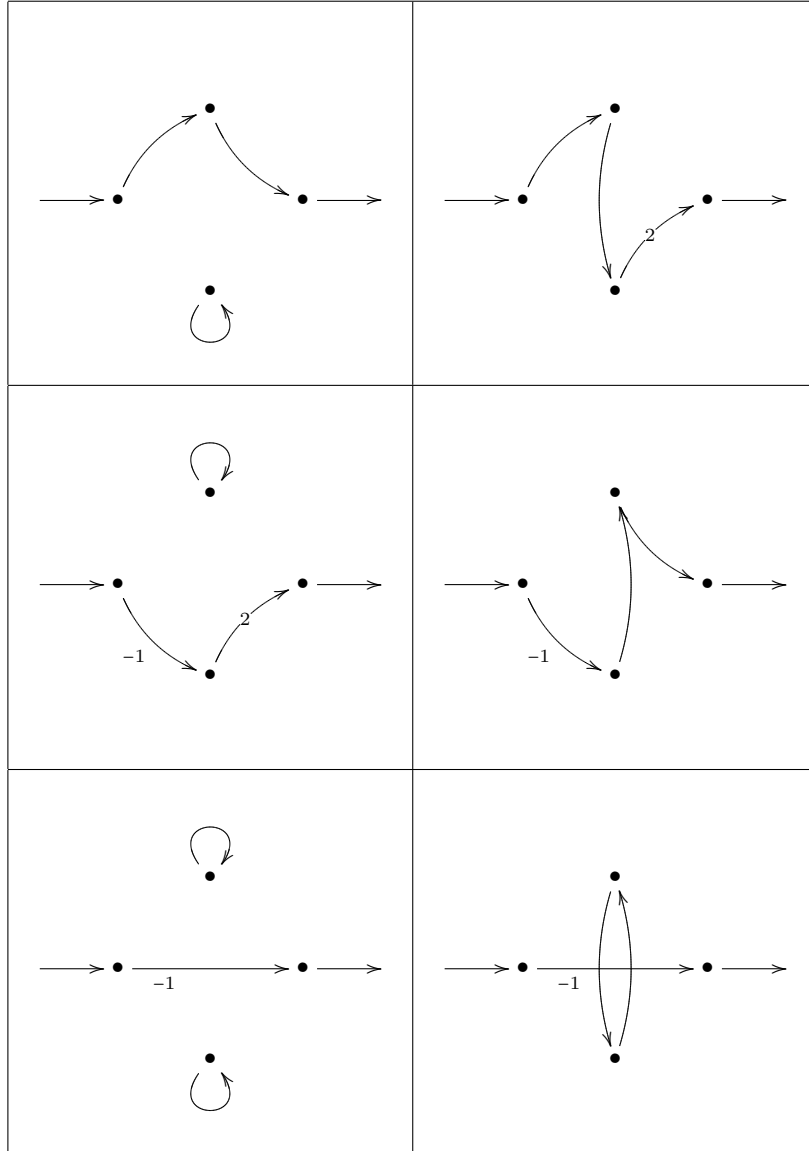


Now observe that the cycle-covers of $XOR_{i,j} - \{u, v, u', v'\}$ sum up to 0:



Thus the cycle-covers of A' that “matter” in $\text{per}(A')$ are the ones for which $XOR_{i,j}$ contributes to exactly one of the paths (u, u') or (v, v') in the cycle-cover (hence the name XOR). Consider such a cycle-cover \mathcal{C} of A' : For every C_j there will be an external edge not appearing in \mathcal{C} say x_i . $XOR_{i,j}$ ensures that the j -th external edge in V_i appears in \mathcal{C} . Thus the “True” cycle of V_i appears in \mathcal{C} and we can take $x_i = T$. So \mathcal{C} induces a satisfying assignment of ϕ .

The weighted sum of paths from u to u' in $XOR_{i,j}$ is -2 :

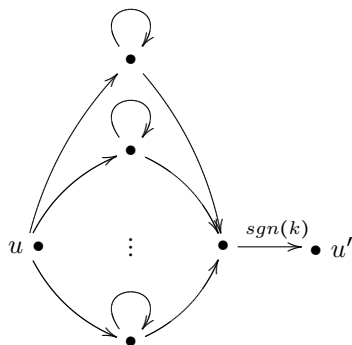


Thus, for a satisfying assignment s of ϕ :

$$\sum_{\mathcal{C} \text{ is a cycle cover of } A' \text{ corresponding to } s} wt(\mathcal{C}) = (-2)^{3m}$$

$$\Rightarrow \text{per}(A') = (-2)^{3m} \#(\phi).$$

The final question is how to reduce A' to a 0-1-matrix A'' : First reduce it to a $\{-1, 0, 1\}$ -matrix by replacing every k -weighted edge (u, u') with $k \in \mathbb{Z} - \{0, 1\}$ by the following graph (there are k vertices on top of each other):



Say $A'' \in \{-1, 0, 1\}^{n \times n}$ then $\text{per}(A'') \in [-(n!), n!] \cap \mathbb{Z}$. So use $N := 2^{n^2}$, work (mod N) and replace -1 by $(N-1)$ in the graph. So we get a $\{0, 1, N-1\}$ -matrix A s.t.

$$\text{per}(A) \equiv (-2)^{3m} \#(\phi) \pmod{N}$$

Exercise 2.15.7. Convert a $\{0, 1, N-1\}$ -matrix to a $\{0, 1\}$ -matrix with the same permanent.

$$\Rightarrow \#SAT \in FP^{\text{permanent of 0-1-matrix}}$$

□

Theorem 2.15.8. (Valiant 1979) PERMANENT for 0-1-matrix is #P-complete.

Theorem 2.15.9. (Toda, 1991)

$$PH \subseteq P^{\#P}$$

First remember that $PH = \cup_{i=0} \Sigma_i^P$ and $P^{\#P} = P^{\#SAT}$

We will use some probabilistic methods during this proof.

Idea: We give a new type of reduction (i.e. random reduction) from any Σ_i^P to a new class $\oplus P$ (parity- p). Surprisingly, this “randomized reduction” will help in proving a deterministic statement.

Definition 2.15.10. A language $L \in \oplus P$ (called *parity-P*) if there is a polynomial-time non-deterministic turing-machine M s.t. for all $x \in \{0, 1\}^*$: $x \in L$ iff $\#(\text{accepting paths of } M \text{ on } x)$ is odd.

Definition 2.15.11.

$$\oplus SAT := \{ \phi \mid \phi \text{ is a boolean formula that has an odd number of satisfying assignments} \}$$

Exercise 2.15.12. $\oplus SAT$ is $\oplus P$ -complete.

Open question: $\oplus P = P \Rightarrow NP = P$

The following theorem gives an evidence towards that:

Theorem 2.15.13. (Valiant-Vazisani) *There is a polynomial-time turing-machine A s.t. for any boolean formula ϕ on n variables:*

$$\begin{aligned}\phi \in SAT &\Rightarrow \Pr_r [A(r, \phi) \in \oplus SAT] \geq \frac{1}{8n} \\ \phi \notin SAT &\Rightarrow \Pr_r [A(r, \phi) \in \oplus SAT] = 0\end{aligned}$$

Remark 2.15.14. *This we state as “SAT randomly reduces to $\oplus SAT$ ”*

Idea: Given a CNF-boolean formula ϕ we want to transform ϕ into a fomula ϕ' that has 0 or 1 satisfying assignments depending on whether ϕ is unsatisfiable respectively. To describe this transformation we need the following lemma “hash functions”:

Lemma 2.15.15. *For a matrix $B \in \{0, 1\}^{k \times n}$ and a vector $b \in \{0, 1\}^k$, consider the transformation:*

$$\begin{aligned}h_{B,b} : \{0, 1\}^n &\rightarrow \{0, 1\}^k \\ x &\mapsto (Bx + b) \pmod{2}\end{aligned}$$

- a) *For a fixed $x \in \{0, 1\}^n : \Pr_{B,b} [h_{B,b}(x) = 0^k] = 2^{-k}$*
- b) *For a fixed $x \neq x' \in \{0, 1\}^n : \Pr_{B,b} [h_{B,b}(x) = h_{B,b}(x') = 0^k] = 2^{-k}$*
- c) *Let $S \subseteq \{0, 1\}^*$ s.t. $2^{k-2} \leq |S| \leq 2^{k-1}$.*

Then

$$\Pr_{B,b} [\#\{x \in S \mid h_{B,b}(x) = 0^k\} = 1] \geq \frac{1}{8}$$

Let us first use the lemma to proof the theorem:

Proof. Description of A : Given a CNF ϕ on n variables randomly pick $k \in \{2, \dots, n+1\}$, $B \in \{0, 1\}^{k \times n}$ and $b \in \{0, 1\}^k$. Output the boolean formula:

$$\psi(x) := \phi(x) \& [h_{B,b}(x) = 0^k]$$

The last term is expressed as a boolean formula.

