

Elliptic Curves, Divisors and Lines

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Abstract

This Script is basis for a seminar talk given in the seminar “Algebraic methods in computational complexity” by Prof. Nitin Saxena in summer term 2010. Its heavily based on a paper by Leonard S. Charlap and David P. Robbins from 1988 [CRD]. We will give all common definitions, results and proofs for this results on elliptic curves over finite fields.

1 Notation and Global Definition

For a field K , $n \in \mathbb{N}$ and $k \in K$ we define

$$n \cdot k := \underbrace{k + \dots + k}_{n\text{-times}}$$

The characteristic of a field K is defined by

$$\text{char}(K) := \begin{cases} 0 & \text{for } C_k = \emptyset \\ \min(C_K) & \text{else} \end{cases}$$

with $C_k := \{p \in \mathbb{N}_{>0} \mid p \cdot 1 = 0, 1 \in K \text{ additive neutral}\}$.

Proposition 1.1. *char(K) is either 0 or prime.*

Global Definition / Notation 1.2. *From now on let*

- K be an algebraically closed field with $\text{char}(K) \notin \{2, 3\}$
- the letters X and Y be variables
- $K[X]$ and $K[X, Y]$ be the polynomial ring in one respective two variables
- $K(X)$ and $K(X, Y)$ be the field of rational functions in one respective two variables

2 Elliptic Curves

Definition 2.1 (Vanishing Set). For $f \in K[X, Y]$ we define

$$V(f) := \{(a, b) \in K^2 \mid f(a, b) = 0\}$$

Definition 2.2 (Elliptic Curve). For $A, B \in K$ the set

$$E := E_{A,B} := V(Y^2 - X^3 - AX - B) \cup \{\mathcal{O}\}$$

is called an elliptic curve over K if $s(x) := s_{A,B}(x) := x^3 + Ax + B$ has three distinct roots. The element $\mathcal{O} \in E$ is called identity or point at infinity and element of $E \setminus \{\mathcal{O}\}$ finite. For a finite point $P = (a, b) \in E$ we abbreviate $(a, -b)$ by $-P$. The term

$$\Delta(E_{A,B}) := -4A^3 - 27B^2$$

is called discriminant.

Remark 2.3. Sometime one defines the set $E_{A,B}$ as elliptic curve and call it non-singular iff $s_{A,B}$ has three distinct roots. Otherwise it is called singular. We will include non-singularity in the definition of elliptic curve because we only want to deal with non-singular ones.

Definition 2.4 (Points of order two). Let $E_{A,B}$ be an elliptic curve and $\omega_1, \omega_2, \omega_3$ the three distinct roots of $s_{A,B}(x)$. The three points $\Omega_i := (\omega_i, 0) \in E_{A,B}$ are called points of order two.

Proposition 2.5. For an arbitrary $f(x) = x^3 + Ax + B$ with $A, B \in K$ with roots ω_1, ω_2 and ω_3 it holds that:

1. $0 = \omega_1 + \omega_2 + \omega_3$
2. $A = \omega_2\omega_3 + \omega_1\omega_3 + \omega_1\omega_2$
3. $B = -\omega_1\omega_2\omega_3$

Proof. Since K is algebraically closed we can write

$$\begin{aligned} f(x) &= (x - \omega_1)(x - \omega_2)(x - \omega_3) \\ &= x^3 + x^2(-\omega_1 - \omega_2 - \omega_3) + x(\omega_2\omega_3 + \omega_1\omega_3 + \omega_1\omega_2) - \omega_1\omega_2\omega_3 \end{aligned}$$

comparing coefficients with $x^3 + Ax + B$ gives the result. \square

Proposition 2.6 (Elliptic curve criterion). The set $E_{A,B}$ is an elliptic curve iff $\Delta(E_{A,B}) \neq 0$.

Proof. We will show that if $E_{A,B}$ is not an elliptic curve (which, by Def. 2.2, means that $s_{A,B}$ has a double or a tripple root) iff $\Delta(E_{A,B}) = 0$.

Suppose $s_{A,B}$ has a double root w.l.o.g. let this root be ω_1 . From [Prop. 2.5](#) we get the three relations

$$\begin{aligned} 0 &= 2\omega_1 + \omega_2 \\ A &= 2\omega_1\omega_2 + \omega_1^2 \\ B &= -\omega_1^2\omega_2 \end{aligned}$$

from the first one we get $\omega_2 = -2\omega_1$. Plugging that into the second and third relation yield

$$\begin{aligned} A &= 2\omega_1(-2\omega_1) + \omega_1^2 = -4\omega_1^2 + \omega_1^2 = -3\omega_1^2 \\ B &= -\omega_1^2(-2\omega_1) = 2\omega_1^3 \end{aligned}$$

and finally we get

$$\Delta(E_{A,B}) = -27B^2 - 4A^3 = -27(2\omega_1^3)^2 - 4(-3\omega_1^2)^3 = -108\omega_1^6 + 108\omega_1^6 = 0$$

Suppose $s_{A,B}$ has a tripple root then the preceeding proof will do it too.

Suppose $\Delta(E_{A,B}) = 0$:

$$\begin{aligned} 0 &= \Delta(E) = -27B^2 - 4A^3 \\ \Leftrightarrow \frac{-27B^2}{8A^3} &= \frac{1}{2} \\ \Leftrightarrow 0 &= \frac{-27B^2}{8A^3} - \frac{1}{2} \\ \Rightarrow 0 &= \left(\frac{-27B^2}{8A^3} - \frac{1}{2}\right)B = \frac{-27B^3}{8A^3} - \frac{3B}{2} + B = s_{A,B} \left(\frac{-3B}{2A}\right) \end{aligned}$$

So we know that $x_1 := \frac{-3B}{2A}$ is a root of $s_{A,B}$ and polynomial division yields

$$(x^3 + Ax + B) : (x + \frac{3B}{2A}) = x^2 - \frac{3B}{2A}x + \left(A + \frac{9B^2}{4A^2}\right)$$

p - q -formula yield the two other roots:

$$\begin{aligned} x_{2,3} &= -\frac{\frac{3B}{2A}}{2} \pm \sqrt{\frac{\left(\frac{3B}{2A}\right)^2}{4} - \left(A + \frac{9B^2}{4A^2}\right)} \\ &= -\frac{3B}{4A} \pm \sqrt{\frac{9B^2}{16A^2} - A - \frac{36B^2}{16A^2}} \\ &= -\frac{3B}{4A} \pm \sqrt{\frac{-27B^2}{16A^2} - A} \end{aligned}$$

Now suppose that $s_{A,B}$ has a double root. Then

- $x_2 = x_3$ or
- $x_1 = x_2$ or $x_1 = x_3$

The first case means that the term under the root is zero:

$$\frac{-27B^2}{16A^2} - A = 0 \Leftrightarrow -27B^2 - 16A^3 = 0$$

together with $-27B^2 - 4A^3 = 0$ that implies $A = B = 0$.

For the second two cases we calculate:

$$\begin{aligned}
-\frac{3B}{2A} &= -\frac{3B}{4A} \pm \sqrt{\frac{-27B^2}{16A^2} - A} \\
-\frac{3B}{4A} &= \pm \sqrt{\frac{-27B^2}{16A^2} - A} \\
\frac{9B^2}{16A^2} &= \frac{-27B^2}{16A^2} - A \\
9B^2 &= -27B^2 - 16A^3 \\
0 &= -36B^2 - 16A^3 \\
0 &= -9B^2 - 4A^3
\end{aligned}$$

Which together with $-27B^2 - 4A^3 = 0$ again implies $A = B = 0$. \square

Proposition 2.7. *Elliptic curves are infinite.*

Proof. Suppose $E_{A,B}$ is finite. Since K , which is as an algebraically closed field, infinite, we can find $a \in K$ s.t. $\forall b \in K : (a, b) \notin E_{A,B}$, hence $\nexists b \in K : b^2 = c$ for $c = a^3 + Aa + B$. But since K is algebraically closed, the polynomial $X^2 - c$ needs to have a root. \square

Definition 2.8. *For a subfield $k \subseteq K$ and $A, B \in k$*

$$E(k) := \{(a, b) \in E_{A,B} \mid a, b \in k\} \cup \{\mathcal{O}\}$$

are called k -rational points.