Note that: If ϕ is unsatisfiable then ψ has 0, hence even, satisfying assignments. If ϕ is satisfiable then, let $S := \{x \in \{0, 1\}^n \mid \phi(x) = 1\}$ with probability $\geq \frac{1}{n}$ we would have chosen k s.t. $2^{k-2} \leq \#S \leq 2^{k-1}$.

Conditioned on this, with probability $\geq \frac{1}{8}$ we have chosen (B, b) s.t.

$$\#\{x \in S \mid h_{B,b}(x) = 0^k\} = 1$$

Thus with probability $\geq \frac{1}{8n}$ we would have chosen (k, B, b) s.t.

$$\#(\text{satisfying assignmen of } \psi) = 1$$

hence odd. □

Proof. Let us now proof 2.15.15.

- a) $h_{B,b}(x) = 0^k$, $Bx = -b \pmod{2}$. If we first pick B then the probability of picking $b \equiv (-Bx) \pmod{2}$ is $\frac{1}{2^k}$ so $\Pr_{B,b} [h_{B,b}(x) = 0^k] = 2^{-k}$

b)

$$\begin{aligned}
\Pr_{B,b}[Bx = -b \ \& \ Bx' = -b] &= \Pr_{B,b}[Bx = -b] \cdot \Pr_{B,b}[Bx' = -b \mid Bx = -b] \\
&= 2^{-k} \cdot \Pr_{B,b}[B(x' - x) = 0 \mid Bx = -b] \\
&= 2^{-k} \Pr_B[B(x' - x) = 0] = 2^{-2k}
\end{aligned}$$

c) Let N be the random variable $\#\{x \in S \mid h_{B,b}(x) = 0^k\}$. Then by inclusion-exclusion:

$$\begin{aligned}
\Pr_{B,b}[N \geq 1] &\geq \left(\sum_{x \in S} \Pr_{B,b}[h_{B,b}(x) = 0^k] \right) - \left(\sum_{x < x' \in S} \Pr_{B,b}[h_{B,b}(x) = h_{B,b}(x') = 0^k] \right) \\
&= |S| \cdot 2^{-k} - \frac{|S|}{2} \cdot 2^{-2k}
\end{aligned}$$

similarly:

$$\begin{aligned}
\Pr_{B,b}(N \geq 2) &\leq \sum_{x < x' \in S} \Pr_{B,b}[h_{B,b}(x) = h_{B,b}(x') = 0^k] \\
&= \frac{|S|}{2} \cdot 2^{-2k}
\end{aligned}$$

So

$$\begin{aligned}
\Pr_{B,b}[N = 1] &= \Pr_{B,b}[N \geq 1] - \Pr_{B,b}[N \geq 2] \\
&\geq |S|2^{-k} - \frac{|S|}{2} 2^{-2k} \\
&= |S|2^{-k} - |S|(|S| - 1)2^{-2k} \\
&\geq |S|2^{-k} - (|S|2^{-k})^2 \\
&\geq |S|2^{-k}(1 - |S|2^{-k}) \\
&\geq \frac{1}{4}(1 - \frac{1}{2}) = \frac{1}{8}
\end{aligned}$$

□

Now we will use the idea in the proof that NP randomly reduces to $\oplus P$ repeatedly to show: PH randomly reduces to $\oplus P$. We will replace \forall and \exists by a \oplus quantifier one-by-one.

Definition 2.15.16. For any boolean formula $\phi(\bar{z})$, $\psi = \oplus \bar{z} \phi(\bar{z})$ is true iff $\#$ satisfying assignments of $\phi(\bar{z})$ is odd. See this as a definition of the quantifier \oplus .

Lemma 2.15.17. Let $c \in \mathbb{N}$ be a constant. There is a deterministic polynomial time transformation A s.t. for any formula ψ starting with c alternating \forall/\exists -quantifiers:

$$\begin{aligned}
\text{If } \psi \text{ is true} &\Rightarrow \Pr_r[A(r, \psi) \in \oplus SAT] = \frac{2}{3} \\
\text{If } \psi \text{ is false} &\Rightarrow \Pr_r[A(r, \psi) \in \oplus SAT] = 0
\end{aligned}$$

Proof. Let ψ be a formula with $c' \leq c$ alternating \forall/\exists -quantifiers. As our aim is to replace them one-by-one with the \oplus -quantifier, let us assume that ψ starts with a \oplus -quantifier. We will demonstrate the proof for $\psi = \oplus z \in \{0, 1\}^l \exists x \in \{0, 1\}^n, \forall w \in \{0, 1\}^k, \phi(z, x, w)$ with a boolean formula ϕ using the $l + n + k$ variables. By the proof of 2.15.13 there exists a formula τ s.t. for a random string r (we will drop the domains of x, w and w in the following)

$$\Pr_r[\oplus x \forall w (\phi(z, x, w) \ \& \ \tau(x, r)) \text{ is true}] \geq \frac{1}{8n}$$

if $\exists x \forall w \phi(z, x, w)$ is true .

$$\Pr_r[\oplus x \forall w (\phi(z, x, w) \ \& \ \tau(x, r)) \text{ is true}] = 0$$

if $\exists x \forall w \phi(z, x, w)$ is false

So $\Pr_r [\oplus z \oplus x \forall w (\phi(z, x, w) \& \tau(x, r)) \text{ is true}] \geq \left(\frac{1}{8n}\right)^2$ if ψ is true.

So we have randomly reduced ψ to $\oplus z \oplus x \forall w (\phi(z, x, w) \& \tau(x, r))$ but the probability of success is extremely low. We improve it by first boosting equation 2.15. For any z , repeat the transformation in equation 2.15 for $t \in \mathbb{N}$ random strings r_1, \dots, r_t .

$$p := \Pr_{r_1, \dots, r_t} \left[\bigvee_{i=1}^t \oplus x \forall w \phi(z, x, w) \& \tau(x, r_i) \text{ is true} \right]$$

- if $\exists x \forall w \phi(z, x, w)$ is true then $p = 1 - \left(1 - \frac{1}{8n}\right)^t$
- if $\exists x \forall w \phi(z, x, w)$ is false then $p = 0$

Consider all $z \in \{0, 1\}^l$:

$$p := \Pr_{r_1, \dots, r_t} [\oplus z \bigvee \oplus x \forall w \phi(z, x, w) \& \tau(x, r_i) \text{ is true}]$$

Exercise 2.15.18. a) if ψ is true then $p = 1 - 2^l \left(1 - \frac{1}{8n}\right)^t$

b) if ψ is false then $p = 0$

Exercise 2.15.19. Proof that $1 - 2^l \left(1 - \frac{1}{8n}\right)^t > \frac{2}{3}$

Hint: Pick $t = 16n(l + 1)$ then something like

$$2^l \left(1 - \frac{1}{8n}\right)^t < 2^l \left(\left(1 - \frac{1}{8n}\right)^{8n} \right)^{2l} \leq 2^l \left(\frac{1}{2n}\right)^{2l} = \frac{1}{2^l}$$

happens

We have randomly reduced $\psi = \oplus z \exists x \forall w \phi(z, x, w)$ to $\psi' = \oplus z \bigvee_{i=1}^t \oplus x \forall w \phi'(z, x, w, r_i)$. How to remove \forall -operators? We develop some useful quantified boolean formula algebra (for a boolean formula F denote the number of satisfying assignments as $\#F$):

a) For boolean formulas $F(\bar{x})$ and $G(\bar{x})$ we define

$$(F + G)(\bar{x}, u) := ((u = 0) \& F(\bar{x})) \vee (u = 1 \& G(\bar{x}))$$

Observation: $\#F = \#G = \#(F + G)$

b) For boolean formula $F(\bar{x})$ and $G(\bar{y})$ define:

$$(F \cdot G)(\bar{x}, \bar{y}) := F(\bar{x}) \& G(\bar{y})$$

Observation: $\#(F \cdot G) = (\#F) \cdot (\#G)$

c) For a boolean formula $F(\bar{x})$ we define

$$(F + 1)(\bar{x}, u) := (u = 0 \& F(\bar{x})) \vee (u = 1 \& \bar{x} = 0^n)$$

Observation: $\#(F + 1) = \#F + 1$

d) $\oplus \bar{x} F_1(\bar{x}) \vee \oplus \bar{y} F_2(\bar{y}) = \oplus (\bar{x}, \bar{y}, u_1, u_2, u_3) ((F_1 + 1)(\bar{x}, u_1) \cdot (F_2 + 1)(\bar{y}, u_2) + 1)(\bar{x}, \bar{y}, u_1, u_2, u_3)$

Thus in this way we can randomly reduce $\psi = \oplus z \exists x \forall w \phi(z, x, w)$ to

$$\psi'' = \oplus z \oplus x^* \forall w \phi''(z, x^*, w)$$

Next we can remove the \forall -quantifier because:

Exercise 2.15.20.

$$\oplus \bar{x} \forall \bar{y} F(\bar{x}, \bar{y}) = \oplus \bar{x} \exists \bar{y} F(\bar{x}, \bar{y})$$

Then repeat the older steps on $\oplus z \oplus x^* \exists w \phi''$ and end up with

$$\oplus(z, x^*, w^*) \phi'''(z, x^*, y^*)$$

and because the number of quantifiers in ψ is constant we only get a polynomial blowup of ϕ''' in the size of ϕ and the probability of $\frac{2}{3}$ can be achieved. So PH randomly reduces to $\oplus P$ (with a “decent” probability of $\frac{2}{3}$). \square

As $\oplus P \subset P^{\#P}$ we already have a randomized reduction from PH to $\#P$. How to derandomize it?

For that we show a property of $\oplus P$:

Lemma 2.15.21. *Let ψ be a boolean formula and $m \in \mathbb{N}_0$ then there exists a deterministic polynomial-time transformation T s.t. $\phi := T(\psi, 1^m)$ is a boolean formula s.t.*

$$\begin{aligned} \#\psi = 1 \pmod{2} &\Rightarrow \#\phi \equiv -1 \pmod{2^{m+1}} \\ \#\psi = 0 \pmod{2} &\Rightarrow \#\phi \equiv 0 \pmod{2^{m+1}} \end{aligned}$$

Proof. We build ϕ iteratively. Let $\phi_0 := \psi$. Consider $\psi_i := 4\phi_0^3 + 3\phi_0^4$.

$$\begin{aligned} \#\phi_0 = 1 \pmod{2} &\Rightarrow \#\phi_1 = -1 \pmod{2^2} \\ \#\phi_0 = 0 \pmod{2} &\Rightarrow \#\phi_1 = 0 \pmod{2^2} \end{aligned}$$

Exercise 2.15.22. *The recurrence $\phi_{i+1} = 4\phi_i^3 + 3\phi_i^4$ gives*

$$\begin{aligned} \#\phi_0 = 1 \pmod{2} &\Rightarrow \#\phi_{i+1} = -1 \pmod{2^{2^{i+1}}} \\ \#\phi_0 = 0 \pmod{2} &\Rightarrow \#\phi_{i+1} = 0 \pmod{2^{2^{i+1}}} \end{aligned}$$

\square

Proof. (of theorem 2.15.9) Let $L \in PH$. We will show how to check $x \in$ using $\#SAT$ as an oracle. By the last two lemmas there exists a deterministic polynomial-time turing-machine M and $m = poly(|x|)$ s.t.

$$\begin{aligned} x \in L &\Rightarrow \Pr_{r \in \{0,1\}^m} [\#\text{accepting paths}(M(x, r)) \equiv -1 \pmod{2^{m+1}}] \\ x \notin L &\Rightarrow \forall r \in \{0,1\}^m \#\text{accepting paths}(M(x, r)) \equiv 0 \pmod{2^{m+1}} \end{aligned}$$

Remark 2.15.23. *M is the non-deterministic turing-machine corresponding to ϕ in the last lemma i.e. M just guesses a satisfying assignment of ϕ and then verifies it.*

Now define a polynomial-time non-deterministic turing-machine M' that on input x , guesses $r \in \{0,1\}^m$ and accepts iff M accepts (x, r) .

$$\#\text{ accepting paths of } (M'(x)) = \sum_{r \in \{0,1\}^m} \#\text{accepting paths}(M(x, r))$$

If $x \in L$ then $\#\text{accepting paths}(M'(x)) \pmod{2^{m+1}} \in [-2^m, -\frac{2}{3}2^m]$.

If $x \notin L$ then $\#\text{accepting paths}(M'(x)) \pmod{2^{m+1}}$ is 0.

Thus, computing $\#\text{accepting paths}(M'(x))$ is enough to solve L which means that $PH \subseteq P^{\#P}$. \square

2.16 Probabilistic turing machines

Now we will formalize randomized computation. Randomness has been useful in the last four decades to:

- a) proving theorems in complexity whose statements did not call for randomness
- b) develop simpler and faster algorithms for several problems in combinatorial optimization (simplex, quicksort), algebraic computation, machine learning and network routing.

Definition 2.16.1. We call M a probabilistic turing machines (PTM) if M has two transition functions δ_0 and δ_1 and in each transition step M randomly follows δ_0 or δ_1 each with probability $\frac{1}{2}$. We say that a probabilistic turing-machine M decides L if for any $x \in \{0, 1\}^*$ $x \in L \Leftrightarrow \Pr_{steps}[M \text{ accepts } x] \geq \frac{2}{3}$

Definition 2.16.2. For a function $T : \mathbb{N} \rightarrow \mathbb{N}$ a probabilistic turing-machine M decides L in time $T(n)$ if M decides L and for all $x \in \{0, 1\}^*$: M halts on x in $\leq T(|x|)$ steps regardless of its random choices.

$$\text{BPTime}(T(n)) := \{L \subseteq \{0, 1\}^* \mid \text{some probabilistic turing-machine } M \text{ decides } L \text{ in time } O(T(n))\}$$

(bounded probabilistic)

$$BPP := \bigcup_{c \in \mathbb{N}} \text{BPTime}(n^c)$$

Exercise 2.16.3. $P \subseteq BPP \subseteq PSPACE \subseteq EXP$

It is open if $P = BPP$ (but “evidence” suggests that it is) or if $BPP = NP$ (we will connect with PH collapse).

Exercise 2.16.4. (Alternative definition of BPP) $L \in BPP$ iff there is a deterministic polynomial-time turing-machine M and $c > 0$ s.t.

$$x \in L \Leftrightarrow \Pr_{r \in \{0, 1\}^{|x|^c}} [M(x, r) = 1] \geq \frac{2}{3}$$

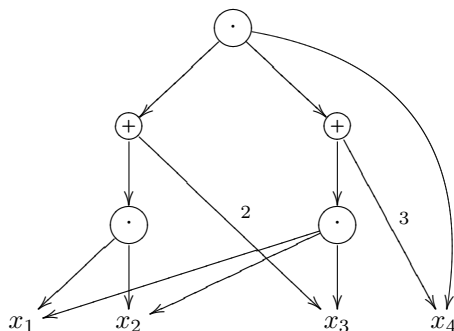
Example 2.16.5. Primality testing given $n \in \mathbb{N}$, check whether it is prime. A randomized algorithm for primality was the first famous probabilistic turing-machine. It was given by Solovay-Strassen (1970s):

- a) Pick a random $a \in (\mathbb{Z}/n\mathbb{Z})^*$
- b) Output YES iff $a^{\frac{n-1}{2}} \equiv \underbrace{\frac{a}{n}}_{\text{Jacobi-Symbol}} \pmod{n}$

Exercise 2.16.6. Prove it to be a probabilistic turing-machine (none trivial)

Today there is a deterministic polynomial-time primality test (Agrawal-Kayal-Saxena 2002).