Remark 2.9. *When $\text{char}(K) \in \{2, 3\}$ the defining equation of an elliptic curve can be more general:*

$$k^2 + a_1hk + a_3k = h^3 + a_2h^2 + a_4h + a_6$$

but in our case ($\text{char}(K) \notin \{2, 3\}$) it can be shown that our equation can define every elliptic curve that can be defined by this more general seeming one. [WER, Prop. 2.3.2]

3 Polynomial and Rational Functions

Definition 3.1 (Polynomials on elliptic curve). *For an elliptic curve $E = E_{A,B}$ we denote the set of polynomials on E by*

$$K[E] := K[X, Y] / \langle Y^2 - X^3 - AX - B \rangle$$

Global Definition / Notation 3.2. *From now on let the small letters x and y be the coordinat functions, defined by $x(a, b) := a$ and $y(a, b) := b$ on an elliptic curve E , which therefore fulfill the equation $y^2 = s(x)$. With this notation, we can also say that $K[E] = K[x, y]$.*

Remark 3.3. *Passing to the quotient means that we can replace every Y^2 in a polynomial $f \in K[X, Y]$ by the term $X^3 + AX + B$ without changing the equivalence class of f . So f can be written as $f(x, y) = v(x) + yw(x)$ with $v, w \in K[X]$ i.e. polynomials in one variable.*

Notation 3.4 (Canonical form). *A polynomial $f \in K[E]$ is said to be written in canonical form when we write $f(x, y) = v(x) + yw(x)$.*

Remark 3.5. *The canonical form is unique.*

Proof. Let $f(x, y) = \tilde{v}(x) + y\tilde{w}(x) = \tilde{v}(x) + y\tilde{w}(x)$ be two canonical forms. We get $\tilde{v}(x) - \tilde{v}(x) + y(\tilde{w}(x) - \tilde{w}(x)) = 0$ so after setting $v(x) = \tilde{v}(x) - \tilde{v}(x)$ and $w(x) = \tilde{w}(x) - \tilde{w}(x)$ it suffices to show that from $v(x) + yw(x) = 0$ follows that $v(x) = w(x) = 0$. We calculate

$$\begin{aligned} 0 &= 0 \cdot (v(x) - yw(x)) \\ &= (v(x) + yw(x)) \cdot (v(x) - yw(x)) \\ &= v^2(x) - y^2w^2(x) \\ &= v^2(x) + (-s(x))w^2(x) \end{aligned}$$

Since $\deg_x(s)$ is odd and $\deg_x(v^2)$ and $\deg_x(w^2)$ are even the polynomial w has to be zero, hence the polynomial v . \square

Definition 3.6 (Conjugate and norm). *Write $f \in K[E]$ in canonical form $f(x, y) = v(x) + yw(x)$. The conjugate of f is defined as $\overline{f}(x, y) := v(x) - yw(x)$. The norm of f is defined by $N_f := f \cdot \overline{f}$.*

Remark 3.7.

1. *One can calculate $N_f = v^2(x) - s(x)w^2(x)$ so $N_f \in K[X]$ i.e. a polynomial in only one variable.*
2. *Because we easily see that $\overline{fg} = \overline{f} \overline{g}$ it follows that $N_{fg} = N_f N_g$.*

Definition 3.8 (Rational functions on elliptic curve). *For an elliptic curve E we denote the set of rational functions on E by*

$$K(E) := K[E]^2 / \sim$$

with the following equivalence relation: For $(f, g), (h, k) \in K[E]^2$:

$$(f, g) \sim (h, k) :\Leftrightarrow f \cdot k = g \cdot h$$

(to check the equality one can write both $f \cdot k$ and $g \cdot h$ in canonical form and compare coefficients). We denote the equivalence class of $(f, g) \in K(E)$ by $\frac{f}{g}$. For $r \in K(E)$ and a finite point $P \in E$ we say r is finite at P iff there exists a representation $r = \frac{f}{g}$ with $f, g \in K[E]$ and $g(P) \neq 0$ in this case we define $r(P) := \frac{f(P)}{g(P)}$. If r is not finite at a point P we write $r(P) = \infty$.

Remark 3.9 (Canonical form for rational functions). One can calculate for $r = \frac{f}{g} \in K(E)$:

$$\frac{f}{g} = \frac{f\bar{g}}{g\bar{g}} = \frac{f\bar{g}}{N_g}$$

writing $(f\bar{g})(x, y) = v(x) + yw(x)$ in canonical form yields

$$\frac{f}{g} = \frac{v(x) + yw(x)}{N_g} = \frac{v(x)}{N_g} + y \frac{w(x)}{N_g}$$

so every rational function can be written in canonical form too.

Proposition 3.10. The rational functions that are finite at $P \in E$ form a ring.

Proof. We want to show that

$$R_P := \{r \in K(E) \mid r \text{ is finite at } P\}$$

together with the pointwise addition and multiplication is a ring. Associativity and commutativity of the addition and multiplication and distributivity is inherited from the underlying field. The elements $\frac{0}{1}, \frac{1}{1} \in R_P$ are the neutral elements, which are clearly finite at P . And we can give additive inverse elements by $-\frac{f}{g} = \frac{-f}{g}$. \square

In the following we want to define the value of a rational function at \mathcal{O} . In calculus and in the situation of only one variable (i.e. $f \in K(X)$) one normally compares the degrees of nominator and denominator to obtain a value at ∞ , but in our case we have two variables. The relation $y^2 = x^3 + Ax + B$ suggests that the degree of y should be $\frac{2}{3}$ of the degree of x . Since we want to avoid fractional degrees, we assign the degree 3 to y and the degree 2 to x . The classical degree of a polynomial $f \in K[X]$ will be denoted by $\deg_x(f)$.

Definition 3.11 (Degree of a polynomial). Let $f \in K[E]$ and write it in canonical form $f(x, y) = v(x) + yw(x)$. The degree of f is defined by:

$$\deg(f) := \max \{2 \cdot \deg_x(v), 3 + 2 \cdot \deg_x(w)\}$$

Remark 3.12. Recall that $\deg_x(0) = -\infty$ and $\deg_x(c) = 0 \forall c \in K \setminus \{0\}$

The classical degree of a polynomial and the degree of a polynomial on E are connected via the norm:

Lemma 3.13 (Connection of degree to classical degree). *For $f \in K[E]$:*

$$\deg(f) = \deg_x(N_f)$$

Proof. Write f in canonical form $f(x, y) = v(x) + yw(x)$ then $N_f = v^2(x) - s(x)w^2(x)$. Since $\deg_x(v^2)$ and $\deg_x(w^2)$ are even and $\deg_x(s)$ is odd, it follows that

$$\begin{aligned} \deg_x(N_f) &= \deg_x(v^2(x) - s(x)w^2(x)) \\ &= \max\{\deg_x(v^2), \deg_x(s) + \deg_x(w^2)\} \\ &= \max\{2 \cdot \deg_x(v), 3 + 2 \cdot \deg_x(w)\} \\ &= \deg(f) \end{aligned}$$

□

Furthermore the degree defined at 3.11 has the fundamental property that we expect of degrees:

Proposition 3.14 (Property of degree of polynomials). *For $f, g \in K[E]$:*

$$\deg(f \cdot g) = \deg(f) + \deg(g)$$

Proof. We easily calculate:

$$\begin{aligned} \deg(fg) &\stackrel{\text{Lemma 3.13}}{=} \deg_x(N_{fg}) \\ &\stackrel{\text{Rem. 3.7}}{=} \deg_x(N_f N_g) \\ &\stackrel{\text{property of } \deg_x}{=} \deg_x(N_f) + \deg_x(N_g) \\ &\stackrel{\text{Lemma 3.13}}{=} \deg(f) + \deg(g) \end{aligned}$$

□

It makes no sense to talk about the "degree of the nominator (or denominator) of a rational function on E " since it may change when the representant is changed:

$$\frac{x+1}{xy-2} = \frac{x^2+x}{x^2y-2x}$$

but by Prop. 3.14 we get that for $r = \frac{f}{g} = \frac{h}{k} \in K(E)$ it always holds that $\deg(f) - \deg(g) = \deg(h) - \deg(k)$ since $fk = gh$. Therefore we can make the following definition concerning the value of a rational function at \mathcal{O} :

Definition 3.15 (Evaluating a rational function at \mathcal{O}). *Let $r = \frac{f}{g} \in K(E)$ and distinguish the following cases:*

$\deg(f) < \deg(g)$: set $r(\mathcal{O}) = 0$

$\deg(f) > \deg(g)$: say that r is not finite at \mathcal{O} .

$\deg(f) = \deg(g)$ and $\deg(f)$ is even: write both f and g in canonical form, they both have a leading terms ax^d and bx^d (for some $a, b \in K$ and $d = \frac{\deg(f)}{2}$) and we set $r(\mathcal{O}) = \frac{a}{b}$.

$\deg(f) = \deg(g)$ **and** $\deg(f)$ **is odd**: write both f and g in canonical form, they both have a leading terms ax^d and bx^d (for some $a, b \in K$ and $d = \frac{\deg(f)-3}{2}$) and we again set $r(\mathcal{O}) = \frac{a}{b}$.

Remark 3.16. It might seem natural to define the degree of a rational function $r = \frac{f}{g}$ as $\deg(f) - \deg(g)$. Then the value at \mathcal{O} depends on the sign of this degree. But this differs from the usual definition of degree of a rational function in algebraic geometry. So we don't define the degree of a rational function at all.