Identity testing Given a polynomial $C \in \mathbb{F}[x_1, \dots, x_n]$ in some “compact” form. Check whether $C = 0$. $C(x_1, \dots, x_n)$ is often presented as an arithmetic circuit: The circuit for $(x_1x_2 + 2x_3)(3x_4 + 4x_1x_2x_3)x_4$ is:



The algorithm of Schwartz-Zippel (1980) is:

- Pick $(a_1, \dots, a_n) \in \mathbb{F}^n$
- Output YES iff $C(a_1, \dots, a_n) = 0$

Exercise 2.16.7. Show that this is a probabilistic turing-machine solving identity testing (none trivial)

Currently no deterministic polynomial-time algorithm is known. The corresponding language is

$$ID := \{C \mid C \text{ is a zero arithmetic statement}\}$$

BPP captures probabilistic algorithms with two-sided error, i.e. a probabilistic turing-machine M decides $L \subseteq BPP$ then $M(x)$ could be erroneous regardless of $x \in L$ or $x \notin L$.

Definition 2.16.8. (One-sided error, Monte-Carlo?) $L \in \text{Rtime}(T(n))$ if there is a probabilistic turing-machine running in time $O(T(n))$ s.t.

$$\begin{aligned} x \in L &\Rightarrow \Pr[M \text{ accepts } x] \geq \frac{2}{3} \\ x \notin L &\Rightarrow \Pr[M \text{ accepts } x] \leq 0 \end{aligned}$$

$$RP := \bigcup_{c \in \mathbb{N}} \text{Rtime}(n^c)$$

$$\text{coRP} := \{L \mid \bar{L} \in RP\}$$

Exercise 2.16.9. a) $PRIMES \in \text{coRP}$

b) $ID \in \text{coRP}$

c) $RP \subseteq BPP$ and $\text{coRP} \subseteq BPP$

d) $RP \subseteq NP$ and $\text{coRP} \subseteq \text{coNP}$

Definition 2.16.10. (Zero-sided but probabilistic error, Las Vegas?) For a probabilistic turing-machine M , $\text{time}_M(x)$ is a random variable (on the choices of transition steps). We say M has an expected running time $T(n)$ if $\text{Exp}[\text{time}_M(x)] \leq T(|x|)$.

$L \in \text{Ztime}(T(n))$ iff there is a probabilistic turing-machine M correctly deciding L in expected time $O(T(n))$.

$$\text{ZPP} := \bigcup_{c \in \mathbb{N}} \text{time}(n^c)$$

Exercise 2.16.11. $\text{ZPP} = \text{RP} \cap \text{coRP}$

Hint (for \subseteq): $L \in \text{ZPP}$, a probabilistic turing-machine M solves L in expected time $T(n)$. Run M for $2T(n)$ steps and if it has not stopped answer “YES”.

Hint (for oposite): $L \in \text{RP} \cap \text{coRP}$, polynomial-time probabilistic turing-machine M_1, M_2 s.t. M_1 is always correct on $x \notin L$ and M_2 is always correct on $x \in L$. Define M' by running $M_1(x, r), M_2(x, r)$:

If $M_1(x, r) = M_2(x, r)$ then output $M_1(x, r)$
else pick another random r' and run $M'(x, r')$

Exercise 2.16.12. $\text{ZPP} \subseteq \text{NP} \cap \text{coNP}$

The $\frac{2}{3}$ in the definition of BPP seems arbitrary. In fact, we can fix it to anything “slightly larger” than $\frac{1}{2}$ and get the same BPP .

Proposition 2.16.13. (Markov’s Inequality) $\Pr[X \geq k] \leq \frac{E[X]}{k}$ for any non-negative random variable X .

Proof. $E[X] = \sum_{v \geq 0} v \Pr[X = v] \geq 0 + k \Pr[X \geq k]$ □

Proposition 2.16.14. (Chernoff’s bound) Let X_1, \dots, X_k be independent, identically distributed boolean random-variables with $\Pr[X_i = 1] = p \forall i \in \{1, \dots, k\}$ and $\delta \in (0, 1)$. Then

$$\Pr \left[\left| \frac{\sum_{i=1}^k X_i}{k} - p \right| > \delta \right] < e^{-\frac{\delta^2}{4} pk}$$

Proof. Define $X := \sum_{i=1}^k X_i$. We know $E[X] = \sum_{i=1}^k E[X_i] = \sum_{i=1}^k p = kp$. Now we estimate $\Pr[X - kp > k\delta]$ and $\Pr[X - kp < -k\delta]$ for an arbitrary $\delta \in (0, 1)$. Let $t > 0$ be a variable (which will be set later):

$$\begin{aligned} E[e^{tX}] &:= E \left[\prod_{i=1}^k e^{tX_i} \right] \\ &= \prod_{i=1}^k E[e^{tX_i}] \\ &= \prod_{i=1}^k ((1-p) \cdot 1 + pe^t) \\ &= \prod_{i=1}^k (1 + p(e^t - 1)) \\ &\leq \prod_{i=1}^k e^{p(e^t - 1)} \\ &= e^{kp(e^t - 1)} \end{aligned}$$

As quantities are all nonnegative, we get

$$\begin{aligned} \Pr[X > kp + k\delta] &= \Pr[e^{tX} > e^{t(kp+k\delta)}] \\ &< \frac{E[e^{tX}]}{e^{t(kp+k\delta)}} \\ &< \frac{e^{kp(e^t-1)}}{e^{t(kp+k\delta)}} \end{aligned}$$

Exercise 2.16.15. a) Show that $t = \ln \left(1 + \frac{\delta}{p} \right)$ is minimizing the right-hand side.

b) in a similar way estimate $\Pr[X - kp < -k\delta]$

□

Theorem 2.16.16. Let $L \subseteq \{0, 1\}^*$ and M be a polynomial-time probabilistic turing-machine s.t. $\exists c > 0, \forall x \in \{0, 1\}^*, x \in L$ iff $\Pr[M \text{ accepts } x] \geq \left(\frac{1}{2} + |x|^{-c}\right)$. Then $\forall d > 0, \exists$ polynomial-time turing-machine M' s.t. $\forall x \in \{0, 1\}^*, x \in L$ iff $\Pr[M' \text{ accepts } x] \geq \left(1 - 2^{-|x|^d}\right)$

Proof. Define M' : on input x run $M(x)$ for k times and let $y_1, \dots, y_k \in \{0, 1\}$ be the outputs. Now output for $M'(x)$ the majority of y_1, \dots, y_k . Let $|x| =: n$ and we will now fix k as a function of n . Let X_i be the random variable s.t. $X_i = 1$ if y_i is correct and $X_i = 0$ if y_i is incorrect. We know $\Pr[X_i = 1] \geq p := \frac{1}{2} + \frac{1}{n^c}$. X_1, \dots, X_k are independent and identically distributed random-variables.

By Chernoff's bound we get that

$$\begin{aligned} \Pr[M' \text{ is wrong}] &= \Pr[\text{majority is wrong}] \\ &= \Pr\left[\frac{\sum_{i=1}^k X_i}{k} < \frac{1}{2}\right] \\ &\leq \Pr\left[\left|\frac{\sum_{i=1}^k X_i}{k} - p\right| > \frac{1}{n^c}\right] \\ &< e^{-\frac{n-2n}{4} \left(\frac{1}{2} + n^{-c}\right)k} \end{aligned}$$

Now it suffices to show that there is a k with $\frac{n-2n}{4} \left(\frac{1}{2} + n^{-c}\right)k > n^d$. So $k > 4n^{d+2c} \left(\frac{2}{1+2n^{-c}}\right)$ must hold. So pick a k with $k > 8|x|^{d+2c}$.

□

2.17 BPP and PH

$BPP \subseteq NP$ is not known but $BPP \subseteq NP^{NP}$ is.

Exercise 2.17.1. $coBPP = BPP$

Theorem 2.17.2. (Sipser-Gács 1983) $BPP = \Sigma_2^P \cap \Pi_2^P$

Proof. We show $BPP \subseteq \Sigma_2^P$. Suppose $L \in BPP$. Then by the definition of BPP and by the error-reduction theorem we get that there is a polynomial-time turing-machine M and $m \in \mathbb{N}[X]$ s.t. $\forall x \in \{0, 1\}^n$,

$$\begin{aligned} x \in L &\Rightarrow \Pr_{r \in \{0,1\}^m} [M(x, r) = 1] \geq \left(1 - \frac{1}{2^n}\right) \\ x \notin L &\Rightarrow \Pr_{r \in \{0,1\}^m} [M(x, r) = 1] \leq \frac{1}{2^n} \end{aligned}$$

Denote $S_x := \{r \in \{0, 1\}^m \mid M(x, r) = 1\}$. Then the above means that $|S_x| \geq (1 - 2^{-n})2^m$ if $x \in L$ while $|S_x| \leq 2^{m-n}$ if $x \notin L$. Can we capture this in Σ_2^P ?

Fix $k := \left(\frac{m}{n} + 1\right)$. For any $U = \{u_1, \dots, u_k\} \subseteq \{0, 1\}^m$ Define a Graph G_U : $V(G_U) := \{0, 1\}^m$, $E(G_U) := \{(s, s') \in \{0, 1\}^m \mid s \oplus u_i = s' \text{ for some } i\}$ where \oplus is bitwise XOR. G_U is of degree k . For any $S \subseteq \{0, 1\}^m$ define $\Gamma_U(S)$ to be the neighbours of S in G_U .

Claim 1: If $|S| \leq 2^{m-n}$ then $\forall U, |U| = k, \Gamma_U(S) \neq \{0, 1\}^m$. Proof: $|\Gamma_U(S)| \leq |U||S| = k2^{m-n} < 2^m$.

Claim 2: $\exists U, |U| = k$ if $|S| \geq (1 - 2^{-n})2^m$ then $\Gamma_U(S) = \{0, 1\}^m$. Proof: We prove the existence of such a $U = \{u_1, \dots, u_k\}$ by a probabilistic argument.

Choose $U \subseteq \{0, 1\}^m$ randomly. Let us fix a set S which is large enough. Now let E_r be the event that $r \in \{0, 1\}^m$ is not in $\Gamma_U(S)$ and $E_{r,i}$ the event that $r \notin S \oplus u_i$. Clearly

$$\begin{aligned} \Pr_U[E_r] &= \prod_{i=1}^k \Pr_U[E_{r,i}] \\ &= \prod_{i=1}^k \Pr_U[u_i \notin S \oplus u_i] \\ &\leq \prod_{i=1}^k 2^{-n} = 2^{-kn} < 2^{-m} \end{aligned}$$

So $\Pr_U[\exists r, r \notin \Gamma_U(S)] \leq \sum_{r \in \{0, 1\}^m} \Pr_U[r \notin \Gamma_U(S)] < 1$. $\Pr_U[\forall r, r \in \Gamma_U(S)] > 0$. So there are many U s.t. $\Gamma_U(S) = \{0, 1\}^*$. So Claims (1) and (2) together with 2.17 mean: $\forall x \in \{0, 1\}^n, x \in L$ iff $\exists u_1, \dots, u_k \in \{0, 1\}^m, \forall r \in \{0, 1\}^m, \bigvee_{i=1}^k [M(x, r \oplus u_i) = 1]$ \square

Exercise 2.17.3. • $P \neq BPP \Rightarrow P \neq NP$

- $BPP = NP \Rightarrow NP = coNP \Rightarrow PH$ collapses to the first level.

Open question: Does an BPP -complete problem exist? It is even not clear how to define such a problem.

2.18 Randomized Reductions

Definition 2.18.1. A language A reduces to B in randomized polynomial-time, $A \leq_r B$ if there exists a polynomial-time probabilistic turing-machine M such that for all $x \in \{0, 1\}^*$:

$$\Pr[B(M(x)) = A(x)] \geq \frac{2}{3}$$

Recall the reduction of PH to $\oplus SAT$.

Definition 2.18.2. A randomized version of NP :

$$BP \cdot NP := \{L \mid L \leq_r SAT\}$$

Exercise 2.18.3. • $NP \subseteq BP \cdot NP$

- $coBP \cdot NP = BP \cdot coNP$

Later we will see that $GI := \text{Graph-Isomorphism} \in NP \cap coBP \cdot NP$. This is a very natural problem which lays between P and NP and is “almost” in $NP \cap coNP$.

2.19 Randomied Space-bounded Computation

Definition 2.19.1. A polynomial-time probabilistic turing-machine M works in space $S(n)$ if for all input $x \in \{0, 1\}^*$ and random strings $r \in \{0, 1\}^*$ $M(x, r)$ need work-space $\leq S(|x|)$.

A language $L \in BPL$ if there exists a $O(\log(n))$ -space probabilistic turing-machine M such that $\forall x$:

$$\Pr[M(x) = L(x)] \geq \frac{2}{3}$$

A language $L \in RL$ if there exists a $O(\log(n))$ -space probabilistic turing-machine M such that $\forall x$:

$$\begin{aligned} x \in L &\Rightarrow \Pr[M(x) = 1] \geq \frac{2}{3} \\ x \notin L &\Rightarrow \Pr[M(x) = 1] = 0 \end{aligned}$$

Exercise 2.19.2. • $RL \subseteq NL \subseteq P$

- * $BPL \subseteq P$ (Hint: Look at the determinant of a modified configuration graph)

One famous RL -algorithm is for $UPath$. Let G be an undirected graph and $s, t \in V(G)$:

$$UPath := \{(G, s, t) \mid \exists \text{ path from } s \text{ to } t\}$$

Recall that $Path$ (the directed case) is NL -complete, and its \mathbb{L} or RL -algorithms are open.

Theorem 2.19.3. *Aleulinas, Karp, Lipton, Lovász, Rackoff [1979]:* $UPath \in RL$

Reingold [2005]: $UPath \in \mathbb{L}$

Proof. (of $UPath \in RL$).

Suppose G is the given undirected connected graph with n vertices and $s, t \in V(G)$. The Problem is to find an undirected path from s to t in G . W.l.o.g. we can assume G to be d -regular (i.e. every vertex has d adjacent edges). For example ($d = 3$) convert a vertex of degree 5 and $\Gamma(v) = \{u_1, \dots, u_5\}$ into three vertices v', v'', v''' , connect them and then connect u_1, u_2 to v' , u_3 to v'' and u_4, u_5 to v''' . Thus in logspace we can “make” G a d -regular graph ($d \geq 3$). Now the RL -algorithm for $UPath$ is:

- do a random walk starting from s , of length $n^3 \log(n)$. We will show that for all vertices $t \in V(G)$, s is connected to t $\Pr[\text{reaching } t] \geq \frac{1}{2n}$.
- we will show that

$$\begin{aligned} s \text{ is connected to } t &\Rightarrow \Pr[\text{stop at } t] > \frac{1}{2} \\ s \text{ is not connected to } t &\Rightarrow \Pr[\text{stop at } t] = 0 \end{aligned}$$

Thus repeating this random walk, say $10n$ times, we reach t with probability $\geq \frac{2}{3}$.

Exercise 2.19.4. *Repeat the proof of error-reduction in BPP to RP for RP-algorithms where probability $\geq \frac{1}{n^c}$ can be boosted to $(1 - 2^{-n^d})$.*

We collect the probabilities $p_i := \Pr[\text{walk is at vertex } i]$ in a column vector $\vec{p} \in [0, 1]^n$. At any step of the walk: $(1, \dots, 1) \circ \vec{p} = 1$. Let $\{\vec{e}^i\}_{i=1}^n$ be the elementary vectors in \mathbb{R}^n (which are zero except at the i -th position where they are one). Initially $\vec{p} = \vec{e}^s$.