Example 3.17. For

$$r(x, y) = \frac{x^3 + 2x + y + 2x^4y}{x + x^2 + 5xy^3}$$

one can write

$$r(x, y) = \frac{x^3 + 2x + y + 2x^4y}{x + x^2 + 5xy(x^3 + Ax + B)} = \frac{(x^3 + 2x) + y(1 + 2x^4)}{(x + x^2) + y(5x^4 + 5Ax^2 + 5Bx)}$$

This representant has a nominator degree of $\max\{2 \cdot 3, 3 + 2 \cdot 4\} = 11$ and a denominator degree of $\max\{2 \cdot 2, 3 + 2 \cdot 4\} = 11$ which are both odd. So $r(\mathcal{O}) = \frac{2}{5}$.

Proposition 3.18. For $r, s \in K(E)$ s.t. $r(\mathcal{O})$ and $s(\mathcal{O})$ are finite then it holds that:

$$(r \cdot s)(\mathcal{O}) = r(\mathcal{O})s(\mathcal{O})$$

and

$$(r + s)(\mathcal{O}) = r(\mathcal{O}) + s(\mathcal{O})$$

4 Zeros and Poles

Definition 4.1 (Zero and Poles). *Let $r \in K(E)$. We say that r has a zero at $P \in E$ if $r(P) = 0$ and that it has a pole at P if $r(P)$ is not finite.*

In the following we will define the multiplicity of a zero and a pole. It is motivated by multiplicities of zeros in analysis of functions in one variable: Consider the elliptic curve $E = E_{1,0}$ which therefore is given by the equation

$$Y^2 = X^3 + X$$

then $P = (0, 0) \in E$. First notice, that P is a zero of the functions x and y . But between this two functions, there is the relation $x = y^2 - x^3$. In the analytic sense, when $x \rightarrow 0$ the term x^3 can be neglected so we would say something like "the function x has a zero at P whose multiplicity is twice that of the zero of y at P ". So lets formalize:

Definition 4.2 (Uniformizer). *For an elliptic curve E let $P \in E$ be a point. $u \in K(E)$ with $u(P) = 0$ is called a uniformizer at P if it has the following property: $\forall r \in K(E) \setminus \{0\} : \exists d \in \mathbb{Z}, s \in K(E)$ finite at P with $s(P) \neq 0$ s.t.*

$$r = u^d \cdot s$$

Lemma 4.3 (Uniformizer in generic case). *Let E be an elliptic curve and $P \in E$ be finite and not of order two. Then for $P = (a, b)$ the function $u(x, y) := x - a$ is a uniformizer at P .*

Proof. First note that $u(a, b) = 0$. Now let $r \in K(E) \setminus \{0\}$ be arbitrary. If r has neither a zero nor a pole at P we can take $d = 0$ and $s = r$ and see that u is immaterial. So first let $r(P) = 0$. We now can write $r = \frac{f}{g}$ with $f(P) = 0$ and $g(P) \neq 0$. If we can decompose $f = u^d s$ as above then we can calculate

$$r = \frac{f}{g} = \frac{u^d s}{g} = u^d \frac{s}{g} = u^d \tilde{s}(x)$$

and we found $\tilde{s} := \frac{s}{g} \in K(E)$ as needed.

Put $s_0(x, y) := f(x, y)$ and repeat the following process (beginning with $i = 0$) while $s_i(P) = 0$: write $s_i(x, y) = v_i(x) + yw_i(x)$ in canonical form. Distinguish the cases $\overline{s_i}(P) = 0$ and $\overline{s_i}(P) \neq 0$:

Case $\overline{s_i}(P) = 0$: Since $y(P) = b \neq 0$ the system of linear equations

$$\begin{aligned} v_i(a) + bw_i(a) &= 0 \\ v_i(a) - bw_i(a) &= 0 \end{aligned}$$

has rank 2 (which is less then the characteristic) and therefore yields $v_i(a) = w_i(a) = 0$. Now we can write

$$s_i(x, y) = v_i(x) + yw_i(x) = (x-a)v_{i+1}(x) + (x-a)yw_{i+1}(x) = (x-a)s_{i+1}(x, y)$$

for $s_{i+1}(x, y) = v_{i+1}(x) + yw_{i+1}(x)$ and feasible polynomials $v_{i+1}, w_{i+1} \in K[E]$.

“ f f&nz” \Leftrightarrow
 f is finite
and non-zero

Stehen
lassen

Case $\overline{s_i}(P) \neq 0$: Multiply s_i by $1 = \frac{\overline{s_i}}{s_i}$ to get

$$s_i(x, y) = \frac{N_{s_i}(x)}{s_i(x, y)}$$

Now $s_i(P) = 0$ and $\overline{s_i}(P) \neq 0$ implies that $N_{s_i}(a) = 0$ so we can write $N_{s_i}(x) = (x - a)n(x)$ and with $s_{i+1}(x, y) := \frac{n(x)}{s_i(x, y)}$ (which is finite at P) we again get

$$s_i(x, y) = \frac{N_{s_i}(x)}{s_i(x, y)} = \frac{(x - a)n_{i+1}(x)}{s_i(x, y)} = (x - a)s_{i+1}(x, y)$$

If this process terminates, we end up with

$$f(x, y) = (x - a)^i s_i(x, y)$$

where $s := s_i$ is finite and nonzero. With $x - a = u(x, y)$ and $d := i$ this is the desired decomposition: $f = u^d s$.

Since s_i is a rational function, not a polynomial, its not clear that this process terminates. To show it anyhow calculate:

$$\begin{aligned} N_f(x) &= N_{u^i s_i}(x) \\ &= ((x - a)^i v_i(x))^2 - s(x) ((x - a)^i w_i(x))^2 \\ &= (x - a)^{2i} (v_i^2(x) - s(x) w_i^2(x)) \\ &= (x - a)^{2i} N_{s_i}(x) \end{aligned}$$

so we have that $\deg_x(N_f) = 2i + \deg_x(N_{s_i})$ and since $\deg_x(N_{s_i}) > 0$ this implies that $\deg_x(N_f) > 2i$, so $2i$ is bound by a finite number.

Thus if r has a zero at P we are done. If r has no zero and no pole we are done too and in the case where r has a pole at P , $\frac{1}{r}$ has a zero and we can take the same u with a negative d and are done too. \square

Lemma 4.4 (Uniformizer at points of order two). *Let E be an elliptic curve and $P := \Omega_i \in E$ be of order two, then $u(x, y) := y$ is a uniformizer at Ω_i .*

Proof. W.l.o.g. we can take $i = 1$. Then note that $u(P) = 0$ and let $r \in K(E) \setminus \{0\}$ be arbitrary with $r(P) = 0$ so it has the form $r = \frac{f}{g}$ with $f(P) = 0$ which implies $v(\omega_1) = 0$ where $f(x, y) = v(x) + yw(x)$ is in canonical form. Hence v has a linear factor: $v(x) = (x - \omega_1)v_1(x)$ for some polynomial v_1 . Since the three roots of s are different we can write

$$\begin{aligned} f(x, y) &= \frac{(x - \omega_1)v_1(x) + yw(x)}{(x - \omega_1)(x - \omega_2)(x - \omega_3)v_1(x) + yw_1(x)} \\ &= \frac{y^2 v_1(x) + yw_1(x)}{(x - \omega_2)(x - \omega_3)} \\ &= y \cdot \frac{y v_1(x) + w_1(x)}{(x - \omega_2)(x - \omega_3)} \\ &= u(x, y) \cdot W(x, y) \end{aligned}$$

where $w_1(x) := w(x)(x - \omega_2)(x - \omega_3)$ and $W(x, y) := \frac{y v_1(x) + w_1(x)}{(x - \omega_2)(x - \omega_3)}$. If $W(P) \neq 0$ we are done, otherwise we can repeat the process with W , but this is only necessary finitely many times since v can only contain finitely many factors. \square

Lemma 4.5 (Uniformizer at \mathcal{O}). *Let E be an elliptic curve then the function $u(x, y) := \frac{x}{y}$ is a uniformizer at $\mathcal{O} \in E$.*

Proof. Since $\deg(y) = 3 > 2 = \deg(x)$ it follows that $u(\mathcal{O}) = 0$. Now let $r = \frac{f}{g} \in K(E) \setminus \{0\}$ be arbitrary with $r(\mathcal{O}) = 0$ or not finite at \mathcal{O} , which means that $d := \deg(g) - \deg(f) \neq 0$. We want to take $s(x, y) = \left(\frac{y}{x}\right)^d r(x, y)$ which now needs to be finite and non-zero at \mathcal{O} because then we see

$$r(x, y) = \left(\frac{x}{y}\right)^d \left(\left(\frac{y}{x}\right)^d r(x, y)\right) = u^d(x, y)s(x, y)$$