W.l.o.g. we assume each vertex in G to have a self-loop.

Now let A be the “normalized adjacency matrix” of G i.e.

$$A_{i,j} := \frac{\#\text{edges between } i \text{ and } j}{d}$$

A is symmetric ($A^T = A$) with entries in $[0, 1]$. and each row and column sums to 1 (such matrices are called symmetric-stochastic-matrices). If the probability vector in the current step is \vec{p} then it will be $\vec{q} = A\vec{p}$ in the next step, because:

$$\begin{aligned} q_i &= \Pr[\text{walk is at } i] \\ &= \sum_{j=0}^n \Pr[\text{walk is at } j] \Pr[\text{walk goes to } i \mid \text{walk was at } j] \\ &= \sum_{j=0}^n p_j A_{i,j} = (A\vec{p})_i \Rightarrow \vec{q} = A\vec{p} \end{aligned}$$

Then after l steps of the walk: $\vec{p} = A^l \vec{e}^s$.

We will show that $\Pr[\text{reaching } i \text{ in } l = 30n^2 \lg(n)] > \frac{1}{2n}$ for all i in the connected component of s and we will study powers of A and see how “soon” does $(A^l \vec{e}^s)_t$ is a “decent” probability.

We will use the following notation

Euclidean norm $\|\vec{v}\| := \sqrt{\sum_{i=1}^n v_i^2}$

inner product $\langle \vec{u}, \vec{v} \rangle = \sum_{i=1}^n u_i v_i$

Cauchy-Schwarz Inequality $\|\vec{u}\| \|\vec{v}\| \geq \sum_{i=1}^n |u_i v_i| \geq \langle \vec{u}, \vec{v} \rangle$

Definition 2.19.5. Let $\vec{1} = (\frac{1}{n}, \dots, \frac{1}{n})^T$ be the uniform distribution vector. Let $\vec{1}^\perp := \{\vec{v} \in \mathbb{R}^n \mid \langle \vec{1}, \vec{v} \rangle = 0\}$. Define:

$$\lambda(A) := \max\{A\vec{v} \mid \vec{v} \in \vec{1}^\perp \text{ \& } \vec{v} \text{ is a unit vector}\}$$

Exercise 2.19.6. a) Show that the largest eigenvalue of A is 1 (with multiplicity 1)

b) Show that the second largest eigenvalue of A is $\lambda(A)$

By the definition of λ :

$$\|A\vec{v}\| \leq \lambda(A) \|\vec{v}\| \quad \forall \vec{v} \in \vec{1}^\perp$$

Note that

$$\langle A\vec{v}, \vec{1} \rangle = \langle \vec{v}, A\vec{1} \rangle = \langle \vec{v}, \vec{1} \rangle = 0$$

which implies that A maps $\vec{1}^\perp$ to itself and shrinks each vector in $\vec{1}^\perp$ at least by a factor of $\lambda(A) \Rightarrow \forall \vec{v} \in \vec{1}^\perp, \|A^l \vec{v}\| \leq \lambda(A)^l \|\vec{v}\|$

$$\Rightarrow \lambda(A^l) \leq \lambda(A)^l$$

Lemma 2.19.7. For every probability vector \vec{p} :

$$\|A^l \vec{p} - \vec{1}\| \leq \lambda(A)^l$$

Remark 2.19.8. The further $\lambda(A)$ is away from 1 the better is the “expansion property” of G .

Proof. Decompose $\vec{p} = \alpha \vec{1} + \vec{p}'$ where $\vec{p}' \in \vec{1}^\perp$.

$$\begin{aligned} \Rightarrow 1 &= \alpha + \langle \vec{p}', \vec{1} \rangle = \alpha \\ \Rightarrow A^l \vec{p} &= A^l \vec{1} + A^l \vec{p}' = (\vec{1} + A^l \vec{p}') \\ \Rightarrow \|A^l \vec{p} - \vec{1}\| &= \|A^l \vec{p}'\| \leq \lambda(A)^l \|\vec{p}'\| \leq \lambda(A)^l \|\vec{p}\| \end{aligned}$$

Observe that $\|\vec{p}\|^2 = \|\vec{1}\|^2 + \|\vec{p}'\|^2$ this implies $\|\vec{p}'\| < \|\vec{p}\| < (\sum_{i=1}^n p_i)^2 = 1$ this from equation 2.19:

$$\|A^l \vec{p} - \vec{1}\| < \lambda(A)^l$$

□

What is $\lambda(A)$ in general?

Lemma 2.19.9.

$$\lambda(A) \leq \left(1 - \frac{1}{8dn^3}\right)$$

Proof. Let $\vec{u} \in \vec{1}^\perp$ be a unit vector and $\vec{v}' = A\vec{v}$. We will show that

$$1 - \|\vec{v}\|^2 \geq \frac{1}{4dn^3}$$

meaning that $\|\vec{v}\| \leq \sqrt{1 - \frac{1}{4dn^3}} < 1 - \frac{1}{8dn^3}$. Which means that $\lambda(A) < 1 - \frac{1}{8dn^3}$ by definition.

$$1 - \|\vec{v}\|^2 = \|\vec{u}\|^2 - \|\vec{v}\|^2 = \sum_{1 \leq i, j \leq n} A_{i,j} (u_i - v_j)^2$$

This holds because

$$\begin{aligned} \sum_{i,j} A_{i,j} (u_i - v_j)^2 &= \sum_{i,j} A_{i,j} u_i^2 - 2 \sum_{i,j} A_{i,j} u_i v_j + \sum_{i,j} A_{i,j} v_j^2 \\ &= \|\vec{u}\|^2 - 2 \langle A\vec{u}, \vec{v} \rangle + \|\vec{v}\|^2 \\ &= \|\vec{u}\|^2 - 2\|\vec{v}\|^2 + \|\vec{v}\|^2 \\ &= \|\vec{u}\|^2 - \|\vec{v}\|^2 \end{aligned}$$

Thus it suffices to show some i, j s.t. $A_{i,j} (u_i - v_j)^2 \geq \frac{1}{4dn^3}$. Because G has self-loops, $A_{i,i} = \frac{1}{d}$ and we can further assume $|u_i - v_i| < \frac{1}{2n^{1.5}}$ for all i , otherwise we are done.

Sort the coordinates of \vec{u} w.l.o.g. $u_1 \geq u_2 \geq \dots \geq u_n$. Since $\sum_{i=1}^n u_i = 0$ and $\sum_{i=1}^n u_i^2 = 1$ $u_1 > 0$, $u_n < 0$ and either $u_1 \geq \frac{1}{\sqrt{n}}$ or $u_n \leq -\frac{1}{\sqrt{n}}$ so $u_1 - u_n \geq \frac{1}{\sqrt{n}}$.

$$\begin{aligned} \Rightarrow \exists i_0 : u_{i_0} - u_{i_0+1} &\geq \frac{1}{n^{1.5}} \\ \Rightarrow \forall i \in \{1, \dots, i_0\} \ \&\ \forall j \in \{i_0 + 1, \dots, n\}, u_i - u_j \geq \frac{1}{n^{1.5}} \end{aligned}$$

□ Since G is connected there exists an edge $(i, j) \in \{1, \dots, i_0\} \times \{i_0 + 1, \dots, n\}$ with $A_{i,j} = \frac{1}{d}$ & $u_i - u_j \geq \frac{1}{n^{1.5}}$.