But because

$$\begin{aligned} & \deg(y^d f(x, y)) - \deg(x^d g(x, y)) \\ \stackrel{\text{Prop. 3.14}}{=} & (\deg(y^d) + \deg(f)) - (\deg(x^d) + \deg(g)) \\ \stackrel{\text{Def. 3.11}}{=} & 3d + \deg(f) - 2d - \deg(g) \\ = & d + (\deg(f) - \deg(g)) = 0 \end{aligned}$$

which implies that $s(x, y) = \frac{y^d f(x, y)}{x^d g(x, y)}$ is indeed finite and non-zero. \square

Theorem 4.6 (Uniformizer theorem). *Every point on an elliptic curve has a uniformizer and the number d in Def. 4.2 does not depend on it's choice.*

Proof. Lemma 4.3, 4.4 and 4.5 together yield the existence of a uniformizer for every point. So its only left to show that d does not depend on it's choice: Let u and \tilde{u} be uniformizers at P then we can write especially $u = \tilde{u}^a q$ and $\tilde{u} = u^b p$ for $a, b \in \mathbb{Z}$ and $q, p \in K(E)$ are both finite and non-zero at P . After calculating

$$u = \tilde{u}^a q = (u^b p)^a q = u^{ab} (p^a q)$$

we assume $ab \neq 1$, divide by u and get $1 = u^{ab-1} (p^a q)$ which, evaluated at P leads to $1 = 0$, so $ab = 1$ and $a = b = \pm 1$. If $a = b = -1$ we get

$$u = \tilde{u}^{-1} q \Leftrightarrow u\tilde{u} = q$$

which, evaluated at P yields $0 = u(P)\tilde{u}(P) = q(P) \neq 0$. So it holds that $a = b = 1$. Now let $r \in K(E) \setminus \{0\}$ be arbitrary, because u and \tilde{u} are uniformizers, there exists $d, \tilde{d} \in \mathbb{Z}$ and $s, t \in K(E)$ finite and non-zero at P with $r = u^d s$ and $r = \tilde{u}^{\tilde{d}} t$. Now we calculate

$$u^d s = \tilde{u}^{\tilde{d}} t = (u p)^{\tilde{d}} t = u^{\tilde{d}} (p^{\tilde{d}} t)$$

which yields

$$u^{d-\tilde{d}} = \frac{p^{\tilde{d}} t}{s}$$

On the right side are only rational functions which are finite and non-zero at P but if $d - \tilde{d} \neq 0$ the left side is zero at P . So $d = \tilde{d}$. \square

Now that we know that uniformizers at a point always yield the same d we can make the following definition:

Definition 4.7 (Order of a rational function). For an elliptic curve E let $P \in E$ be a point and u an uniformizer at P . For $r \in K(E) \setminus \{0\}$ with $r = u^d \cdot s$ we call d the order of r at P and write

$$\text{ord}_P(r) =: d$$

The multiplicity of a zero is the order at that point and the multiplicity of a pole is the negative of the order.

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Remark 4.8. This definition of order at a zero agrees with the well known definition of order of a zero of a polynomial in one variable in the case that the zero does not correspond to a point of order two: Let $f \in K[X]$ with

$$f(x) = g(x) \cdot (x - a)^k$$

for $g \in K[X]$ with $g(a) \neq 0$, $k \in \mathbb{N}_{>0}$ and $a \in K$. We should now say that f has a zero of order k at a . Now see f as a polynomial $f \in K[E]$ and pick a uniformizer u at $P = (a, s(a))$ (which is a point on E , by assumption not of order two and a root of f), for instance $u(x, y) = x - a$, and write f as:

$$f(x, y) = u^d(x, y) \cdot s(x, y) = (x - a)^d \cdot g(x)$$

which implies $k = d = \text{ord}_P(f)$.

However, when $a = \omega_i$ (w.l.o.g. $i = 1$) we see that $P = (a, s(a)) = (a, 0)$ is a zero of order $2k$ of f since with the uniformizer $u(x, y) = y$ at P and the rational function $s(x, y) := \frac{g(x)}{(x - \omega_2)^k (x - \omega_3)^k}$ we write:

$$\begin{aligned} f(x, y) &= u^d(x, y) \cdot s(x, y) \\ &= y^d \cdot \frac{g(x)}{(x - \omega_2)^k (x - \omega_3)^k} \\ &= y^d \cdot \frac{(x - a)^k g(x)}{(x - \omega_1)^k (x - \omega_2)^k (x - \omega_3)^k} \\ &= y^d \cdot \frac{(x - a)^k g(x)}{y^{2k}} \end{aligned}$$

so $(x - a)^k \cdot g(x) = f(x, y) = y^d \cdot \frac{(x - a)^k g(x)}{y^{2k}}$ which implies $d = 2k$.

Proposition 4.9 (Order at finite non-root). Let $r \in K(E)$ and $P \in E$ s.t. $r(P) \neq 0$ and r is finite at P then:

$$\text{ord}_P(r) = 0$$

Proof. Pick a uniformizer at P , take $s(x, y) = r(x, y)$ (which is finite and non-zero at P) and write

$$r(x, y) = u^0(x, y)r(x, y) = u^d(x, y)s(x, y)$$

i.e. $\text{ord}_P(f) = d = 0$. □

Proposition 4.10 (Order of polynomials at non-root). Let $f \in K[E]$ and $P \in E \setminus \{\mathcal{O}\}$ s.t. $f(P) \neq 0$ then:

$$\text{ord}_P(f) = 0$$

Proof. Since polynomials don't have finite roots, this follows from [Prop. 4.9](#).
□

Proposition 4.11 (Order of polynomials at \mathcal{O}). *For $f \in K[E] \setminus \{0\}$:*

$$\text{ord}_{\mathcal{O}}(f) = -\deg(f)$$

Proof. $u(x, y) = \frac{x}{y}$ is a uniformizer at \mathcal{O} by [Lemma 4.5](#). With $k := \deg(f)$ we take $s(x, y) = \frac{x^k}{y^k} f(x, y)$. Because $\deg(x^k \cdot f(x, y)) \stackrel{\text{Prop. 3.14}}{=} 2k + \deg(f) = 3k$ and $\deg(y^k) = 3k$ we know that s is finite and non-zero and can write

$$f(x, y) = u^d(x, y) s(x, y) = \left(\frac{x}{y}\right)^d \frac{x^k}{y^k} f(x, y)$$

which implies that $d = -k = -\deg(f)$. □

Proposition 4.12 (Property of order of rational functions). *For $r_1, r_2 \in K(E)$ and $P \in E$:*

$$\text{ord}_P(r_1 \cdot r_2) = \text{ord}_P(r_1) + \text{ord}_P(r_2)$$

Proof. Let $P \in E$ and pick a uniformizer u at P . We now get numbers $d, d_1, d_2 \in \mathbb{Z}$ and at P finite and non-zero rational functions $s, s_1, s_2 \in K(E)$ s.t.

$$\begin{aligned} r_1 \cdot r_2 &= u^d \cdot s \\ r_1 &= u^{d_1} \cdot s_1 \\ r_2 &= u^{d_2} \cdot s_2 \end{aligned}$$

and can calculate

$$u^d \cdot s = r_1 \cdot r_2 = (u^{d_1} \cdot s_1) \cdot (u^{d_2} \cdot s_2) = u^{d_1+d_2} \cdot s_1 \cdot s_2$$

and since [Thm. 4.6](#) it follows that

$$\text{ord}_P(r_1 \cdot r_2) = d = d_1 + d_2 = \text{ord}_P(r_1) + \text{ord}_P(r_2)$$

□

Example 4.13. *Let $P = (a, b) \in E$ with $b \neq 0$ i.e. P finite and not of order two. We now want to calculate the orders of $r(x, y) = x - a$ at all points $Q \in E$ where $r(Q)$ is not finite or zero (at all other points it holds that $\text{ord}_Q(r) = 0$):*

$Q = P$ or $Q = P' := (a, -b) \neq P$: *Take a uniformizer u at Q , since r itself is a uniformizer it follows that $r = u^d \cdot s = r^1 \cdot 1$ and $\text{ord}_Q(r) = d = 1$.*

$Q = \mathcal{O}$: *Take a uniformizer $u(x, y) = \frac{x}{y}$ at Q and $s(x, y) = \frac{x^3 - ax^2}{y^2}$ (note $s(Q) = 1$)*

$$u^d(x, y) \cdot s(x, y) = \left(\frac{x}{y}\right)^{-2} s(x, y) = \frac{y^2}{x^2} \frac{x^3 - ax^2}{y^2} = x - a = r(x, y)$$

and $\text{ord}_Q(r) = d = -2$.

Summing up we see that r has two simple zeros and a single double pole.

Example 4.14. Now consider $r(x, y) := y$ since $u(x, y) = y$ is a uniformizer at the three points of order two we have $\text{ord}_{\Omega_i}(r) = 1$. At every other finite point r has order zero. In \mathcal{O} we can take $u(x, y) = \frac{x}{y}$ as a uniformizer and with $s(x, y) = \frac{x^3 y}{y^3}$ (which is finite at \mathcal{O}) it follows that:

$$u^d(x, y) \cdot s(x, y) = \left(\frac{x}{y}\right)^{-3} \cdot s(x, y) = \frac{y^3}{x^3} \cdot \frac{x^3 y}{y^3} = y = r(x, y)$$

and $\text{ord}_{\mathcal{O}}(r) = d = -3$. Summing up we see that r has three simple zeros and a single tripple pole.

Example 4.15. What about $r(x, y) = \frac{x}{y}$? Since $\deg(x) = 2 < 3 = \deg(y)$ it holds that $r(\mathcal{O}) = 0$ to obtain the order we take $u(x, y) = \frac{x}{y}$ as a uniformizer at \mathcal{O} and calculate for $s(x, y) = 1$ that

$$u^d(x, y) \cdot s(x, y) = \left(\frac{x}{y}\right)^1 \cdot 1 = r(x, y)$$

and get $\text{ord}_{\mathcal{O}}(r) = 1$. Now distinguish the two cases:

$B \neq 0$: The two points $P_{\pm} := (0, \pm\sqrt{B})$ are zeros of r . To calculate the multiplicity we take $u(x, y) = x$ as a uniformizer at P_{\pm} , $s(x, y) := \frac{1}{y}$ (which is finite and nonzero for $y = \pm\sqrt{B}$ and calculate

$$\frac{x}{y} = r(x, y) = u^d(x, y)s(x, y) = x^d \frac{1}{y}$$

to obtain $\text{ord}_{P_{\pm}}(r) = d = 1$. Furthermore r is not finite at all points of order two Ω_i : We take a uniformizer $u(x, y) = y$ at Ω_i , $s(x, y) := x$ (which is finite and nonzero at Ω_i since $B \neq 0$ and [Prop. 2.5](#) implies that $\omega_i \neq 0$) and calculate

$$\frac{x}{y} = r(x, y) = u^d(x, y)s(x, y) = y^d x$$

to get $\text{ord}_{\Omega_i}(r) = d = -1$. So summing up, we get three zeros of order one and three poles of order one.

$B = 0$: An elliptic curve $E_{A,0}$ is given by

$$y^2 = x^3 + Ax = x(x - \sqrt{-A})(x + \sqrt{-A})$$

so we get $\omega_1 = 0$, $\omega_2 = \sqrt{-A}$ and $\omega_3 = \sqrt{A}$ as the three points of order two. First note, that Ω_2 and Ω_3 are poles of r , since $\omega_2 \neq 0$ and $\omega_3 \neq 0$. To obtain the order, we take $u(x, y) = y$ as a uniformizer, $s(x, y) = x$ (which is finite and nonzero) and calculate:

$$\frac{x}{y} = r(x, y) = u^d(x, y)s(x, y) = y^d x$$

to obtain $\text{ord}_{\Omega_2}(r) = \text{ord}_{\Omega_3}(r) = d = -1$. Furthermore we calculate

$$r(x, y) = \frac{x}{y} = \frac{xy}{y^2} = \frac{xy}{x(x - \sqrt{-A})(x + \sqrt{-A})} = \frac{y}{(x - \sqrt{-A})(x + \sqrt{-A})}$$

and therefore get, that $(0, 0)$ is a zero of r . To obtain the order at $(0, 0)$ we take the uniformizer $u(x, y) = y$ and calculate

$$\frac{y}{(x - \sqrt{-A})(x + \sqrt{-A})} = r(x, y) = u^d(x, y)s(x, y) = y^d \frac{1}{(x - \sqrt{-A})(x + \sqrt{-A})}$$

with $s(x, y) = \frac{1}{(x - \sqrt{-A})(x + \sqrt{-A})}$ and get $\text{ord}_{(0,0)}(r) = d = 1$. So summing up, we get two simple zeros and two simple poles.

The three examples 4.13, 4.14 and 4.15 suggest that the sum of orders over all points is zero, which is sort of a baby Riemann-Roch Theorem. To prove this, we need the following lemma:

Lemma 4.16 (Sum of multiplicities of roots equal degree). For $f \in K[E]$:

$$\deg(f) = \sum_{\substack{P \in E \\ f(P)=0}} \text{ord}_P(f)$$

Proof. Define $n := \deg(f)$. By Lemma 3.13 it follows that $n = \deg_x(N_f)$. We can write

$$(f\bar{f})(x) = N_f(x) = \prod_{i=1}^n (x - a_i)$$

with not necessarily different a_i s. By Rem. 4.8 it follows that dependent on whether $(a_i, 0)$ is of order two or not the factor $(x - a_i)$ has two distinct roots on E (namely $(a_i, \pm\sqrt{s_{A,B}(a_i)})$) or one double one. So, counting multiplicities, we get that $f\bar{f}$ has exactly $2n$ roots on E . Since f and \bar{f} have the same number of roots on E , f has exactle n roots (again counting multiplicities), which is a synonym for the right side of the above equation. \square

Theorem 4.17 (Sum of orders is zero). For $r \in K(E)$:

$$\sum_{P \in E} \text{ord}_P(r) = 0$$

Proof. Since for $r = \frac{h}{g} \in K(E)$ it holds that

$$\sum_{P \in E} \text{ord}_P(r) = \sum_{P \in E} \text{ord}_P(h) - \sum_{P \in E} \text{ord}_P(g)$$

for any $P \in E$, it suffices to show the result for a polynomial $f \in K[E]$. One can calculate

$$\sum_{P \in E \setminus \{\mathcal{O}\}} \text{ord}_P(f) \stackrel{\text{Prop. 4.10}}{=} \sum_{\substack{P \in E \\ f(P)=0}} \text{ord}_P(f) \stackrel{\text{Lemma 4.16}}{=} \deg(f)$$

On the other hand by Prop. 4.11 the order of f at \mathcal{O} is $-\deg(f)$ which yields the result. \square

Lemma 4.18. *Let f be a nonconstant polynomial on E , then f must have at least two simple zeros or one double zero at finite points of E .*

Proof. Since f is not constant, it contains an x or a y . Since $\deg(x) = 2$ and $\deg(y) = 3$ the result follows from [Lemma 4.16](#). \square

Lemma 4.19. *If two rational function agree on an infinite number of points of E (which is possible since E is infinite by [Prop. 2.7](#)), they are equal.*

Proof. Let $f, g \in K(E)$ with $f(P) = g(P)$ for infinitely many $P \in E$ and define $h := f - g$, which therefore has infinitely many zeros. Since $\text{ord}_P(h) > 0$ for a zero $P \in E$ the sum

$$\sum_{\substack{P \in E \\ f(P)=0}} \text{ord}_P(f)$$

is not finite. But if h is not the zero-polynomial $\deg(h)$ is finite which would contradict [Lemma 4.16](#). \square

Lemma 4.20. *A rational function without a finite pole is a polynomial.*

Proof. Write an $r \in K(E)$ without poles in canonical form $r(x, y) = a(x) + yb(x)$ with $a, b \in K(x)$ ([Rem. 3.9](#)).

$$\begin{aligned} & r \text{ has no finite pole} \\ \Rightarrow & \bar{r} = a - yb \text{ has no finite pole} \\ \Rightarrow & r + \bar{r} = 2a \text{ has no finite pole} \\ \Rightarrow & yb = r - a \text{ has no finite pole} \\ \Rightarrow & (yb)^2 = sb^2 \text{ has no finite pole} \end{aligned}$$

If b has a pole, b^2 has a double pole. But sb^2 has no finite pole, hence s has a double zero which contradicts the definition of elliptic curve [2.2](#). \square

Definition 4.21 (Rational map). *A pair of rational functions $(u, v) \in K(E_{A,B})$ is called rational map if*

$$v^2 = u^3 + Au + B$$

Remark 4.22. *Because of the relation between u and v of a rational map $F = (u, v)$ it holds for every $P \in E$:*

$$u(P) \text{ is (not) finite} \Leftrightarrow v(P) \text{ is (not) finite}$$

When we make the convention that $F(P) = \mathcal{O}$ if u and v are not finite at P we see that F defines a map $E \rightarrow E$ by $P \mapsto (u(P), v(P))$.

Remark 4.23. *Given a field K , form the elliptic curve E using the equation from [Def. 2.2](#):*

$$Y^2 = X^3 + AX + B$$

and consider the field of rational functions over E , namely $K(E)$ and use the same equation to define an elliptic curve over that field, denoted by $E(K(E))$. Since $K(E)$ may not be algebraically closed, the points of $E(K(E))$ may have coordinates in the algebraic closure of $K(E)$. The $K(E)$ -rational points ([Def. 2.8](#)) of $E(K(E))$ are exactly the rational maps. We think of the identity of this curve, call it \mathcal{O}_M , as the map with constant value \mathcal{O} .