Note that $|u_i - v_j| \geq |u_i - u_j| - |u_j - v_j| > \frac{1}{n^{1.5}} - \frac{1}{2n^{1.5}} = \frac{1}{2n^{1.50}}$. Which finally shows that $A_{i,j} (u_i - v_j)^2 \geq \frac{1}{d} \frac{1}{4n^3}$ and $1 - \|\vec{v}\|^2 > \frac{1}{4dn^3}$. □

Lemma 2.19.10. *Do a random walk on G from s for $l \geq 10dn^3 \lg(n)$ steps. Then*

$$\Pr[\text{reaching } s \text{ at the } l\text{-th step}] > \frac{1}{2n}$$

Proof. Let \vec{p} be the probability distribution on $V(G)$ at the l -th step. By 2.19.7 and 2.19.9:

$$\|A^l \vec{e}^s - \vec{1}\| < \left(1 - \frac{1}{8dn^3}\right)^l < \frac{1}{2n^{1.5}}$$

and by Cauchy-Schwartz

$$\begin{aligned} \Rightarrow \sum_{i=1}^n |(A^l \vec{e}^s - \vec{1})_i| &< \frac{1}{2n} \\ \Rightarrow |(A^l \vec{e}^s - \vec{1})_t| &< \frac{1}{2n} \\ \Rightarrow (A^l \vec{e}^s)_t &> \frac{1}{n} - \frac{1}{2n} = \frac{1}{2n} \end{aligned}$$

□

Remark 2.19.11. a) So we have seen that $UPath \in RL$ [1979]

b) Now, $UPath \in \mathbb{L}$ is known

Idea: If we can transform G to a graph G' (in \mathbb{L}) with a constant $\lambda(G')$ (again this is the second largest eigenvalue of the normalized adjacency-matrix) then it will have a much better “expansion”, i.e.

$$|A^l e^{\vec{s}} - \vec{1}| < \lambda(G')^l \leq \frac{1}{n^2}$$

for $l \in O(\lg(n))$, $n := |V(G')|$. Proved by Reingold [2005]. The transformation will be shown in the next course.

c) An expander is a family of graphs $\{G_i\}_{i=1}^{\infty}$ with $\lambda(G_i) < \epsilon \in \mathbb{R} \forall i \in \mathbb{N}$

2.20 Graph Isomorphism (GI)

Definition 2.20.1.

$$\begin{aligned} GI &:= \{(G_1, G_2) \mid \text{finite graphs } G_1 \cong G_2\} \\ GNI &:= \{(G_1, G_2) \mid \text{finite graphs } G_1 \not\cong G_2\} \end{aligned}$$

It is trivial that $GI \in NP$ and $GNI \in coNP$ but it is open if $GNI \in NP$.

Theorem 2.20.2. (Goldwasser-Sipser [1986])

$$GNI \in BP \cdot NP$$

Proof. We will show the existence of a polynomial-time transformation A and a constant $c > 0$ s.t.

$$\begin{aligned} (G_1, G_2) \in GNI &\Rightarrow \Pr_r [\exists y, A(G_1, G_2, r, y) = 1] \geq \frac{2}{3} \\ (G_1, G_2) \notin GNI &\Rightarrow \Pr_r [\exists y, A(G_1, G_2, r, y) = 1] \leq \frac{1}{3} \end{aligned}$$

where $r, y \in \{0, 1\}^{|(G_1, G_2)|^c}$.

The key idea is to look at a set S associated with the graphs G_1 and G_2 (having n vertices):

$$\begin{aligned} S &:= \{(H, \pi) \mid H \text{ is a graph on vertices } \{1, \dots, n\} \\ &\quad H \cong G_1 \vee H \cong G_2, \pi \in \text{Aut}(H)\} \end{aligned}$$

- If $G_1 \cong G_2$ then $\#S = \#(\{H \mid H \cong G_1\} \times \text{Aut}(G_1)) \Rightarrow \#S = \frac{n!}{\#\text{Aut}(G_1)}$.
 $\#\text{Aut}(G_1) = n!$
- If $G_1 \not\cong G_2$ then $\#S = \sum_{i=1}^2 \#(\{H \mid H \cong G_i\} \times \text{Aut}(G_i)) = 2n!$.
- And “membership-in- S ” $\in NP$.

Thus $\#S$ is larger (by a factor of 2) when $(G_1, G_2) \in GNI$. We now give a general method for set-lower-bound in $BP \cdot NP$.

Recall from the proof of $SAT \leq_r \oplus SAT$, a hash function for $B \in \{0, 1\}^{k \times m}$, $b \in \{0, 1\}^k$ (also see 2.15.15):

$$\begin{aligned} h_{B,b} : \{0, 1\}^m &\rightarrow \{0, 1\}^k \\ u &\mapsto (Bu + b) \end{aligned}$$

with the above properties.

Let $m = \max_{s \in S} \{|s|\}$ (where we think of S as a subset of $\{0, 1\}^m$). And let $k \in \mathbb{N}$ be such that $2^{k-2} \leq 2n! \leq 2^{k-1}$.

Idea: For a random hash-function $h_{B,b}$ and a random image z there exists a pre-image with high-probability iff S is “large”.

- If $\#S = 2n!$ then

$$\Pr_{B,b,z} [\exists y \in S : h_{B,b}(y) = z] \geq \frac{\#S}{2^k} \left(1 - \frac{\#S}{2^{k+1}}\right) \geq \frac{3}{16}$$

- If $\#S = n!$ then

$$\Pr_{B,b,z} [\exists y \in S : h_{B,b}(y) = z] \leq \frac{\#S}{2^k} = \frac{n!}{2^k} \leq \frac{1}{4}$$

- It is easy to see that repeating this, say 8 times gives us:

$$\begin{aligned} \#S = 2n! &\Rightarrow \Pr_{\bar{B}, \bar{b}, \bar{z}} [\exists \bar{y} \in S^8 : h_i(y_i) = u_i \forall i] > \frac{2}{3} \\ \#S = n! &\Rightarrow \Pr_{\bar{B}, \bar{b}, \bar{z}} [\exists \bar{y} \in S^8 : h_i(y_i) = u_i \forall i] < \frac{1}{3} \end{aligned}$$

- We can check $h(y) = z$ in polynomial-time and $y \in S$ too, using a certificate. Thus we get a suitable polynomial-time turing-machine A .

□

So we see that $GNI \in coNP \cap BP \cdot NP$

Theorem 2.20.3. (Schöning [1987]) *If GI is NP-complete then $\Sigma_2^P = \Pi_2^P$.*

Proof. Suppose GI is NP-complete then GNI is coNP-complete. Let $\psi := \exists x \forall y \phi(x, y)$ (where ϕ is a boolean formula) be a Σ_2^P -instance with $n := |x| = |y|$.

We can convert the question of $\forall y \phi(x, y)$ to an equivalent question of graphs $g: g(x) \in GNI$.

Now define a new quantifier M by $M(z \in \{0, 1\}^m) : \tau(z)$ is true iff $\tau(z)$ is true for “most” $z \in \{0, 1\}^m$ (probability bound will depend on the context).

Since $GNI \in BP \cdot NP$ (M, \exists) we can rewrite $g(x) \in GNI$ as

$$Mr \exists a : T(x, r, a) = 1$$

for some polynomial-time turing-machine T .

Thus $\psi_1 := \exists x Mr \exists a T(x, r, a) = 1$ is equivalent to ψ . By a suitable error reduction, we get a polynomial-time turing-machine T' and bigger strings r', a' s.t. $\psi_2 := Mr' \exists a' T'(x, r', a') = 1$ is equivalent to ψ_1 .

Exercise 2.20.4. *Work out the amplification under which ψ_1 and ψ_2 become equivalent.*

Recall the proof of 2.17.2), it can be seen as a general way to replace M by $\forall \exists$: $\psi_3 := \forall s_1 \exists s_2 \exists s_3 \exists s_4 T''(\vec{s}) = 1$ is equivalent to ψ_2 , hence to ψ .

$$\begin{aligned} \Rightarrow \Sigma_2^P SAT &\in \Pi_2^P \\ \Rightarrow \Sigma_2^P &\subseteq \Pi_2^P \\ \Rightarrow \Sigma_2^P &= \Pi_2^P \end{aligned}$$

$\Rightarrow PH$ collapses.

□

Chapter 3

Circuits

3.1 Definition of Boolean & Arithmetic Circuits

Turing machines capture problems that can be solved by some algorithm. What about a language L for which there is a different algorithm A_n for each $x \in \{0, 1\}^*$ with $n = |x|$ (non-uniform vs. uniform computation). There is a mathematically elegant way to capture these problem: circuits (inspired by real "silicon chips").

Definition 3.1.1. A boolean circuit $C(x_1, \dots, x_n)$ is a directed rooted tree with boolean input nodes x_1, \dots, x_n at the leaves. The internal nodes are labeled with OR, AND and NOT and the output is calculated at the root. Sometimes a boolean circuit can have several outputs and so it has several roots.

The maximal indegree of a node is the fanin of C and the maximal outdegree the fanout. $|C| := \text{size}(C) := \# \text{nodes in the tree}$. $\text{depth}(C) := \# \text{levels in the tree}$. A circuit is called a formula if its fanout is 1. A boolean circuit with n inputs and m outputs computes a function $\{0, 1\}^n \rightarrow \{0, 1\}^m$.

Now we can formalize when a circuit family solves a problem:

Definition 3.1.2. Let $S : \mathbb{N} \rightarrow \mathbb{N}$ be a function. A $s(n)$ -sized circuit family is a sequence of boolean circuits $\{C_n\}_{n \in \mathbb{N}}$ s.t. $|C_n| = O(s(n))$.

$$\text{size}(s(n)) := \{L \subseteq \{0, 1\}^* \mid \exists s(n) \text{ - sized circuit family } \{C_n\}_{n \in \mathbb{N}} \\ \text{s.t. } \forall x : C_n(x) = L(x) \text{ where } n = |x|\}$$

$$P/poly := \bigcup_{c \in \mathbb{N}} \text{Size}(n^c)$$

non-uniform polynomial-time.

Exercise 3.1.3. a) Any language L has a $n \cdot 2^n$ -sized circuit family i.e. $\text{size}(n2^n) = 2^{\{0,1\}^*}$.

b) Uncomputable problems are solvable with $n2^n$ -circuit families

c) there exists an uncomputable problem solvable by an n -sized circuit family

Hint: Consider

$$L := \{1^n \mid M_n(1^n) \text{ where } M_n \text{ is a turing-machine described by } (n)_2\}$$

So constant-sized circuits can solve some uncomputable problems.
We reduce the strength of $P/poly$ by a uniformity restriction.

Definition 3.1.4. A circuit family $\{C_n\}$ is called logspace-uniform if there exists a logspace algorithm that generates C_n on input 1^n .

$$(\text{logspace-uniform})P/poly := \{L \subseteq \{0,1\}^* \mid \exists c > 0, \exists \text{ logspace-uniform } n^c\text{-sized circuit family } \{C_n\} \text{ s.t. } C_n \text{ decides } L \cap \{0,1\}^n\}$$

Theorem 3.1.5. $(\text{logspace-uniform})P/poly = P$

Proof. "⊆" Even with polynomial-time in place of logspace it is true!

"⊇" Let $L \in P$ be a language and M is a n^c -time turing-machine deciding L . Idea: We encode the steps of M on $\{0,1\}^n$ in a polynomial-sized circuit C_n in $O(\log(n))$ space. As in Cook-Levins (proof of NP -hardness of SAT) first convert M into an n^{2^c} -time turing-machine \tilde{M} which is oblivious (i.e. the i -th head-movement of \tilde{M} depends only on i). Thus the i -th head-position of \tilde{M} can be computed in $O(\log(n))$ space given 1^i . Let $\zeta_1, \dots, \zeta_{n^{2^c}}$ be the n^{2^c} configurations of \tilde{M} starting from the initial to the final state of \tilde{M} on input x_1, \dots, x_n . Each ζ_i is an array (head-position, head-bit, state). Construct the circuit C_n as: In the i -th level it computes ζ_i from ζ_{i-1} using $\delta(\tilde{M})$. Finally it outputs 1 iff $\zeta_{n^{2^c}}$ is in the accept state. So $|C_n| = \text{depth}(C_n) = O(n^{2^c})$. C_n can be generated given 1^n in $O(\log(n))$ space. And we see that L has a logspace non-uniform n^c -sized circuit family. \square

Exercise 3.1.6. a) $P \subseteq P/poly$

b) $SAT \notin P/poly \Rightarrow P \neq NP$

Open: $SAT \notin P/poly$

Remark 3.1.7. SAT can have a polynomial-sized circuit even if $SAT \notin P$.

Theorem 3.1.8. (Karp-Lipton, 1980) $NP \subseteq P/Poly \Rightarrow \Pi_2 = \Sigma_2 \Rightarrow PH = \Sigma_2$

Proof. Suppose $SAT \in P/Poly$ then for any boolean formula $\phi(x_1, \dots, x_n)$ of size m there is a constant c and a boolean circuit $C_m(\phi(x_1, \dots, x_n))$ of size m^c s.t. $C_m(\phi) = 1$ iff ϕ is satisfiable.

Note that $\phi(x_1, \dots, x_n)$ is satisfiable iff $\phi(1, x_2, \dots, x_n)$ or $\phi(0, x_2, \dots, x_n)$ is satisfiable (or both). So using SAT as an oracle you can actually find a satisfying assignment. This property is called self-reducibility.

By repeating this n times we get a circuit C'_m of size $O(nm^c)$ that outputs a satisfying assignment of ϕ (if one exists). C'_m can be expressed using m^{3c} bits.

Let $\forall u \exists v \psi(u, v)$ be a $\Pi_2 SAT$ instance. Look at the formula $\forall [\psi(u, C'_m(\psi)) = 1]$. Now look at $\exists w \forall u [w \text{ is a circuit of size } \leq m^{3c} \ \& \ \psi(u, w(\psi)) = 1]$. The two quantified formulars are equivalent. $\Pi_2 \subseteq \Sigma_2 \Rightarrow PH = \Sigma_2$. \square

This theorem gives hope that " SAT does not have polynomial-sized circuits". There are results known for SAT not having certain special boolean circuits, e.g. monotone circuits.

It is interesting that most of the functions $\{0,1\}^n \rightarrow \{0,1\}$ have high circuit complexity.

Theorem 3.1.9. “Almost all” boolean functions $\{0, 1\}^n \rightarrow \{0, 1\}$ require circuits of size $\geq 2^n/10n$.

Proof. $\#\{f : \{0, 1\}^n \rightarrow \{0, 1\}\} = 2^{2^n}$ and w.l.o.g. fanin of every circuit is 2 and fanout is 1 (by breaking a circuit with more fanout / fanin up in more levels) then $\#\{\text{circuits of size } s \text{ on } n\text{-sized input}\} < s^{3s}$. For $s = \frac{2^n}{10n}$, $s^{3s} \leq 2^{\frac{2^n}{3}} < 2^{2^n}$. Thus a “random” function requires circuits of size $> \frac{2^n}{10n}$. \square

Open: Find such a function explicitly.

Exercise 3.1.10. Prove the non-uniform hierarchy theorem:

$\forall T, T' : \mathbb{N} \rightarrow \mathbb{N}$ s.t. $T'(n) = \omega(T(n) \lg(T(n)))$ then $\text{size}(T(n)) \not\subseteq \text{size}(T'(n))$

Hint: By counting a function in $\text{size}(T'(n)) - \text{size}(T(n))$

BPP is also related to *P/poly*:

Theorem 3.1.11. (Adleman 1978) $BPP \subseteq P/poly$

Proof. Suppose $L \in BPP$ then there exists a polynomial-time turing-machine M s.t. $\forall n \in \mathbb{N}, x \in \{0, 1\}^n$:

$$\begin{aligned} x \in L &\Rightarrow \Pr_{r:|r|=m}[M(x, r) = 1] \geq \left(1 - \frac{1}{2^{n+1}}\right) \\ x \notin L &\Rightarrow \Pr_{r:|r|=m}[M(x, r) = 1] \leq \frac{1}{2^{n+1}} \end{aligned}$$

Say $r \in \{0, 1\}^m$ is bad if for some $x \in \{0, 1\}^n$: $M(x, r)$ is wrong. Thus

$$\#\{r \mid r \text{ is bad}\} \leq 2^n \frac{2^m}{2^{n+1}} = \frac{2^m}{2}$$

So pick an $r_n \in \{0, 1\}^m$ for which $M(x, r_n)$ is correct for all $x \in \{0, 1\}^n$. Define C_n to be the circuit that simulates $M(x_1, \dots, x_n, r_n)$ (where x_i is the i -th bit of x). Which implies that $LinP/poly$. \square