5 Divisors and Lines

To store the zeros and poles of a rational function (together with their degree), we will use a formal sum. For this we recall the definition of a free abelian group:

Definition 5.1 (Free abelian group). *Let S be a set. The free abelian group \mathcal{F}_S generated by S is the set of formal linear combinations*

$$\sum_{s \in S} \lambda(s) \cdot \langle s \rangle$$

where $\lambda : S \rightarrow \mathbb{Z}$ and $\lambda(s) = 0$ for almost all $s \in S$ (i.e. for all $s \in S$ except of finitely many) together with the formal addition of two such formal linear combinations.

Definition 5.2 (Divisor). *For a elliptic curve E we define the group of divisors of E by*

$$\text{Div}(E) := \mathcal{F}_E$$

For a divisor $\Delta = \sum_{P \in E} \lambda(P) \cdot \langle P \rangle \in \text{Div}(E)$ we define the degree of Δ as

$$\text{deg}(\Delta) := \sum_{P \in E} \lambda(P)$$

and the norm of Δ as

$$|\Delta| := \sum_{P \in E \setminus \{\mathcal{O}\}} |\lambda(P)|$$

Fact 5.3. *A Divisor of norm 1 has the form $\pm \langle P \rangle + n \langle \mathcal{O} \rangle$ for $n \in \mathbb{Z}$.*

Proposition 5.4 (Property of divisor degree). *For $\Delta_1, \Delta_2 \in \text{Div}(E)$:*

$$\text{deg}(\Delta_1 + \Delta_2) = \text{deg}(\Delta_1) + \text{deg}(\Delta_2)$$

Proof. Note that for $\Delta_i = \sum_{P \in E} \lambda_i(P) \langle P \rangle$ the sum $\Delta_1 + \Delta_2$ is again a formal sum, hence a divisor and one can calculate:

$$\begin{aligned} \text{deg}(\Delta_1 + \Delta_2) &= \text{deg}(\sum_{P \in E} \lambda_1(P) \langle P \rangle + \sum_{P \in E} \lambda_2(P) \langle P \rangle) \\ &\stackrel{\text{finite sums}}{=} \text{deg}(\sum_{P \in E} (\lambda_1(P) + \lambda_2(P)) \langle P \rangle) \\ &\stackrel{\text{Def. 5.2}}{=} \sum_{P \in E} (\lambda_1(P) + \lambda_2(P)) \\ &\stackrel{\text{finite sums}}{=} \sum_{P \in E} \lambda_1(P) + \sum_{P \in E} \lambda_2(P) \\ &\stackrel{\text{Def. 5.2}}{=} \text{deg}(\Delta_1) + \text{deg}(\Delta_2) \end{aligned}$$

□

Definition 5.5 (Associated divisor). *For a rational function $r \in K(E) \setminus \{0\}$ we define the associated divisor by*

$$\text{div}(r) = \sum_{P \in E} \text{ord}_P(r) \cdot \langle P \rangle$$

nearly every result from the last lecture only holds for non-zero functions

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Remark 5.6. A rational function has a finite number of zeros and poles by [Lemma 4.16](#) so the associated divisor is well-defined.

Fact 5.7. Constant non-zero functions have divisor 0.

The Divisor of a rational function is a possibility to write down all information about poles and zeros of a rational functions i.e. the positions and multiplicities.

Fact 5.8. For $f \in K[E]$:

$$|\operatorname{div}(f)| \stackrel{\text{Def. 5.2}}{=} \sum_{P \in E \setminus \{\mathcal{O}\}} \operatorname{ord}_P(f) \stackrel{\text{Prop. 4.10}}{=} \sum_{\substack{P \in E \\ f(P)=0}} \operatorname{ord}_P(f) \stackrel{\text{Lemma 4.16}}{=} \deg(f)$$

Definition 5.9. Let $r \in K(E)$, then the leading coefficient is defined by

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$$\operatorname{lc}(r) := \left[\left(\frac{x}{y} \right)^{\operatorname{ord}_{\mathcal{O}}(r)} \cdot r \right] (\mathcal{O})$$

Example 5.10. Let $r(x, y) = \frac{2x^2+7x}{3yx+2}$. With the uniformizer $\frac{x}{y}$ at \mathcal{O} ([Lemma 4.5](#)) and

$$\left(\frac{x}{y} \right)^{-1} r(x, y) = \frac{2yx^2 + 7yx}{3yx^2 + 2x}$$

we get $\deg_{\mathcal{O}}(r) = -1$. Evaluating at \mathcal{O} yields $\operatorname{lc}(r) = \frac{2}{3}$ which makes perfect sense with our intuition of what a leading coefficient should be.

Proposition 5.11. If two rational functions have the same divisor, their quotient is constant.

Proof. Let $r_1, r_2 \in K(E)$ with $\operatorname{div}(r_1) = \operatorname{div}(r_2)$, so they have the same roots and the same poles (with same multiplicities). If $\operatorname{div}(r_1)$ (and hence $\operatorname{div}(r_2)$) has no finite poles, [Lemma 4.20](#) implies that r_1 and r_2 are polynomials, which additionally have same degree (by [Lemma 4.16](#)) and the same roots, which implies that they are equal and the quotient is 1 which is constant. Now assume that $\operatorname{div}(r_1)$ has a finite pole, say $P \in E$ of order m . Pick a uniformizer u at P and write

$$\frac{r_1}{r_2} = \frac{u^m s_1}{u^m s_2} = \frac{s_1}{s_2}$$

for $s_1, s_2 \in K(X, Y)$ finite and non-zero at P . So $\frac{s_1}{s_2}$ is finite and non-zero at P , hence is $\frac{r_1}{r_2}$. Since this works for every finite pole P by [Lemma 4.20](#) again $\frac{r_1}{r_2}$ is a polynomial, which is possible only if r_1 is a multiple of r_2 . \square

Thus we can check if two rational functions are equal if they have the same divisor and agree at any point on E for example \mathcal{O} . If the two functions have a pole at \mathcal{O} we can compare their leading coefficients:

Lemma 5.12. Two rational functions with the same divisor and leading coefficient are equal.

Proof. Let $r_1, r_2 \in K(E)$ be two rational function with the same divisor and leading coefficient. We know that

$$\begin{aligned}
0 &= \text{lc}(r_1) - \text{lc}(r_2) \\
&\stackrel{\text{Def. 5.9}}{=} \left[\left(\frac{x}{y} \right)^{\text{ord}_{\mathcal{O}}(r_1)} r_1 \right] (\mathcal{O}) - \left[\left(\frac{x}{y} \right)^{\text{ord}_{\mathcal{O}}(r_2)} r_2 \right] (\mathcal{O}) \\
&\stackrel{d:=\text{ord}_{\mathcal{O}}(r_1)=\text{ord}_{\mathcal{O}}(r_2)}{=} \left[\left(\frac{x}{y} \right)^d r_1 \right] (\mathcal{O}) - \left[\left(\frac{x}{y} \right)^d r_2 \right] (\mathcal{O}) \\
&\stackrel{\text{Prop. 3.18}}{=} \left[\left(\frac{x}{y} \right)^d r_1 - \left(\frac{x}{y} \right)^d r_2 \right] (\mathcal{O}) \\
&= \left[\left(\frac{x}{y} \right)^d (r_1 - r_2) \right] (\mathcal{O})
\end{aligned}$$

Since [Prop. 5.11](#) we have $r_1 = c \cdot r_2$ which implies

$$\begin{aligned}
0 &= \left[\left(\frac{x}{y} \right)^d (c \cdot r_2 - r_2) \right] (\mathcal{O}) \\
&= \left[\left(\frac{x}{y} \right)^d (c-1) \cdot r_2 \right] (\mathcal{O}) \\
&\stackrel{\text{Prop. 3.18}}{=} (c-1) \left[\left(\frac{x}{y} \right)^d \cdot r_2 \right] (\mathcal{O})
\end{aligned}$$

which implies $c = 1$ and therefore $r_1 = r_2$. □

Example 5.13. 1. Let $P = (a, b), P' = (a, -b) \in E$ with $b \neq 0$ and $r(x, y) = x - a$. With [Exa. 4.13](#) we see that

$$\text{div}(r) = \langle P \rangle + \langle P' \rangle - 2\langle \mathcal{O} \rangle$$

2. Let $P_i = (\omega_i, 0) \in E$ and $r(x, y) = y$. With [Exa. 4.14](#) we see that

$$\text{div}(r) = \langle P_1 \rangle + \langle P_2 \rangle + \langle P_3 \rangle - 3\langle \mathcal{O} \rangle$$

3. Let $Q = (0, \sqrt{B}), Q' = (0, -\sqrt{B}) \in E_{A,B}$ and $r = \frac{x}{y}$. With [Exa. 4.15](#) we see that for $B \neq 0$:

$$\text{div}(r) = \langle Q \rangle + \langle Q' \rangle - \langle P_1 \rangle - \langle P_2 \rangle - \langle P_3 \rangle + \langle \mathcal{O} \rangle$$

Definition 5.14 (Principal divisors). $\Delta \in \text{Div}(E)$ is called principal if:

$$\exists r \in K(E) : \Delta = \text{div}(r)$$

Furthermore we say that $\Delta_1, \Delta_2 \in \text{Div}(E)$ are linearly equivalent or in the same divisor class if $\Delta_1 - \Delta_2$ is principal. We then write $\Delta_1 \sim \Delta_2$.

The following Proposition and Corrolar yield that \sim is indeed an equivalents relation and that the set of principal divisors is a subgroup of $\text{Div}(E)$:

Fact 5.15. For $r_1, r_2 \in K(E)$ it holds:

$$\text{div}(r_1 \cdot r_2) = \text{div}(r_1) + \text{div}(r_2)$$

Proof. With [Prop. 4.12](#) it directly follows from the [Def. 5.2](#). □

Corrolar 5.16. For $r \in K(E)$:

1. $\operatorname{div}(-r) = \operatorname{div}(r)$
2. $-\operatorname{div}(r) = \operatorname{div}\left(\frac{1}{r}\right)$

Proof.

1. $\operatorname{div}(-r) = \operatorname{div}((-1) \cdot r) \stackrel{\text{Fact 5.15}}{=} \operatorname{div}(-1) + \operatorname{div}(r) \stackrel{\text{Fact 5.7}}{=} \operatorname{div}(r)$
2. $0 \stackrel{\text{Fact 5.7}}{=} \operatorname{div}(1) = \operatorname{div}\left(\frac{r}{r}\right) = \operatorname{div}\left(\frac{1}{r} \cdot r\right) \stackrel{\text{Fact 5.15}}{=} \operatorname{div}\left(\frac{1}{r}\right) + \operatorname{div}(r)$

□

Definition 5.17. We define the following two subgroups of $\operatorname{Div}(E)$:

$$\operatorname{Prin}(E) := \{ \Delta \in \operatorname{Div}(E) \mid \Delta \text{ is principal} \}$$

and

$$\operatorname{Div}_0(E) := \{ \Delta \in \operatorname{Div}(E) \mid \deg \Delta = 0 \}$$

and the so called Picard group of E or divisor class group of E :

$$\operatorname{Pic}(E) := \operatorname{Div}(E) / \operatorname{Prin}(E)$$

Since [Thm. 4.17](#) we know that $\operatorname{Prin}(E) \subseteq \operatorname{Div}_0(E)$ and are able to define the degree zero part of the Picard group:

$$\operatorname{Pic}_0(E) := \operatorname{Div}_0(E) / \operatorname{Prin}(E)$$

The goal of this chapter will be to show that $\operatorname{Pic}_0(E)$ and E itself are one-to-one.

Definition 5.18 (Line). A line on E is a polynomials of the form

$$l(x, y) = \alpha x + \beta y + \gamma$$

with $\alpha, \beta, \gamma \in K$ and $\alpha \neq 0$ or $\beta \neq 0$. If $P \in E$ is a zero of l we say l goes through P and P is on l .

Proposition 5.19. For $P_1, P_2 \in E$ finite with $P_1 \neq P_2$ there is a line through P_1 and P_2 .

Proof. With $P_i = (a_i, b_i)$ we find that

$$l(x, y) = \begin{cases} \frac{b_2 - b_1}{a_2 - a_1}(x - a_1) - (y - b_1) & \text{if } a_1 \neq a_2 \\ x - a_1 & \text{else} \end{cases}$$

defines a line with roots P_1 and P_2 . □

The following special line through an arbitrary point will be very useful:

Proposition 5.20. For $P = (a, b) \in E$ finite and not of order two, the line

$$l(x, y) = m(x - a) - (y - b)$$

with $m = \frac{3a^2 + A}{2b}$ has a double zero at P and one other finite zero. In other words:

$$\exists Q \in E : \text{div}(l) = 2(P) + (Q) - 3(\mathcal{O})$$

Proof. We clearly see, that $l(P) = 0$, we now want to show, that the order at P is 2: Let $u(x, y) = x - a$ be a uniformizer at P and write:

$$l(x, y) = (x - a)^2 s(x, y)$$

and $s(x, y) = \frac{l(x, y)}{(x - a)^2}$ has to be finite and non-zero at P . Let $g(x, y) := \frac{y - b}{x - a}$. Polynomial division and the fact that $b^2 = a^3 + Aa + B$ yield:

$$\begin{aligned} g(x, y) &= \frac{y - b}{x - a} = \frac{y^2 - b^2}{(x - a)(y + b)} \\ &= \frac{x^3 + Ax + B - b^2}{(x - a)(y + b)} \\ &= \frac{x^2 + ax + A + a^2}{y + b} \\ g(a, b) &= \frac{3a^2 + A}{2b} = m \end{aligned}$$

Now we calculate with $2mb = 3a^2 + A$:

$$\begin{aligned} s(x, y) &= \frac{m(x - a) - (y - b)}{(x - a)^2} \\ &= \frac{m}{x - a} - \frac{g(x, y)}{x - a} \\ &= \frac{m}{x - a} - \frac{x^2 + ax + A + a^2}{x - a} \cdot \frac{1}{y + b} \\ &= \frac{m \frac{y + b}{x - a} - x + 2a + \frac{A + 3a^2}{x - a}}{y + b} \\ &= \frac{m \frac{y + b}{x - a} - x - 2a - \frac{2mb}{x - a}}{y + b} \\ &= \frac{m \frac{y - b}{x - a} - x - 2a}{y + b} \\ &= \frac{m \cdot g(x, y) - x - 2a}{y + b} \end{aligned}$$

Which, evaluated at P yields: $s(a, b) = \frac{m^2 - 3a}{2b}$ which is finite and non-zero at P .

□

Lemma 5.21 (Divisor of Line). *Let l be a line:*

$$|\operatorname{div}(l)| \in \{2, 3\}$$

Proof. $l(x, y) = \alpha x + \beta y + \gamma$ is a polynomial of degree 2 (if $\beta = 0$) or 3 (if $\beta \neq 0$). Hence by [Lemma 4.16](#), the sum of multiplicities of the zeros of l is 2 or 3, which by [Fact 5.8](#) is $|\operatorname{div}(l)|$. \square

Proposition 5.22. *Let l be a line and $P_1, P_2, P_3 \in E$ pairwise distinct points on l , then one of the following holds:*

1. $\operatorname{div}(l) = \langle P_1 \rangle + \langle P_2 \rangle + \langle P_3 \rangle - 3\langle \mathcal{O} \rangle$
2. $\operatorname{div}(l) = 2\langle P_1 \rangle + \langle P_2 \rangle - 3\langle \mathcal{O} \rangle$
3. $\operatorname{div}(l) = 3\langle P_1 \rangle - 3\langle \mathcal{O} \rangle$
4. $\operatorname{div}(l) = \langle P_1 \rangle + \langle P_2 \rangle - 2\langle \mathcal{O} \rangle$
5. $\operatorname{div}(l) = 2\langle P_1 \rangle - 2\langle \mathcal{O} \rangle$

In the contrary, there is a line for each of this divisors.

Proof. First we show that all possible divisors are given by 1-5. Since l is a polynomial, it has a pole at \mathcal{O} and \mathcal{O} is the only pole. By [Prop. 4.11](#) $\operatorname{ord}_{\mathcal{O}}(l) = -\deg(l) \in \{-2, -3\}$. By [Thm. 4.17](#) and combinatorial arguments we get for

case $\operatorname{ord}_{\mathcal{O}}(l) = -3$: there can only be

- three single roots (1. $\operatorname{div}(l) = \langle P_1 \rangle + \langle P_2 \rangle + \langle P_3 \rangle - 3\langle \mathcal{O} \rangle$)
- one single root and one double root (2. $\operatorname{div}(l) = 2\langle P_1 \rangle + \langle P_2 \rangle - 3\langle \mathcal{O} \rangle$)
- one tripple root (3. $\operatorname{div}(l) = 3\langle P_1 \rangle - 3\langle \mathcal{O} \rangle$)

case $\operatorname{ord}_{\mathcal{O}}(l) = -2$: there can only be

- two single roots (4. $\operatorname{div}(l) = \langle P_1 \rangle + \langle P_2 \rangle - 2\langle \mathcal{O} \rangle$)
- one double root (5. $\operatorname{div}(l) = 2\langle P_1 \rangle - 2\langle \mathcal{O} \rangle$)

Now we show that all this divisors are possible.

Case $\operatorname{ord}_{\mathcal{O}}(l) = -3$:

three single roots For $l(x, y) = y$ we get:

$$\operatorname{div}(l) = \langle \Omega_1 \rangle + \langle \Omega_2 \rangle + \langle \Omega_3 \rangle - 3\langle \mathcal{O} \rangle$$

one single root and one double root [Prop. 5.20](#)

one tripple root We know that $P = (0, \sqrt{B}) \in E$ is a point on $l(x, y) = Ax - y + \sqrt{B}$. If $B \neq 0$ (which means that P is not of order two) we can take the uniformizer $u(x, y) = x$ and calculate

TODO

Case $\text{ord}_{\mathcal{O}}(l) = -2$: Let $P = (a, b) \in E$ be finite and $l(x, y) := x - a$.

P **not of order two** [Exa. 4.13](#) says that P and $(a, -b)$ are two single roots of L

P **of order two** W.l.o.g. $P = \Omega_1$. Pick the uniformizer $u(x, y) = y$ at P . Then we get for $d = 2$ and $s(x, y) = \frac{1}{(x-\omega_2)(x-\omega_3)}$ (which is finite and non-zero at P):

$$u^d(x, y)s(x, y) = \frac{y^2}{(x-\omega_2)(x-\omega_3)} = x - \omega_1 = r(x, y)$$

This says, that l has a double zero at P .

□

Notation 5.23. Whenever we write an $?$ as a coefficient in a divisor, the statement in which the divisor occurs is meant to be quantified with “it exists an integral $?$ ”. In other words: we are not interested in the special value of the coefficient.

Theorem 5.24 (Linear Reduction). Let $\Delta \in \text{Div}(E)$. Then there exists $\tilde{\Delta} \in \text{Div}(E)$ with:

- $\tilde{\Delta} \sim \Delta$
- $\deg(\tilde{\Delta}) = \deg(\Delta)$
- $|\tilde{\Delta}| \leq 1$

Proof. The idea is, that we can, given an arbitrary divisor Δ , add or subtract associated divisors of lines, listed in [Prop. 5.22](#) to obtain a divisor Δ_1 . This operation will not change the linear equivalence class since

$$[\Delta_1 = \Delta \pm \text{div}(l)] \Leftrightarrow [\Delta_1 - \Delta = \text{div}(l) \text{ or } \Delta - \Delta_1 = \text{div}(l)] \Leftrightarrow [\Delta \sim \Delta_1]$$

and obtain the degree of Δ because

$$\deg(\Delta_1) \stackrel{\text{Prop. 5.4}}{=} \deg(\Delta) + \deg(l) \stackrel{\text{Thm. 4.17}}{=} \deg(\Delta)$$

We try to do it in a way, that the norm reduces.

So write $\Delta = \sum_{P \in E} \lambda(P)\langle P \rangle$. We first want to reduce Δ to a linear equivalent divisor Δ' of same degree, with an equal or lesser norm which can be written as:

$$\Delta' = n_1\langle P \rangle - n_2\langle Q \rangle + ?\langle \mathcal{O} \rangle \tag{1}$$

where $n_1, n_2 \in \mathbb{N}_{>0}$.

Suppose Δ is not of this form. If Δ contains only one finite point, say $\langle P \rangle$ and this point $P = (\omega, 0)$ is of order two, we can subtract or add (depending on the sign of $\langle P \rangle$ in Δ) the divisor of $l(x, y) := x - \omega$ which is $\langle l \rangle = 2\langle P \rangle - 2\langle \mathcal{O} \rangle$ and are finished. If P is not of order two, we can subtract or add the divisor of

l from [Prop. 5.20](#) through P and get a norm-reduced divisor which is in form [Equation 1](#) or contains at least two different points with the same sign.

So now suppose that we can take finite Q and R with $Q \neq R$ such that $\langle Q \rangle$ and $\langle R \rangle$ appear with nonzero coefficient of the same sign. Let l be a line through Q and R ([Prop. 5.19](#)). This line has two or three distinct roots.

If $\lambda(Q), \lambda(R) < 0$: Set $\Delta_1 := \Delta + \text{div}(l)$

If $\lambda(Q), \lambda(R) > 0$: Set $\Delta_1 := \Delta - \text{div}(l)$

For $\Delta_1 = \sum_{P \in E} \mu(P) \langle P \rangle$ we get $|\mu(Q)| = |\lambda(Q)| - 1$ and $|\mu(R)| = |\lambda(R)| - 1$ i.e. the norm of the coefficients of $\langle Q \rangle$ and $\langle R \rangle$ each decreases by one.

In the case where l has three distinct roots, we changed the coefficient of another $\langle S \rangle$ for a finite point $S \in E$ in Δ_1 by 1. So summing up, two coefficient decrease by one and maximal one increases by one, which implies $|\Delta_1| < |\Delta|$.

We can repeat this process a finite number of times until we get the divisor Δ' , linear equivalent to and of same degree as Δ in the form:

$$\Delta' = n_1 \langle P \rangle - n_2 \langle Q \rangle + ? \langle \mathcal{O} \rangle$$

where $n_1, n_2 \in \mathbb{N}_{>0}$.

Suppose $n_1 > 1$.

P not of order two Let l be the line from [5.20](#) $\Rightarrow \text{div}(l) = 2 \langle P \rangle + \langle S \rangle - 3 \langle \mathcal{O} \rangle$

$P = (\omega, 0)$ of order two $l(x, y) = x - \omega \Rightarrow \langle l \rangle = 2 \langle P \rangle - 2 \langle \mathcal{O} \rangle$

Subtraction reduces n_1 and $|\Delta'|$ and brings us back to the form of the start with reduced norm. The same algorithm works for n_2 and we end up with a divisor of the form

$$\langle P \rangle - \langle Q \rangle + ? \langle \mathcal{O} \rangle$$

with $P = (a, b)$. The line $l(x, y) = x - a$ has divisor $\text{div}(l) = \langle P \rangle + \langle R \rangle - 2 \langle \mathcal{O} \rangle$ or $\text{div}(l) = 2 \langle P \rangle - 2 \langle \mathcal{O} \rangle$, subtracting brings us back to a previous case. \square

Corrolar 5.25. For each $\Delta \in \text{Div}_0(E)$ there is a unique $P \in E$ such that:

$$\Delta \sim \langle P \rangle - \langle \mathcal{O} \rangle$$

Proof. [Thm. 5.24](#) tells us that Δ is equivalent to a divisor of norm 1, i.e. a divisor $\Delta_1 = \pm \langle P \rangle + ? \langle \mathcal{O} \rangle$. We can w.l.o.g. assume that the sign of $\langle P \rangle$ is a plus, because otherwise for $P = (a, b)$, we add $\text{div}(l)$ for $l(x, y) = x - a$ which, since [Prop. 5.22](#), is

$$\text{div}(l) = \begin{cases} \langle P \rangle + \langle Q \rangle - 2 \langle \mathcal{O} \rangle & \text{if } P \text{ not of order two} \\ 2 \langle P \rangle - 2 \langle \mathcal{O} \rangle & \text{if } P \text{ of order two} \end{cases}$$

to obtain $\Delta_1 \sim \langle Q \rangle + ? \langle \mathcal{O} \rangle$ and after renaming: $\langle P \rangle + ? \langle \mathcal{O} \rangle \sim \Delta_1$. But we are given that $\Delta \in \text{Div}_0(E)$ i.e. $0 = \text{deg } \Delta = \text{deg } \Delta_1$ and therefore conclude that the coefficient of $\langle \mathcal{O} \rangle$ is -1 i.e. $\Delta \sim \Delta_1 = \langle P \rangle - \langle \mathcal{O} \rangle$.

So its left to show that P is unique. Assume

$$\langle P \rangle - \langle \mathcal{O} \rangle \sim \Delta \sim \langle Q \rangle - \langle \mathcal{O} \rangle$$

Then $\langle Q \rangle \sim \Delta + \langle \mathcal{O} \rangle \sim \langle P \rangle$ which means that $\langle Q \rangle - \langle P \rangle$ is principal i.e. there is a rational function $r \in K(E)$ s.t. $\text{div}(r) = \langle P \rangle - \langle Q \rangle$. Similarly as above, as long as $P \neq Q$ we add and subtract lines such that we end up at a rational function r with $\text{div}(r) = \langle S \rangle - \langle \mathcal{O} \rangle$. This shows that r has no finite poles and is a polynomial because of [Lemma 4.20](#). But it has only one single zero, which is impossible because of [Lemma 4.18](#). So we conclude $P = Q$. \square

Define a map $\bar{\sigma} : \text{Div}_0(E) \rightarrow E$ by $\bar{\sigma}(\Delta) = P$ where P is the unique point with $\Delta \sim \langle P \rangle - \langle \mathcal{O} \rangle$. Since $\text{div}(r) \sim 0$ it follows that $\bar{\sigma}(\langle r \rangle) = \mathcal{O}$ and we see that $\bar{\sigma}$ induces a map $\sigma : \text{Pic}_0(E) \rightarrow E$.

Corrolar 5.26. σ is a bijection.

Proof.

surjective Let $P \in E$, then $\sigma(\langle P \rangle - \langle \mathcal{O} \rangle) = P$.

injective Let $P, Q \in E$, $\Delta \in \text{Pic}_0(E)$ s.t. $\sigma(\Delta) = P$ and $\sigma(\Delta) = Q$. Since [Cor. 5.25](#) we know that $\exists! S \in E$ s.t. $\Delta \sim \langle S \rangle - \langle \mathcal{O} \rangle$, which then implies $P = S = Q$.

\square

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